

OFF-ROAD RACER

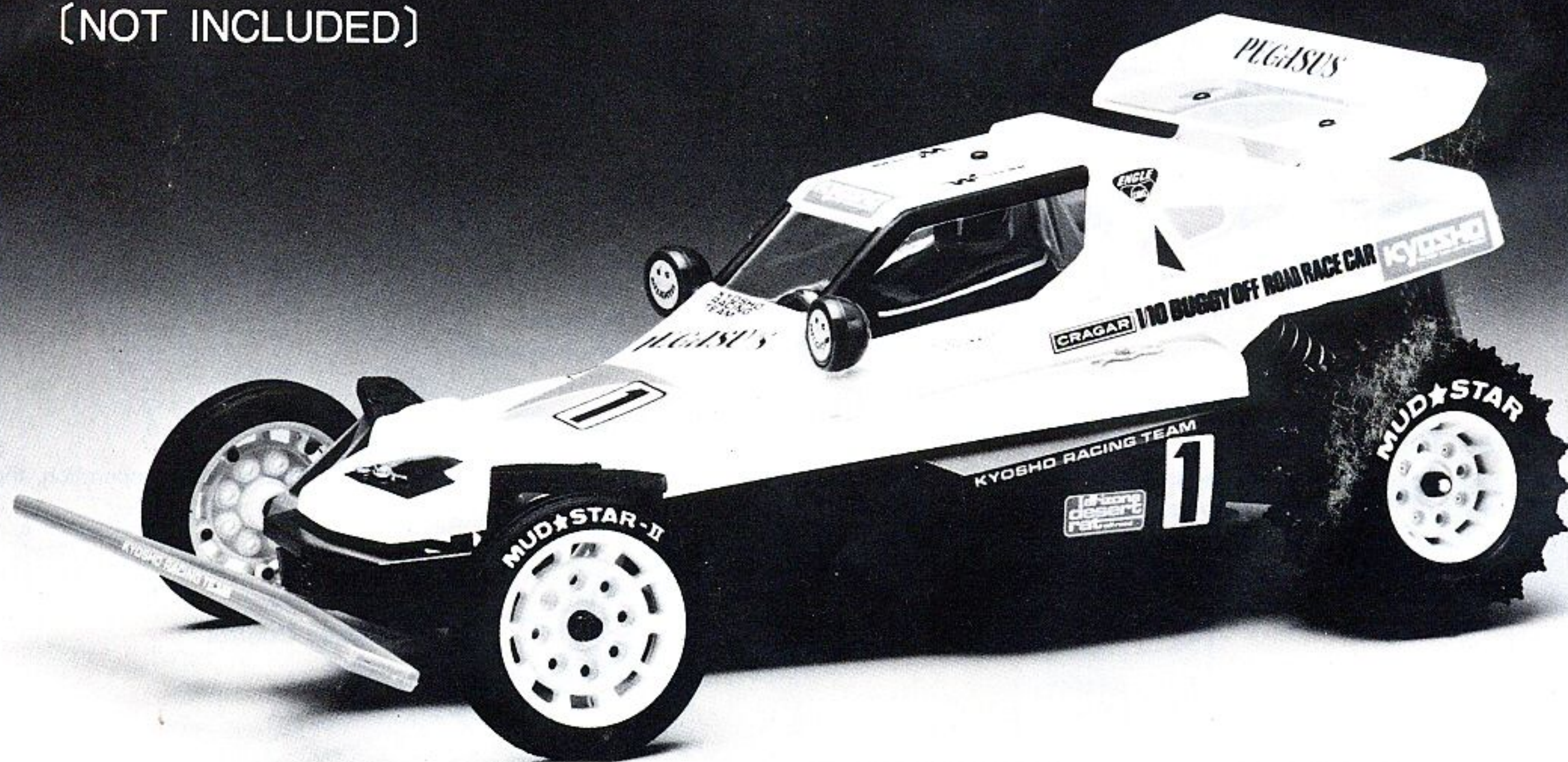
PEGASUS

RADIO CONTROLLED ELECTRIC POWERED RACING BUGGY

- ★ IDEAL ENTRY LEVEL ELECTRIC OFF-ROAD RACER
- ★ EASY ASSEMBLY WITH SIMPLE ADJUSTMENTS AND MAINTENANCE
- ★ SOPHISTICATED SUSPENSION SYSTEM FOR TOP HANDLING
- ★ "BIG LEAGUE" POWERFUL MABUCHI 540S MOTOR INCLUDED
- ★ DOUBLE WISHBONE FRONT SUSPENSION
- ★ SWING ARM REAR SUSPENSION
- ★ FRICTION-TYPE SHOCK ABSORBERS
- ★ TRUE GEAR-TYPE DIFFERENTIAL
- ★ LIGHTWEIGHT ABS THREE-PIECE RACING WHEELS
- ★ SPACIOUS CHASSIS BOX ACCEPTS ANY TYPE OF SERVO
- ★ INFINITE-FLEX PIVOT SYSTEM FOR TROUBLE-FREE SUSPENSION
- ★ LARGE FRONT BUMPER FOR MAXIMUM CRASH PROTECTION
- ★ ALL PNEUMATIC RUBBER TIRES

1:10 SCALE

BATTERY: 7.2V-1200mAh
RADIO: 2ch.
[NOT INCLUDED]



KYOSHO
THE FINEST RADIO CONTROL MODELS

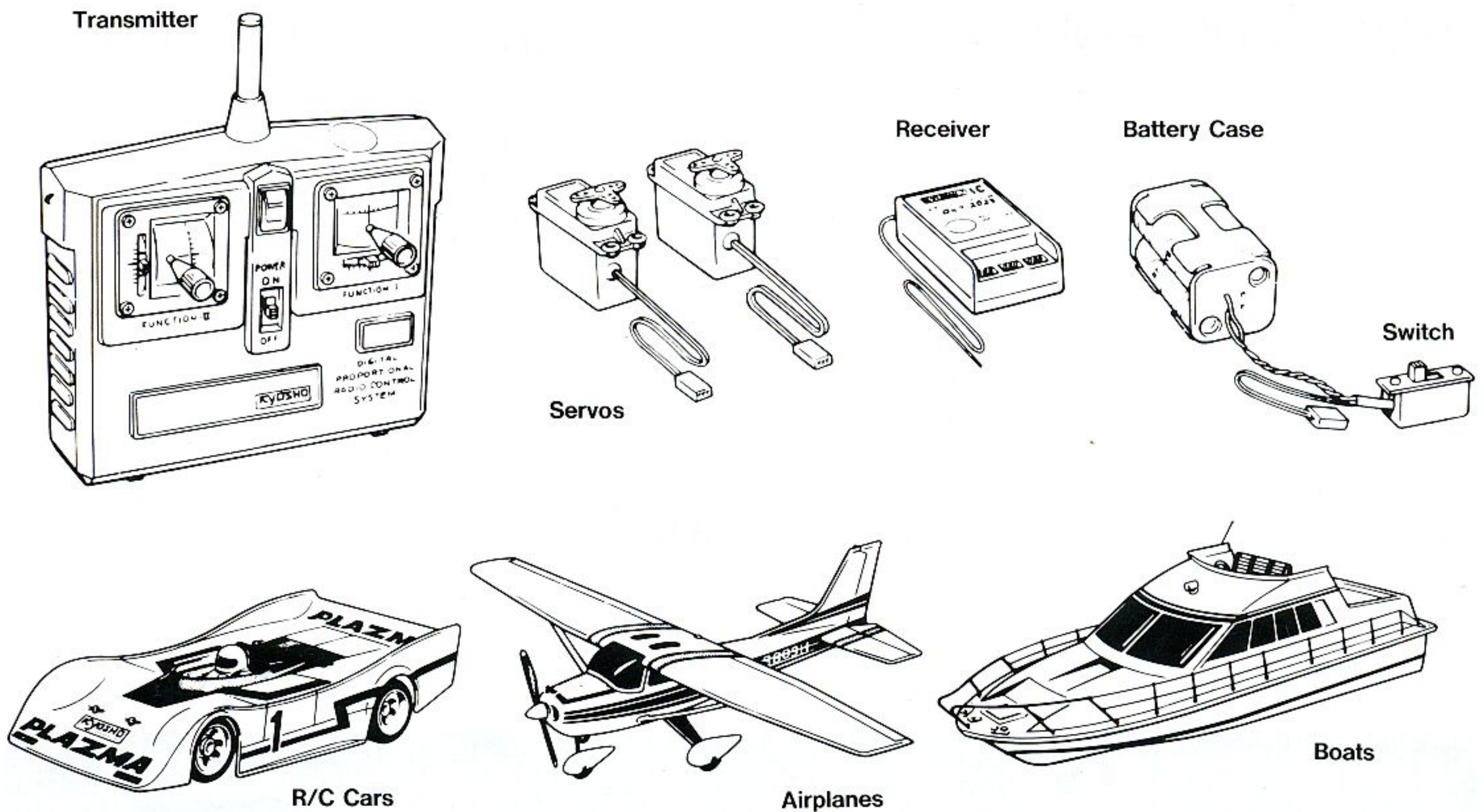
KIT No.3082

Injection X
A WEBSITE FOR THE SERIOUS RACER

PEGASUS

NOTES ON RADIO CONTROL SETS

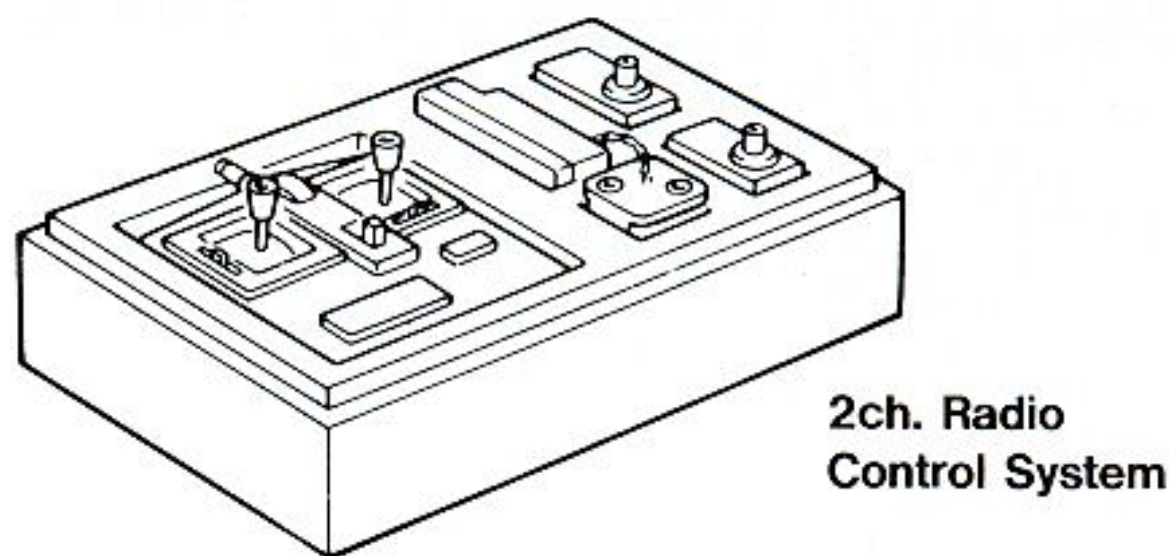
A digital proportional radio control set is required for operating this car. Two servos (standard or mini size) are required. The transmitter and receiver may be a 2-channel type, although a 3- or 4-channel set may be used with only two servos.



THINGS TO BE PROCURED BESIDES THE KIT

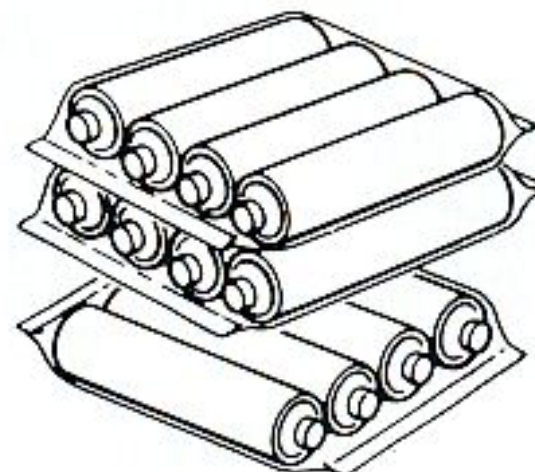
[2 channel Radio Control System]

Two types of transmitter are available. One uses a wheel for controlling the direction of the vehicle, while the other uses two "sticks" that control direction and speed when pushed sideways or backward/forward. The choice is yours, and depends on cost and comfort using it.



Batteries for radio set

Simple radio control sets use penlight dry cells for power. While such sets are the least expensive way to begin radio control operation, the batteries must be replaced regularly at appreciable cost. In the long run it is more economical to purchase a radio set that is supplied with nickel-cadmium (NiCd) batteries, or to substitute NiCd pencils for the disposable type.



CAR BATTERY

Pegasus is designed to use a rechargeable 7.2V 1200mAh NiCd battery pack. A Kyosho Racing Battery, part number 2218 (and some other brands) may be recharged at a wide range of rates. The charging rate depends on the type of charger used.

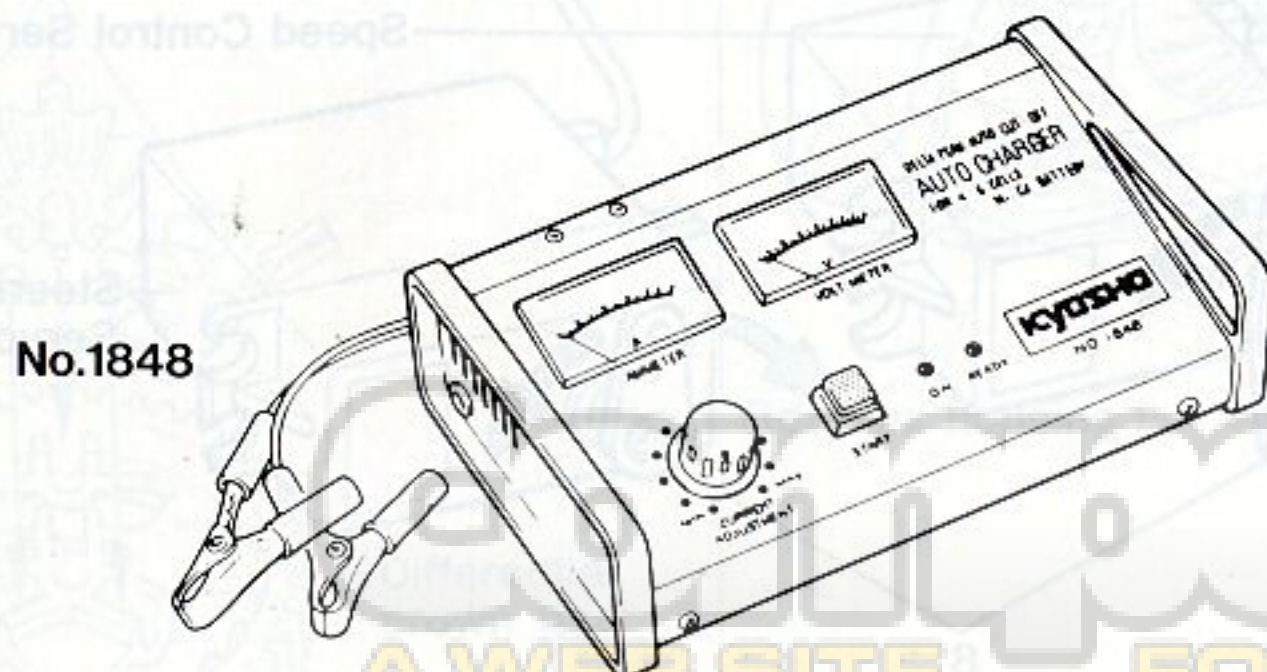
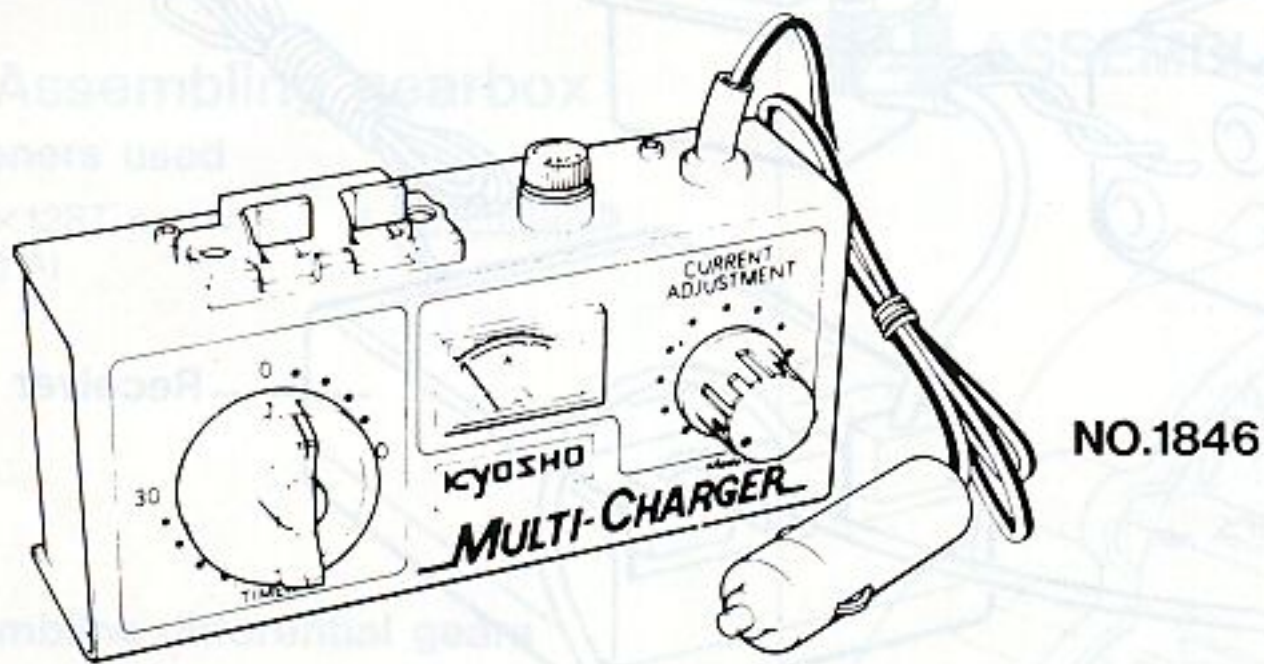
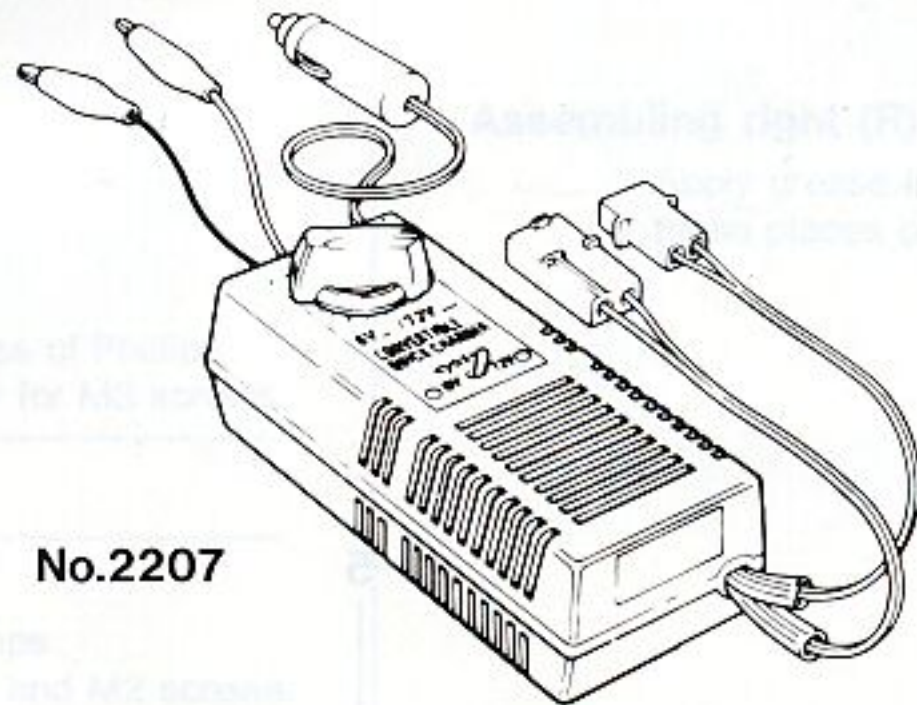


BATTERY CHARGER

The simplest charger supplies a low current, and the battery is charged for 14-16 hours. This type of charger operates on household AC power. Faster chargers are available, all operated from a well-charged 12V car battery. Using these, the battery pack can be recharged in 15-20 minutes. With two or three battery packs, it is possible to run the car almost continuously. Kyosho offers three types of fast charger.

Type 2207 charges at a constant current for a time set by a timer. Type 1846 allows adjusting the current using a built-in ammeter, and a timer shuts off the current at the time set by the user. Type 1848 also allows adjusting the current with a built-in ammeter, but a circuit in it monitors the voltage of the cells and cuts off the charging current when the cells are fully charged. The latter two can charge a battery pack to 100% of its capacity, while the first gives about 70% of full charge safely.

Item No.	Name of Charger	Charging time	Charging Rate	Features
No. 2207	Super Ni-Cd Rapid Charger (DC-12V)	15 minutes	about 70%	For beginners; timer built in
No. 1846	Multi Charger (DC 12V)	20 minutes	100%	Timer, ammeter built in
No. 1848	Auto Charger (DC 12V)	about 20 minutes	100%	Ammeter, volt-meter built in; automatic cut-off at peak of charge

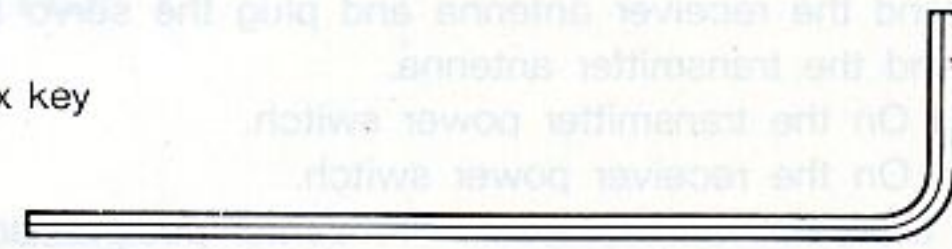


REQUIRED TOOLS

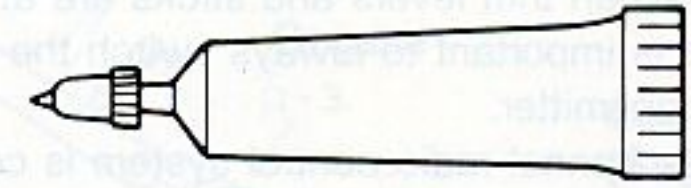
Several tools are required for assembling Pegasus.

The following are included with the kit:

1.5mm hex key

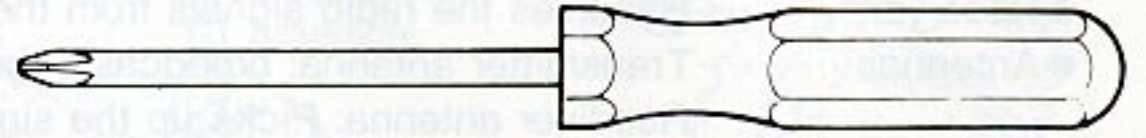


Grease

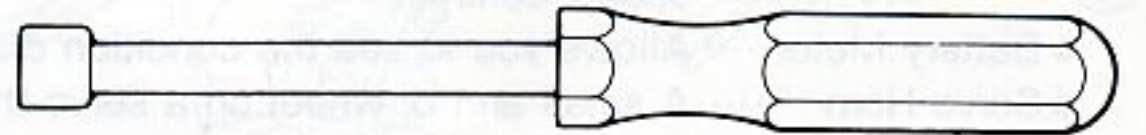


The following are not included:

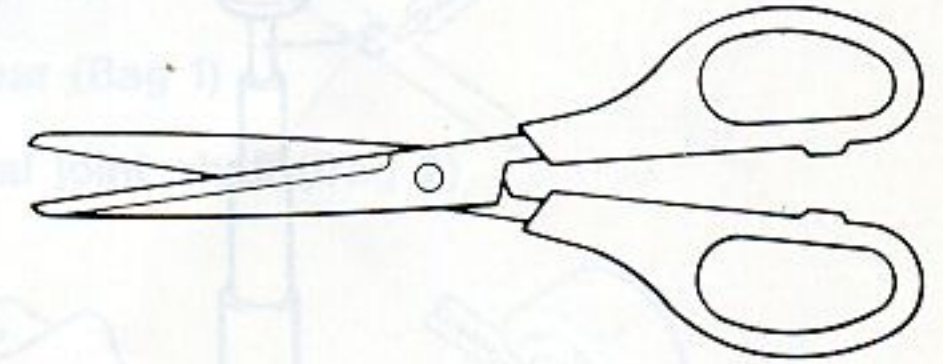
Phillips-head screwdriver (medium size)



5 and 7mm nutdrivers or socket wrenches



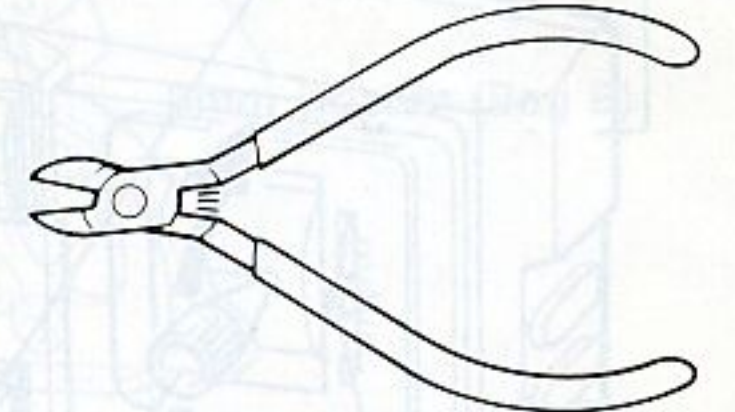
Scissors



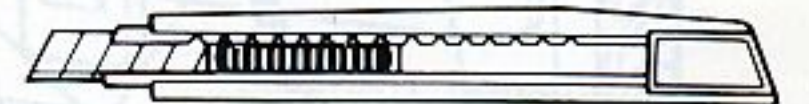
Awl or 3mm and 4mm drills



Wire cutter



Hobby "cutter" knife



Cyanoacrylate adhesive



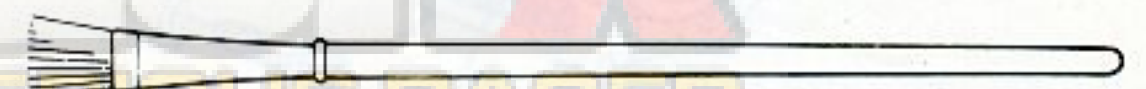
The following items are useful for finishing the body attractively:

Polyca (or similar) acrylic paint



Micron-line tape

Small paint brush

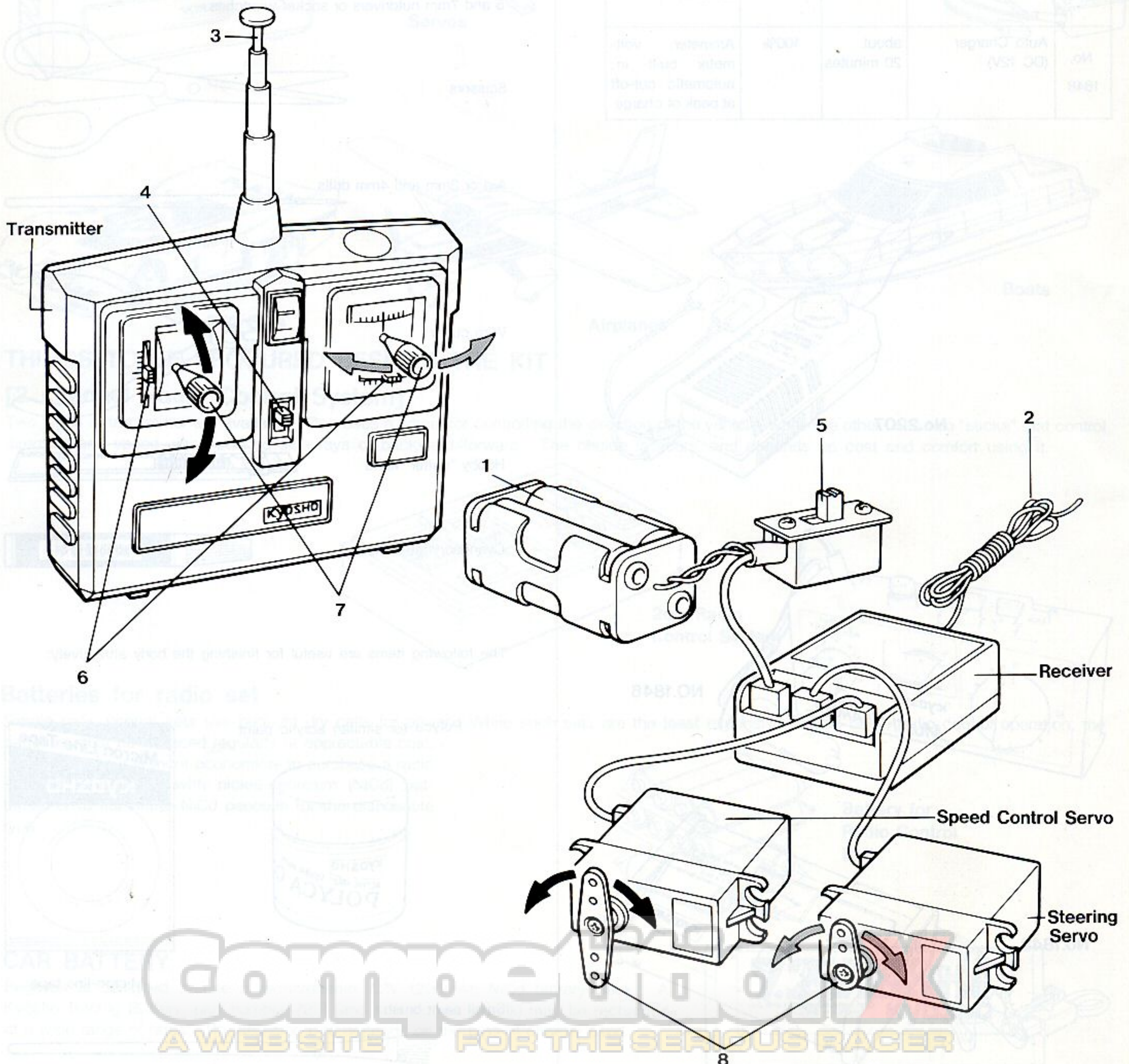


CHECKING YOUR RADIO SYSTEM

1. Install the batteries into both the transmitter and receiver. If your radio uses rechargeable batteries, charge it as outlined in the manual that came with your set.
 2. Unwind the receiver antenna and plug the servo and battery connectors into the receiver.
 3. Extend the transmitter antenna.
 4. Turn On the transmitter power switch.
 5. Turn On the receiver power switch.
 6. Set the small trim levers to the center position and make sure that both main control sticks are also centered.
 7. Move both main control sticks slowly through their full travel. The servo horns should move in proportion to the movement of your sticks.
 8. When trim levers and sticks are at their neutral positions, the servo horns should be centered. Switch off the transmitter, then the receiver.
- It is important to always switch the transmitter on first..... then the receiver. When turning off the system, turn off the receiver first, then the transmitter.

A 2-channel radio control system is composed of a transmitter, receiver, two servos, and a battery holder (for the receiver.)

- Transmitter.....A "box" with external controls ("sticks" or a wheel and trigger, for example) that can be moved by the operator to control the model by means of a radio signal.
- Receiver.....Receives the radio signals from the transmitter and operates the required servo(s).
- Antennas.....Transmitter antenna: broadcasts the radio signal produced by the transmitter.
Receiver antenna: Picks up the signals from the transmitter and conducts them to the receiver.
- Servos.....Electric motor units that move the controls of the model in response to the movements of the controls of the transmitter.
- Trim Levers.....Adjust the neutral position of the servos from the transmitter. Trim levers provide fine tuning of the steering and speed control.
- Battery Meter..... Allows you to see the condition of your transmitter batteries.
- Servo Horn.....A small arm or wheel on a servo that transfers the movement of the servo.



BEFORE ASSEMBLY

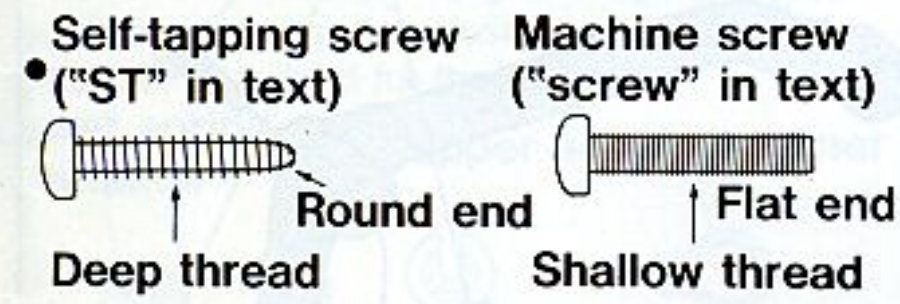
Please read through these instructions before assembly. Your thorough understanding of the assembly will enable you to build the kit without difficulty. Check the components in the kit prior to starting assembly. Any claim for replacement or refund for a model in the process of assembly will not be accepted.

Apply "GREASE" to points indicated with "Grease" mark.

Assembly is simple and straightforward. Just follow each of the following instructions, step by step, and refer to the drawings for an illustration of the appearance of each assembly.

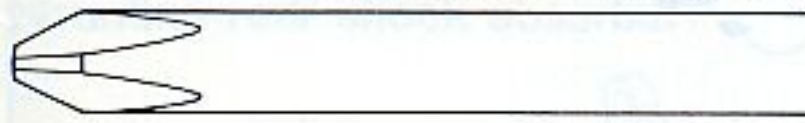
Large parts are identified individually. Small parts, like screws and washers, are identified by the parts bag in which they are packed.

Note: Every screw, etc., has a specific place in which it is to be used. Please refer to the text and drawings to find a description and illustration of the part required.

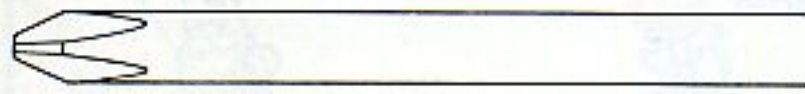


Screws are shown full size in these sections. Match the actual screw with the drawing to be sure of having the right part for each place.

Use this size of Phillips screwdriver for M3 screws.



Use this size of Phillips screwdriver for M2.6 and M2 screws.



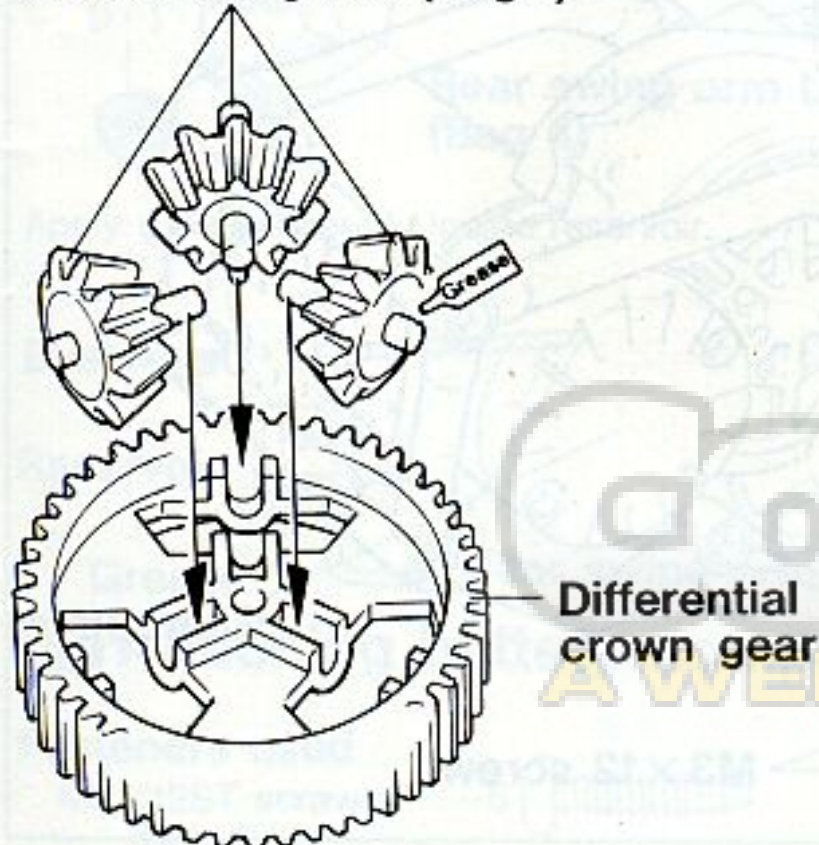
2 Assembling gearbox

Fasteners used

M3×12ST screw 5 (Bag A)

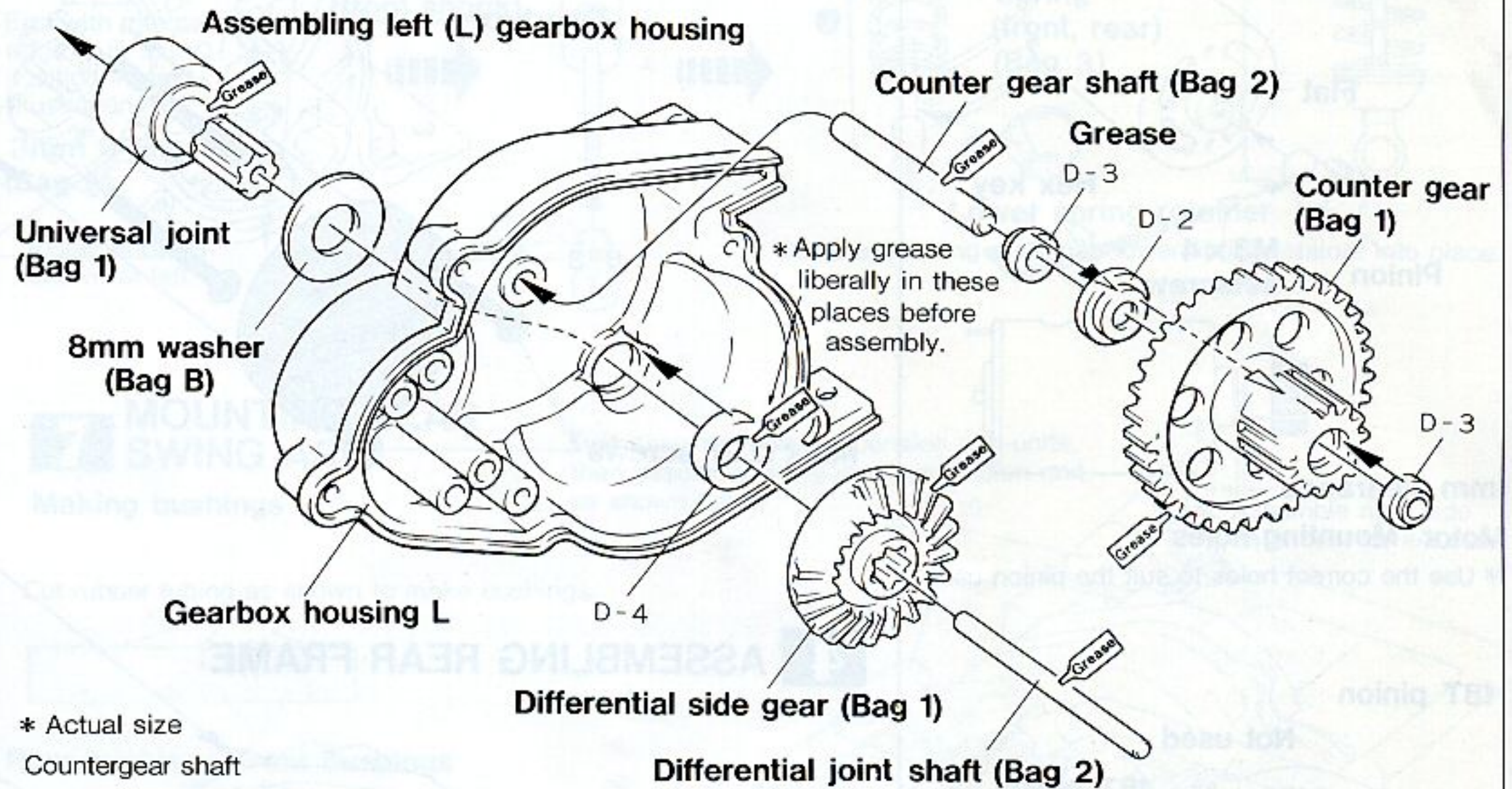
Assembling differential gears

Differential gears (Bag 1)



1 ASSEMBLING GEARBOX-STEP 1

* Assemble counter gear and shaft first.

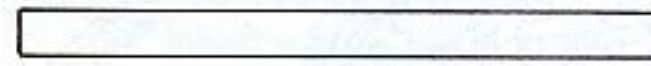


* Actual size

Countergear shaft

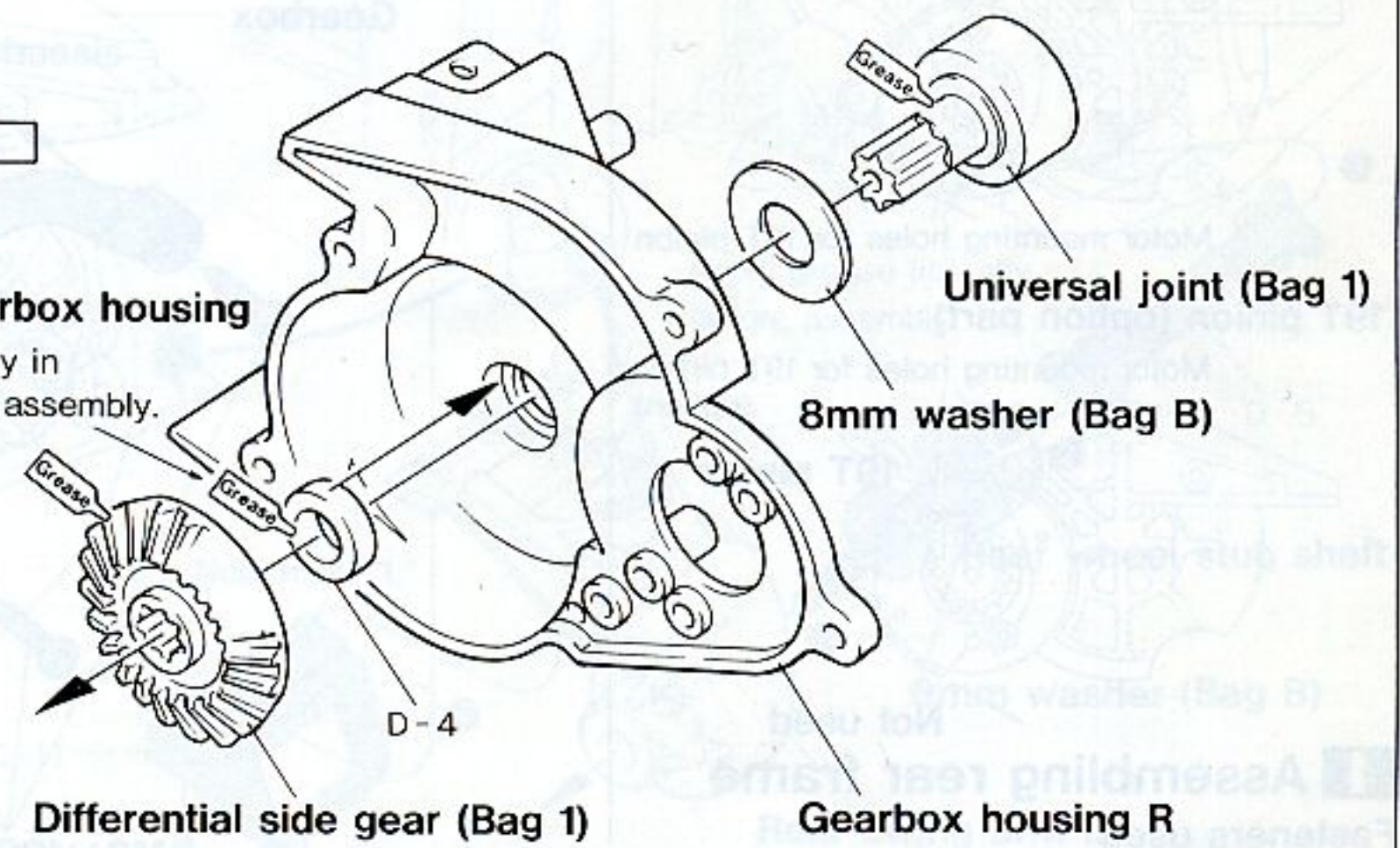


Differential joint shaft

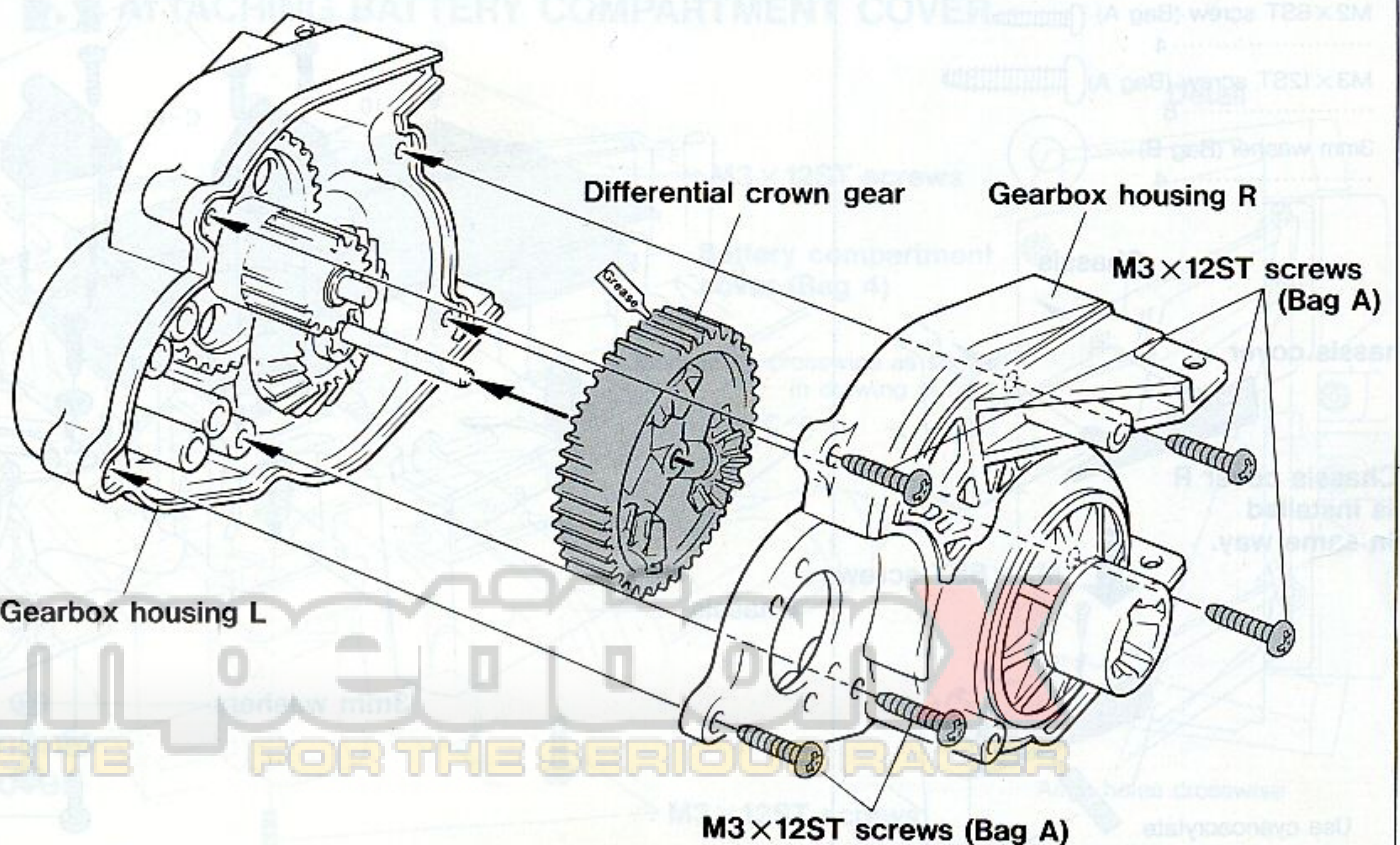


Assembling right (R) gearbox housing

Apply grease liberally in these places before assembly.

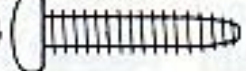




2 ASSEMBLING GEARBOX-STEP 2

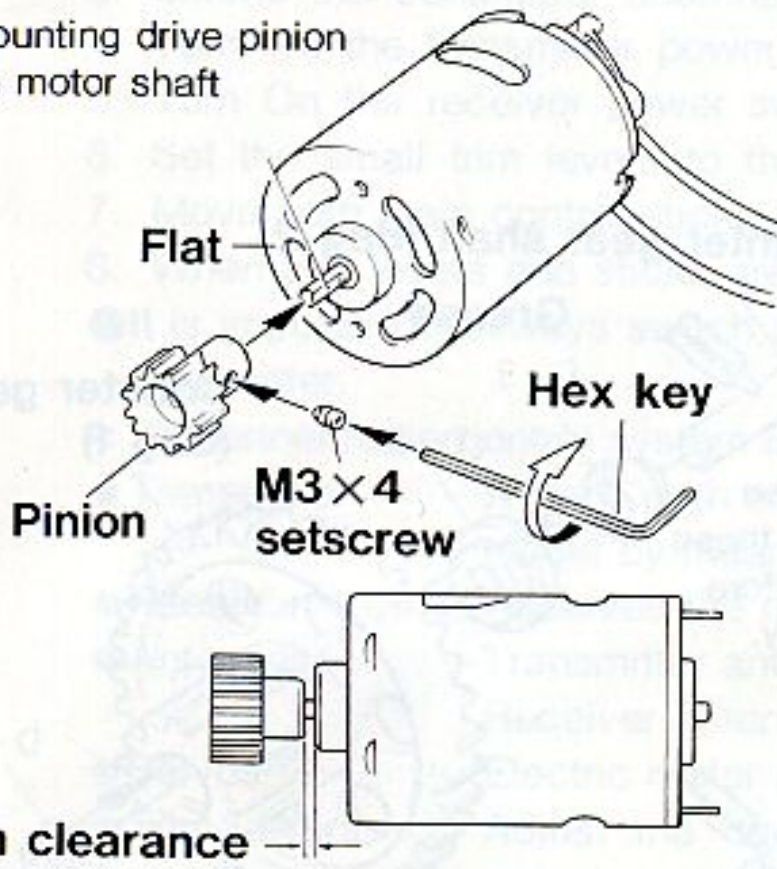


3 Installing motor

Fasteners used

- M3×12ST screw (Bag A)  2
- M3×30 screw (Bag B)  2
- M3×4 setscrew (Bag B)  1

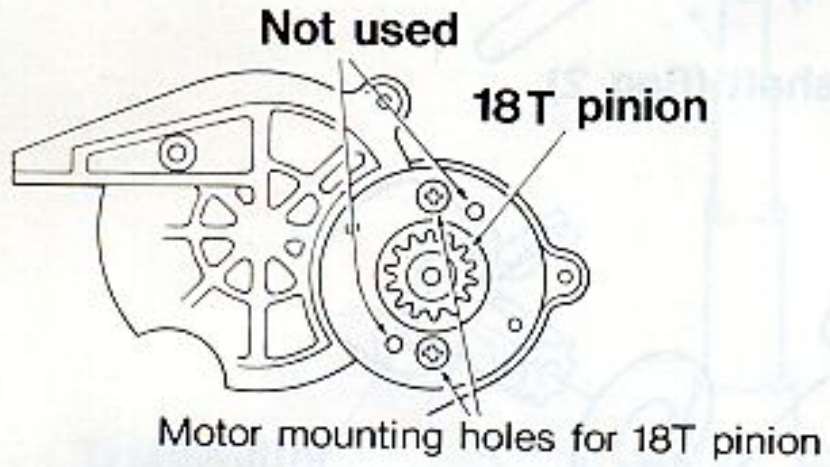
Mounting drive pinion on motor shaft



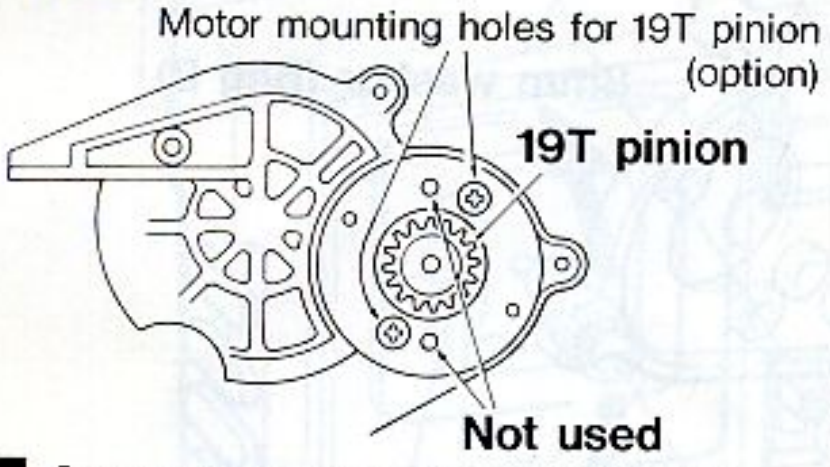
Motor Mounting holes

* Use the correct holes to suit the pinion used.

18T pinion




19T pinion (option part)




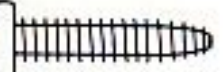

4 Assembling rear frame

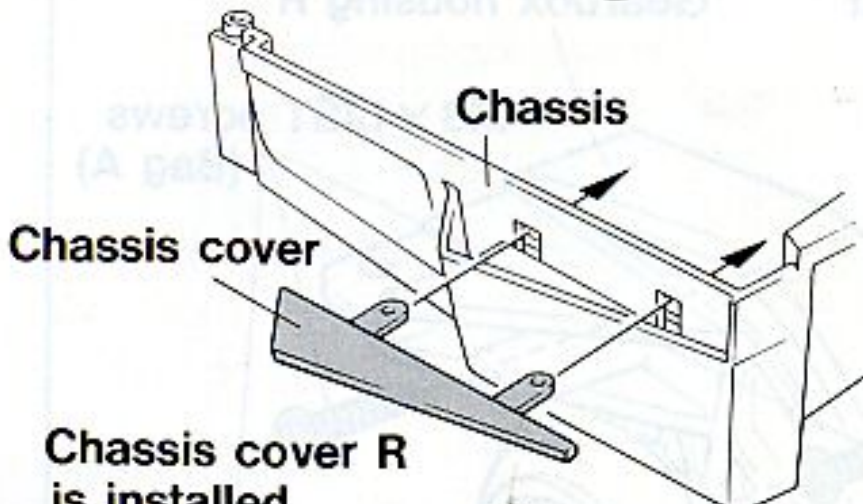
Fasteners used

- M3×12ST screw (Bag A)  8

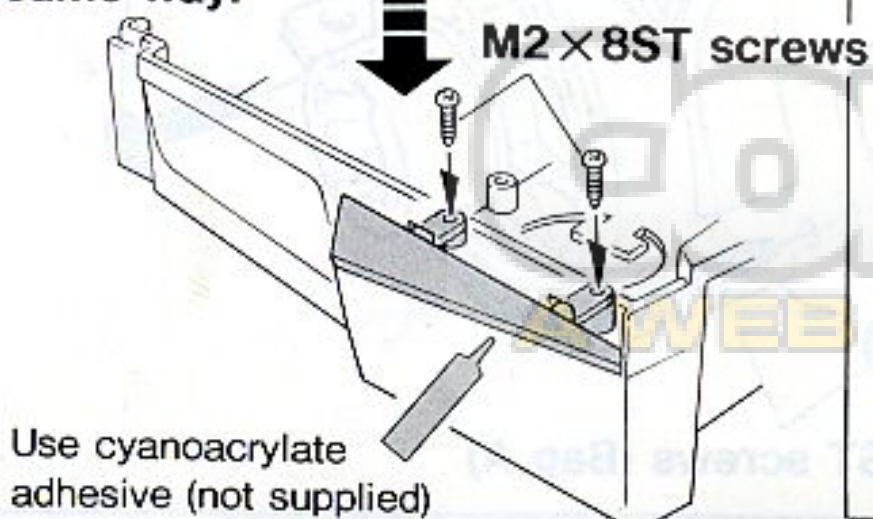
5 Mounting gearbox

Fasteners used

- M2×8ST screw (Bag A)  4
- M3×12ST screw (Bag A)  8
- 3mm washer (Bag B)  4

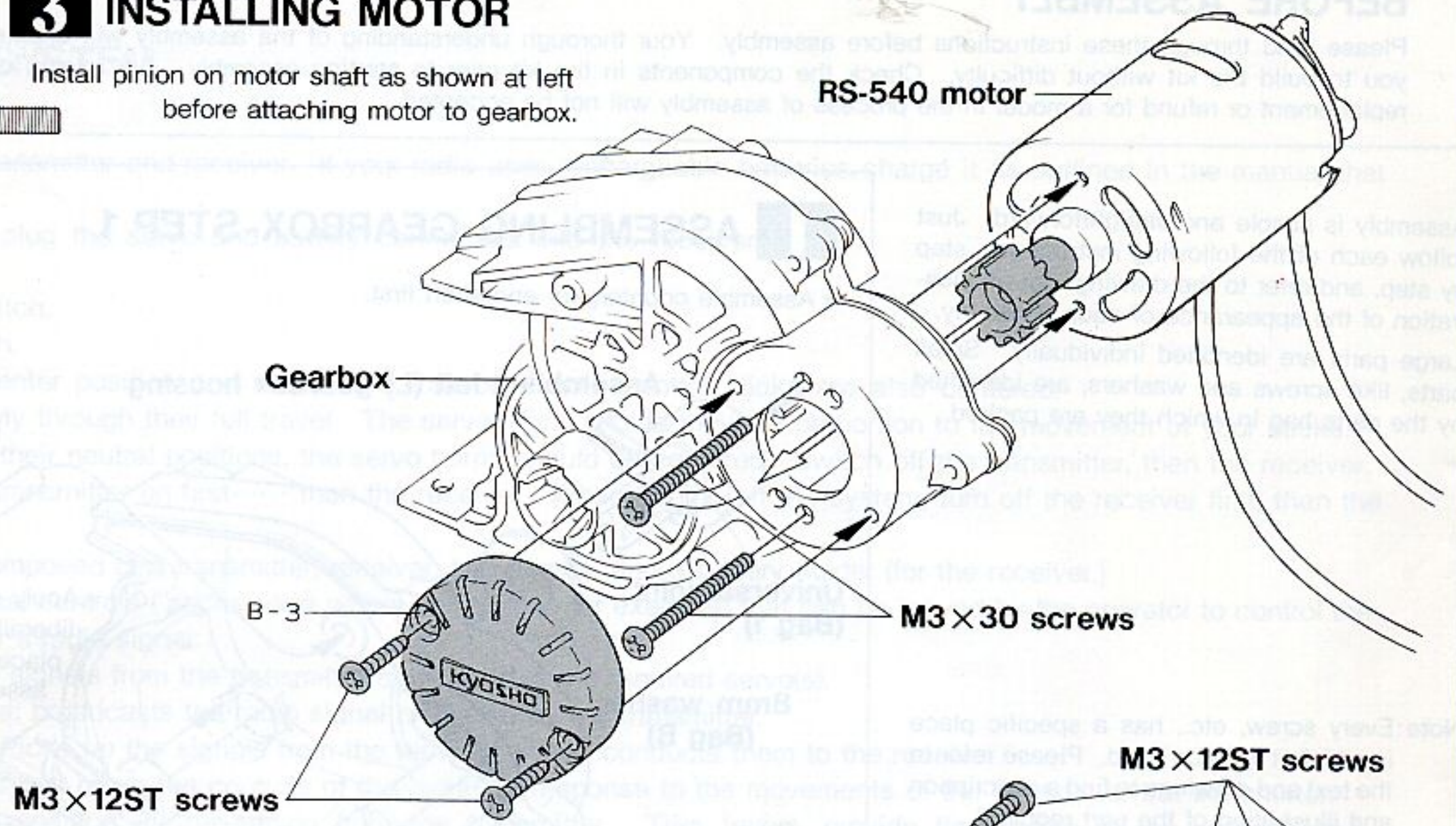


Chassis cover R is installed in same way.

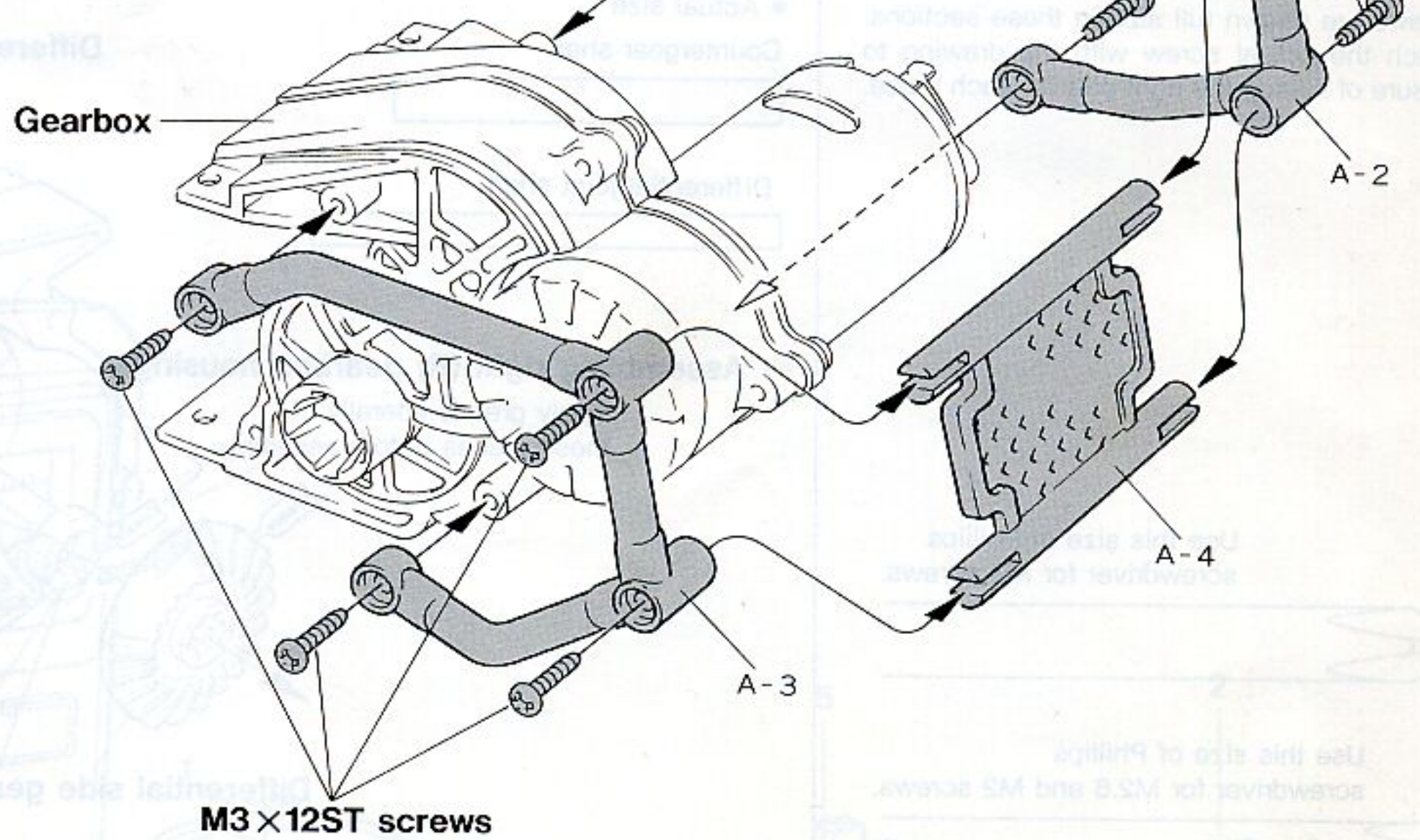


3 INSTALLING MOTOR

Install pinion on motor shaft as shown at left before attaching motor to gearbox.

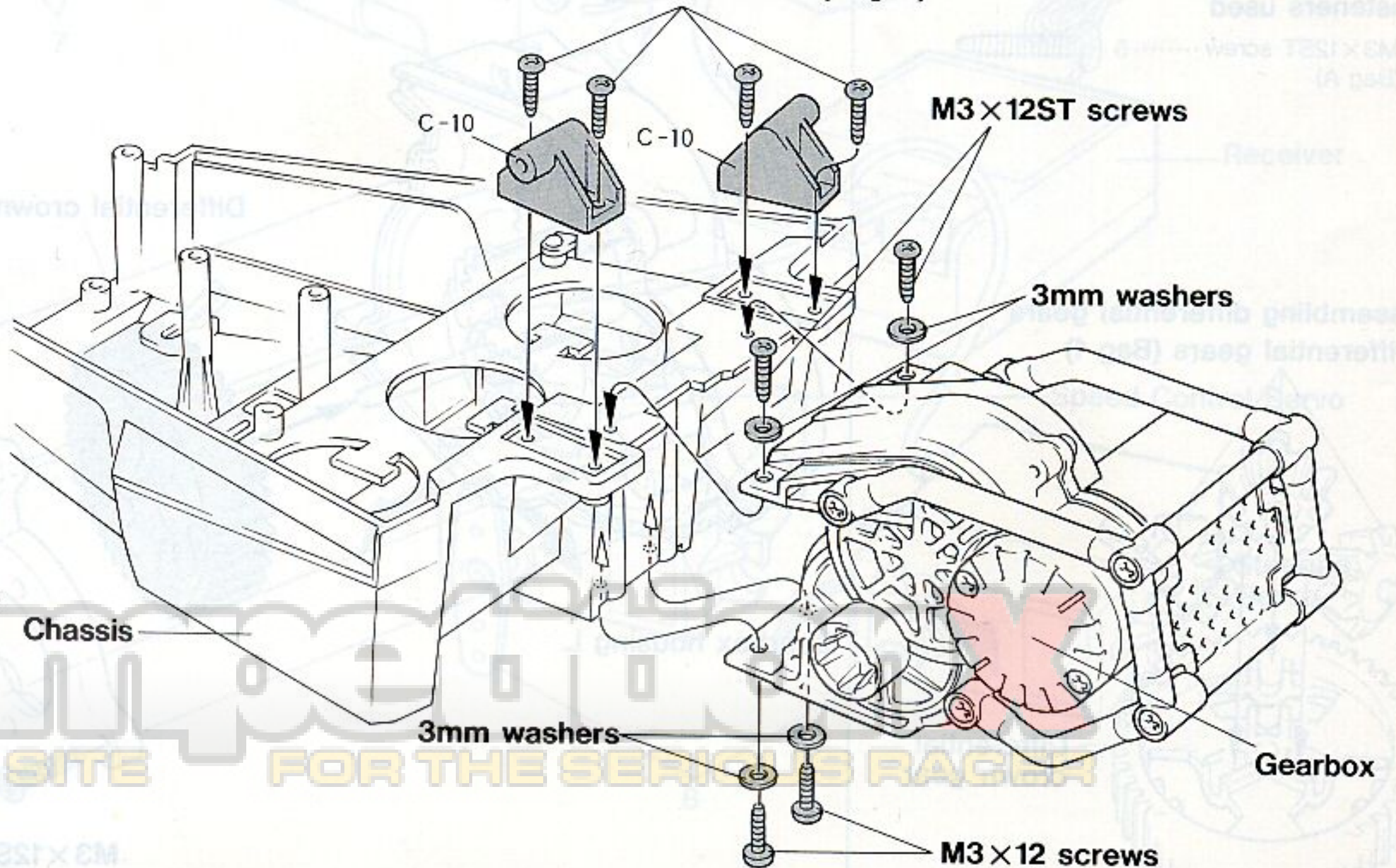


4 ASSEMBLING REAR FRAME



5 INSTALLING GEARBOX

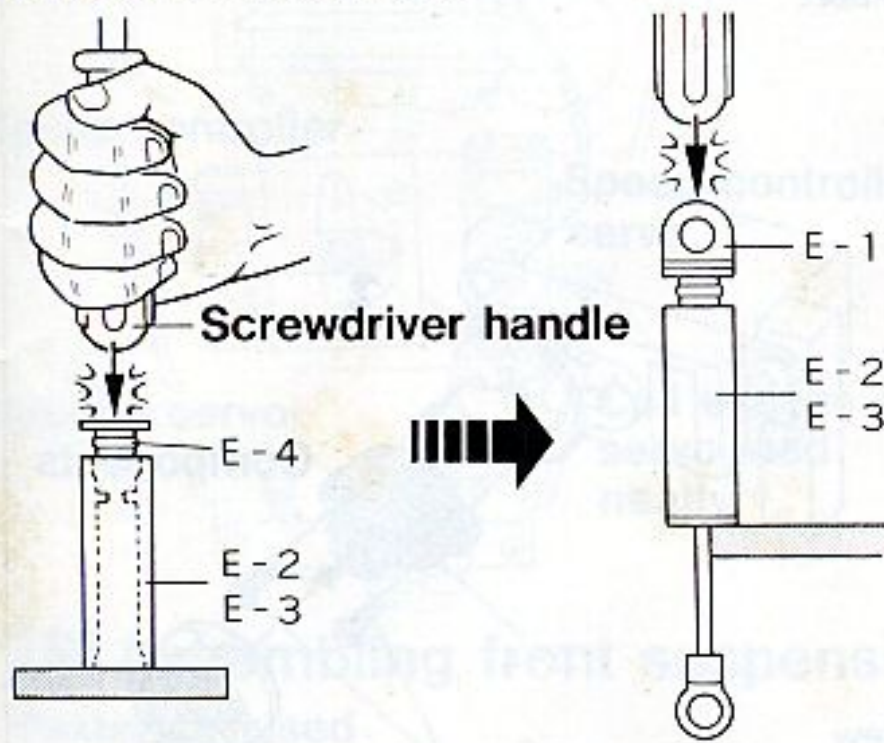
M3×12ST screws (Bag A)



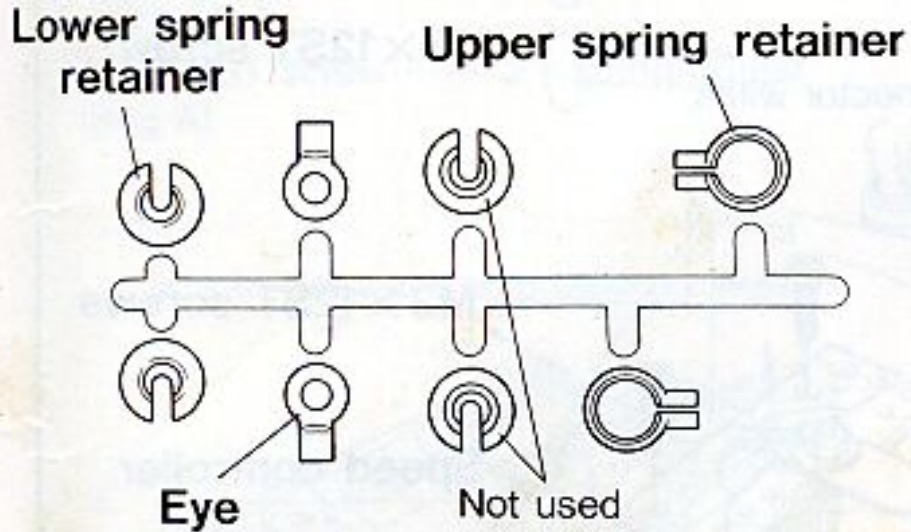
6 Assembling shock absorbers

Fasteners used
M2×8ST screw.....4 (Bag A)

The two front shock absorbers are shorter than the rear pair.
Place the cylinder on a hard surface, put the O-ring into place, then tap the end cap into place with a screwdriver handle or similar firm (but not hard) object.



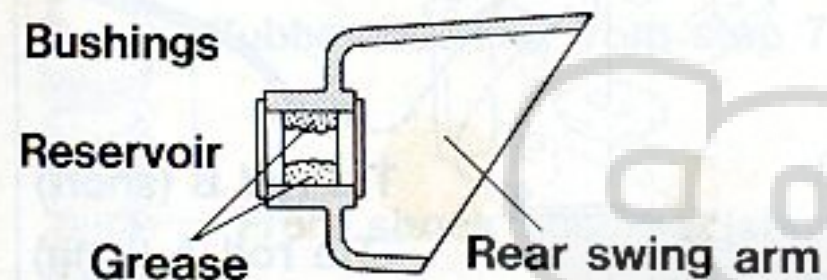
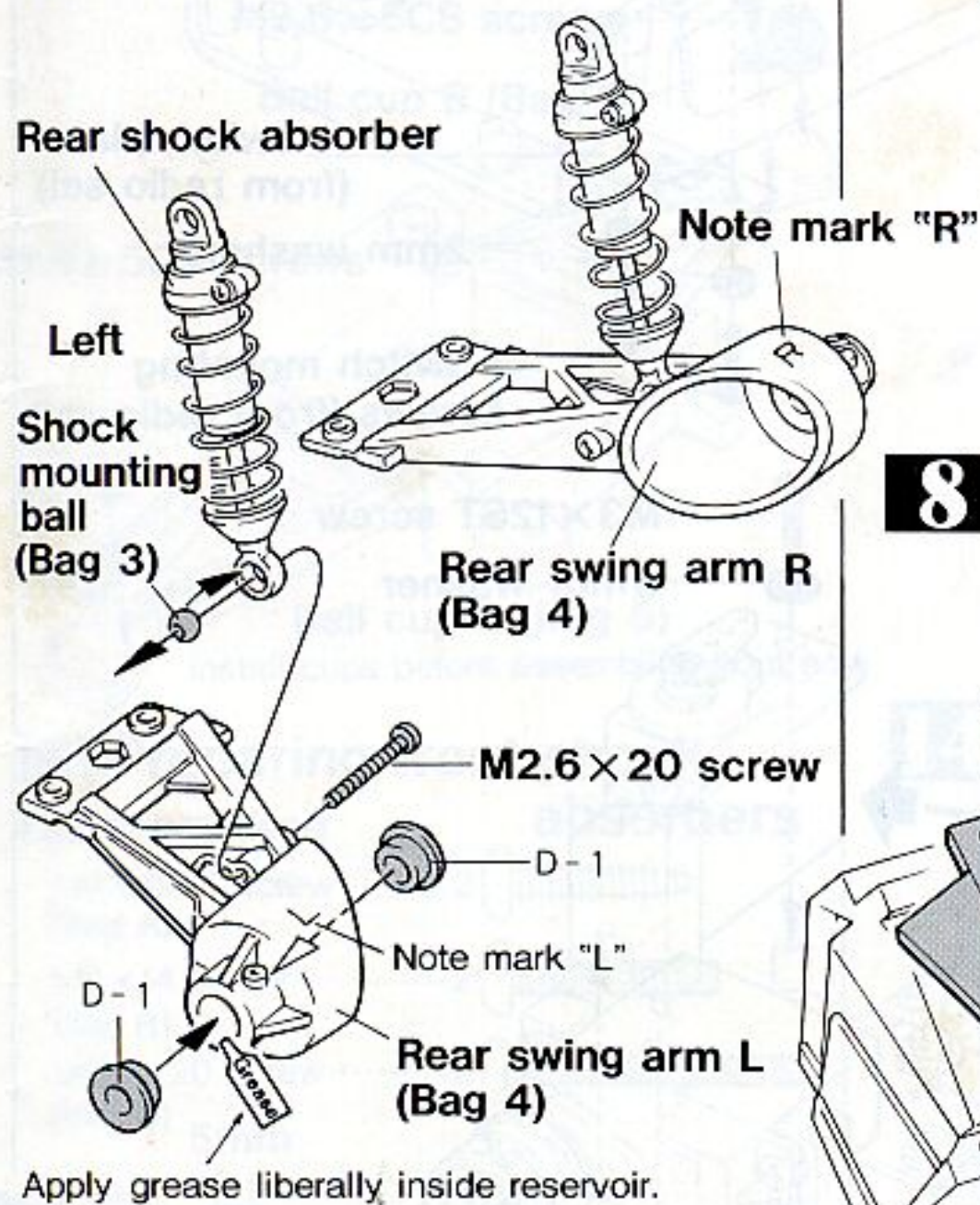
Place shock absorber body on edge of a hard surface and tap the bushing-end cap into place as described for the end cap.



7 Assembling rear swing arms

Fasteners used
M2.6×20 screw.....2 (Bag B)
M3×14ST screw.....4 (Bag A)
3mm washer.....2 (Bag B)

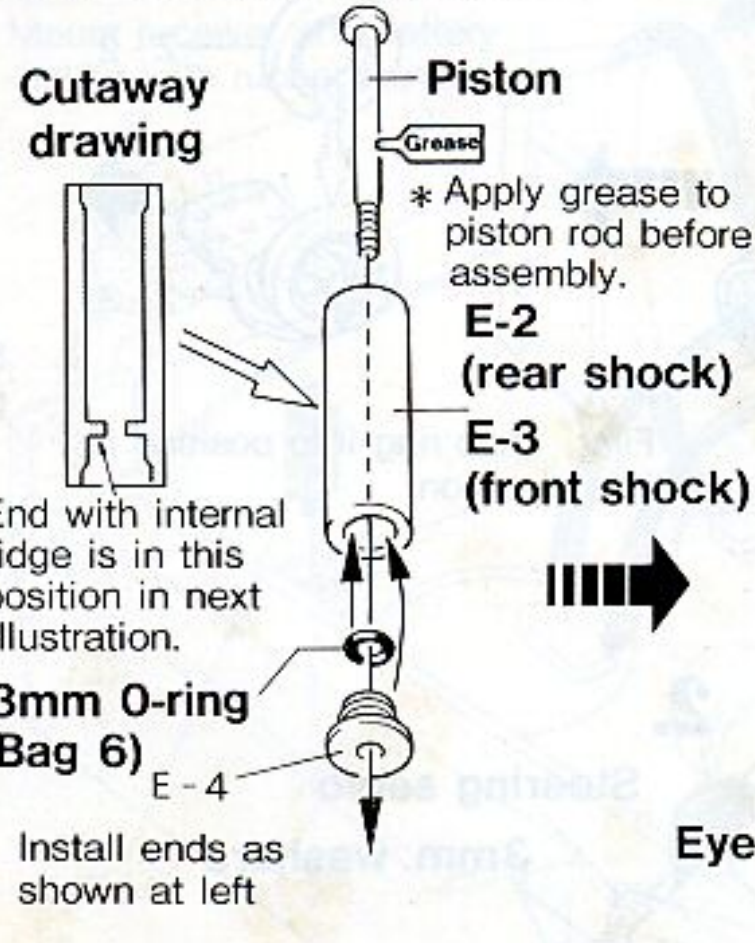
Mounting rear shock absorber



8 Attaching battery compartment cover

Fasteners used
M3×12ST screw.....5 (Bag A)

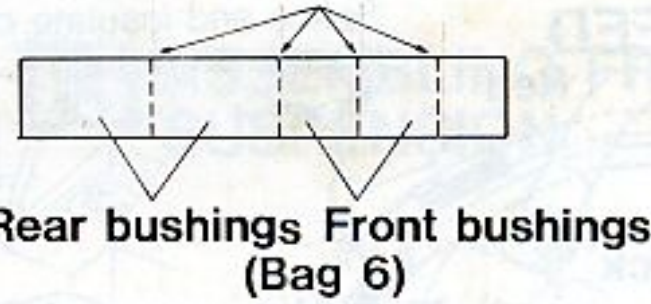
6 ASSEMBLING SHOCK ABSORBERS



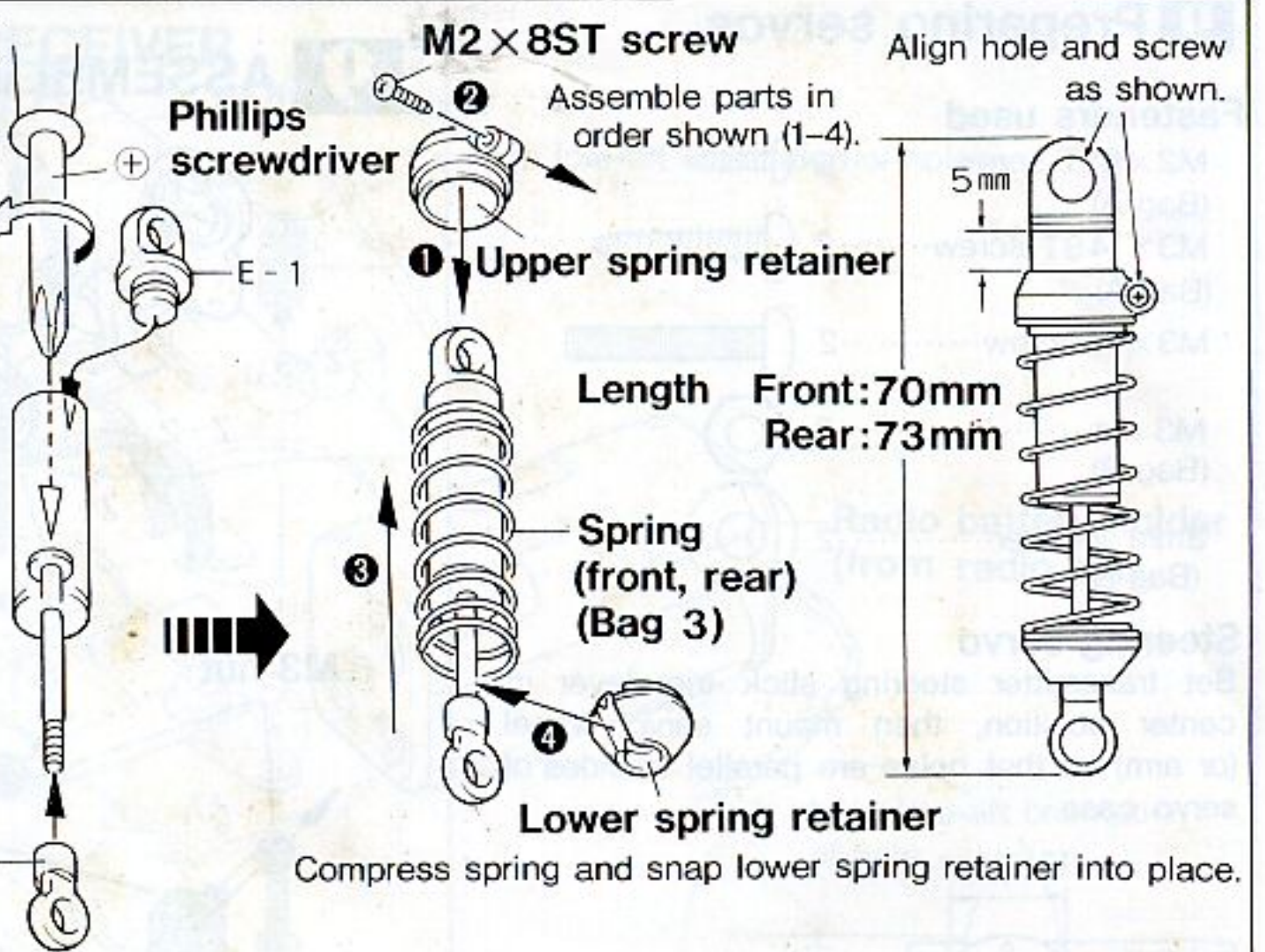
7 MOUNTING REAR SWING ARM

Making bushings

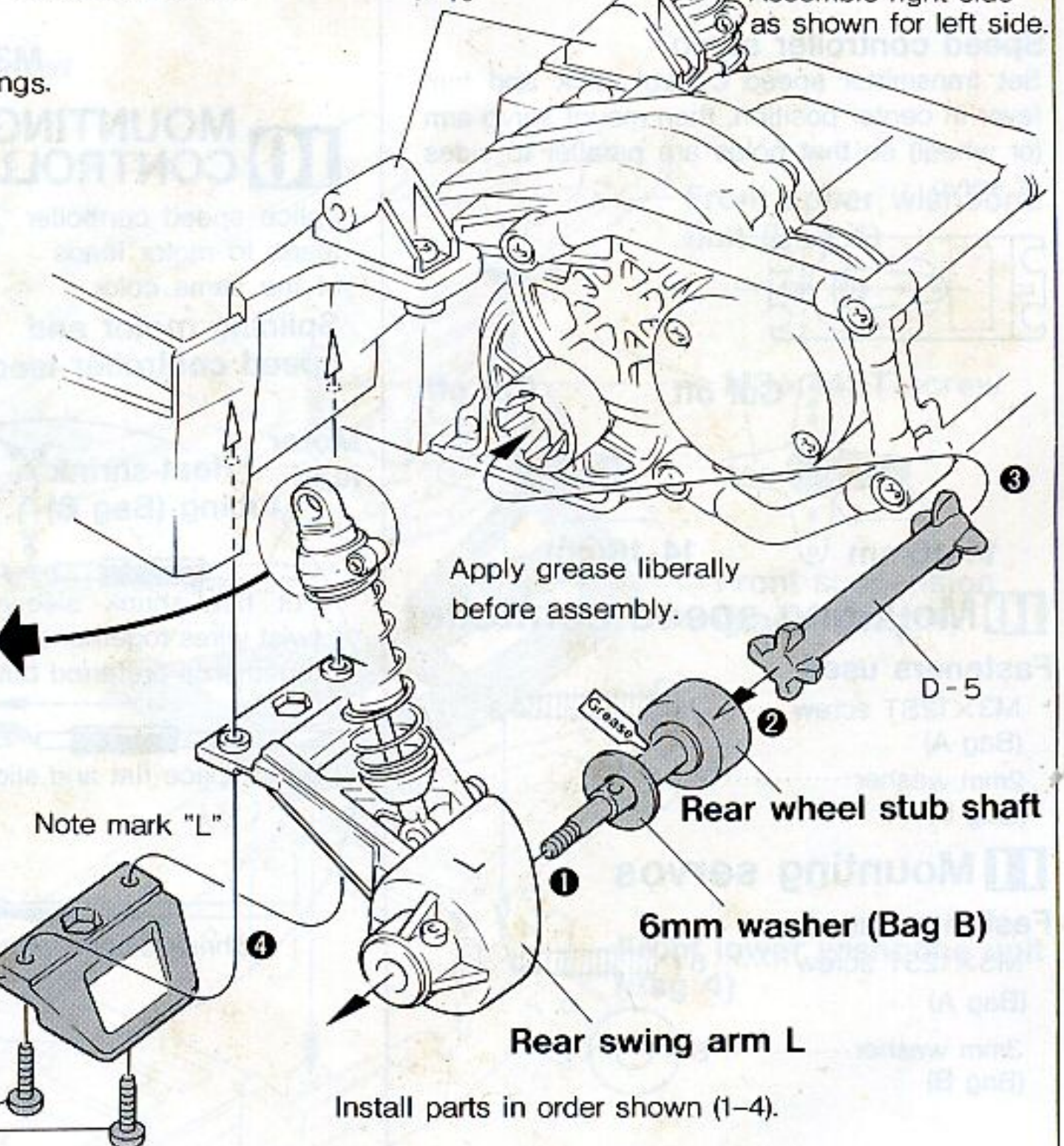
Cut rubber tubing as shown to make bushings.



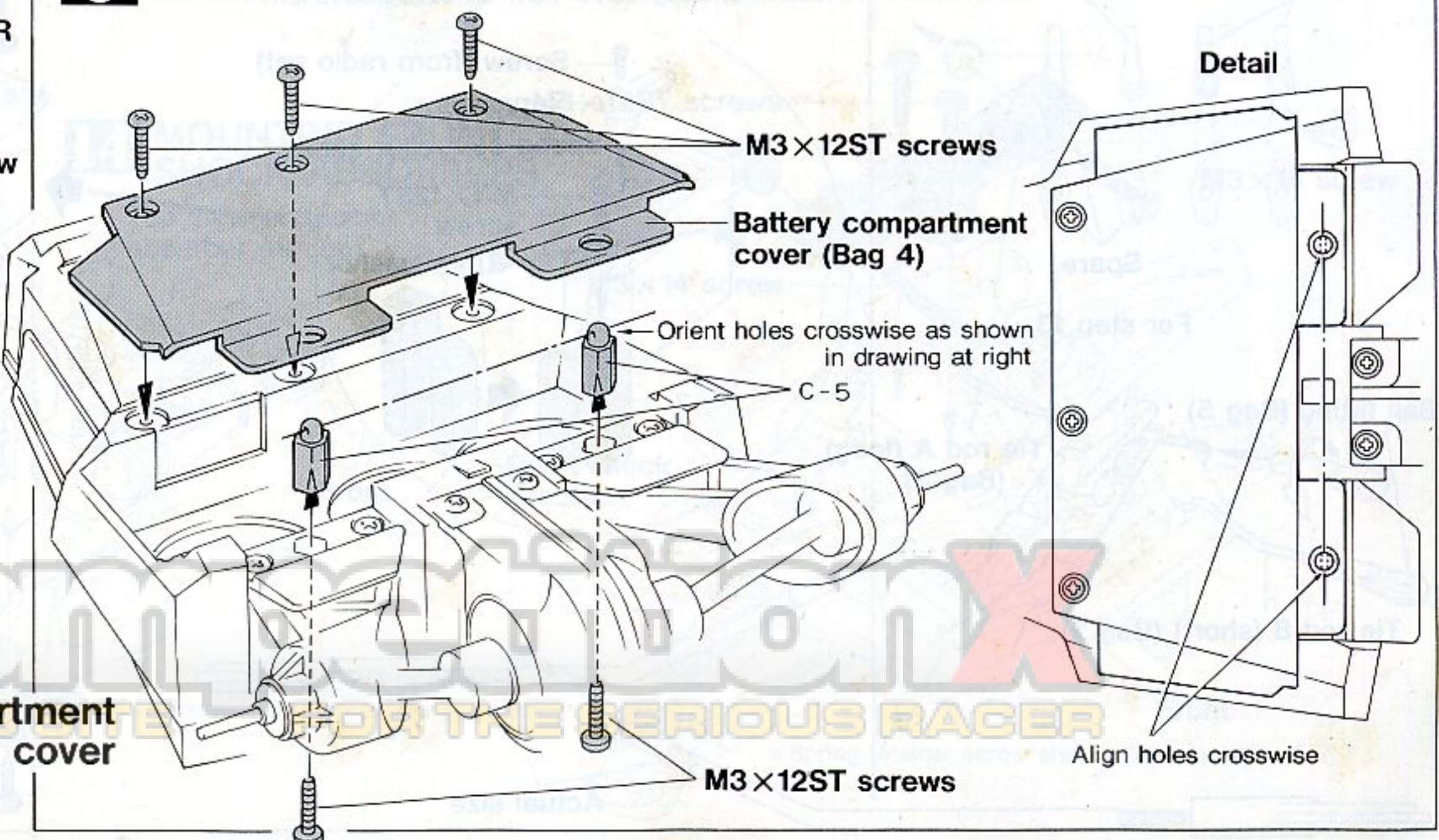
Attaching rear shocks to chassis



First assemble rear suspension sub-units, then assemble entire rear suspension unit as shown below.



8 ATTACHING BATTERY COMPARTMENT COVER



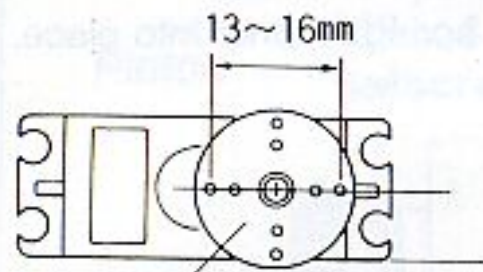
9 Preparing servos

Fasteners used

- M2×6ST screw 2 (Bag A)
- M3×14ST screw 2 (Bag A)
- M3×14 screw 2
- M3 nut 2 (Bag B)
- 3mm washer 2 (Bag B)

Steering servo

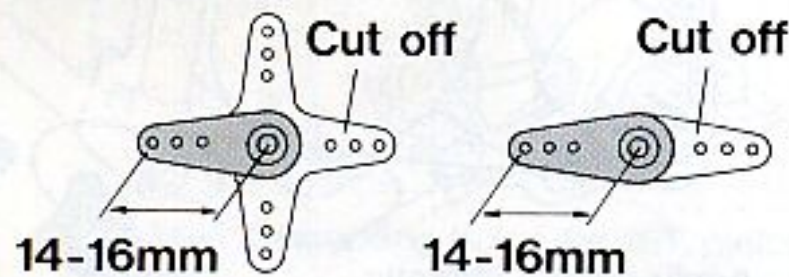
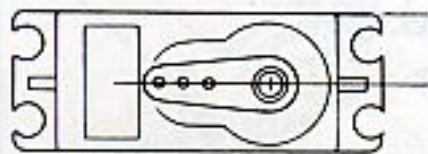
Set transmitter steering stick trim lever in center position, then mount servo wheel (or arm) so that holes are parallel to sides of servo case.



Use holes in servo wheel (or arm) that are 13-16mm apart. (Holes should be equal distance on each side of screw.)

Speed controller servo

Set transmitter speed control stick and trim lever in center position, then mount servo arm (or wheel) so that holes are parallel to sides of servo.



10 Mounting speed controller

Fasteners used

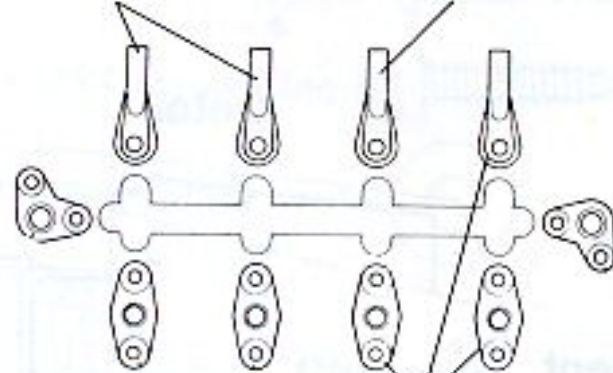
- M3×12ST screw 2 (Bag A)
- 2mm washer 2 (Bag B)

11 Mounting servos

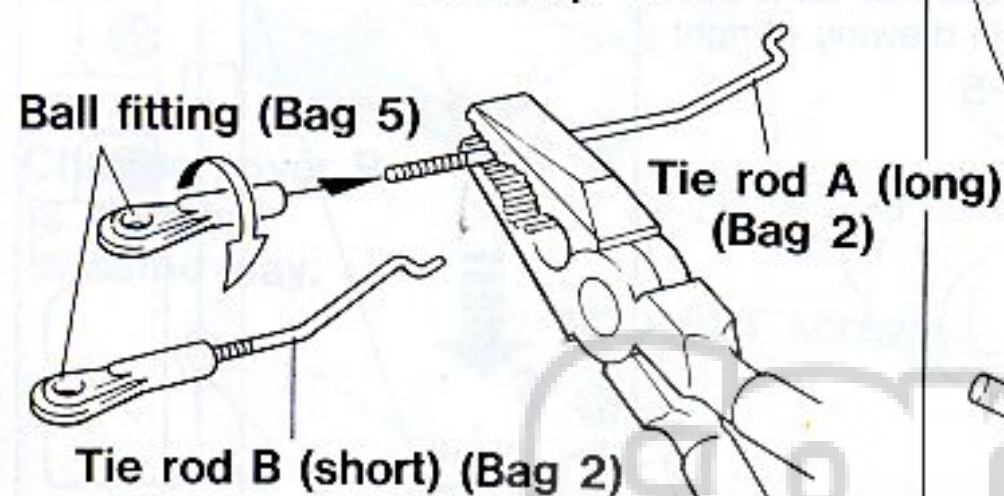
Fasteners used

- M3×12ST screw 6 (Bag A)
- 3mm washer 6 (Bag B)

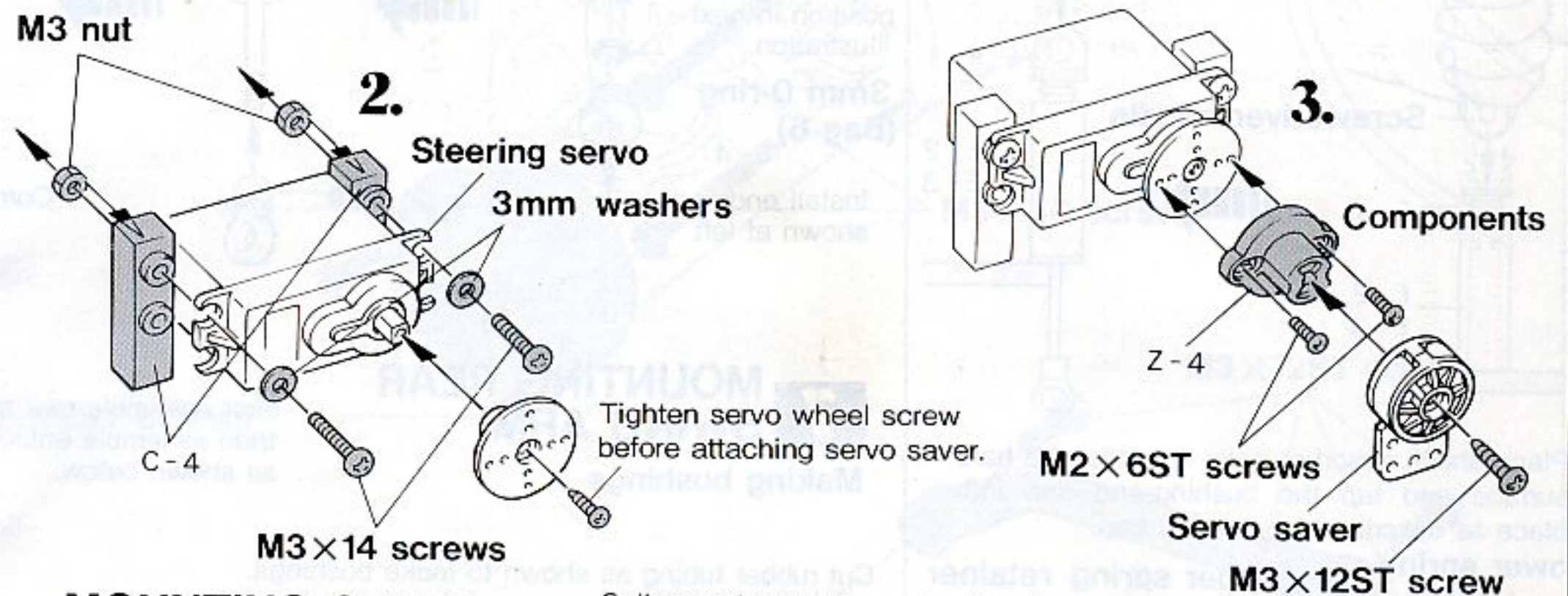
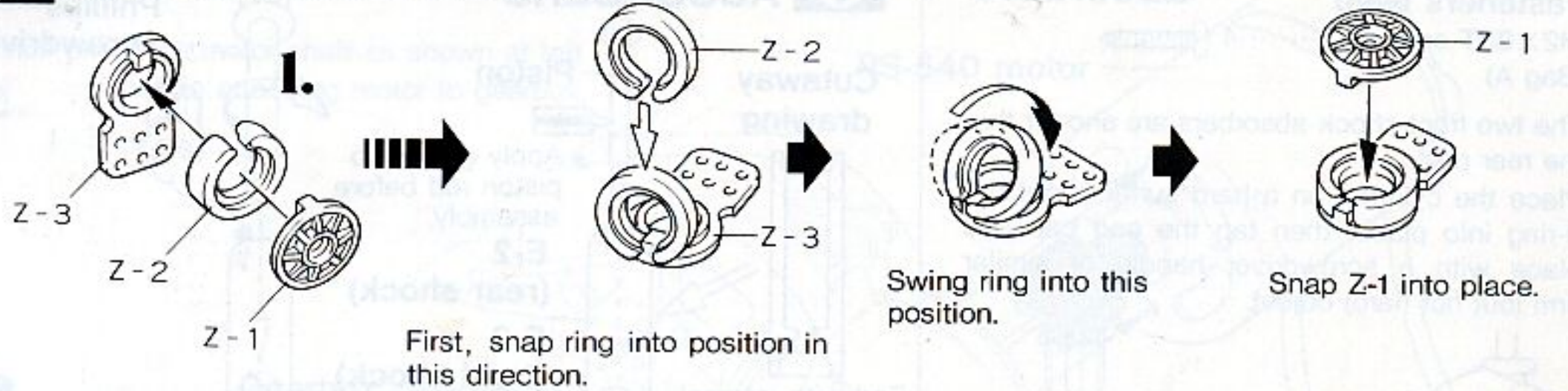
For steering gear For speed controller



For step 13



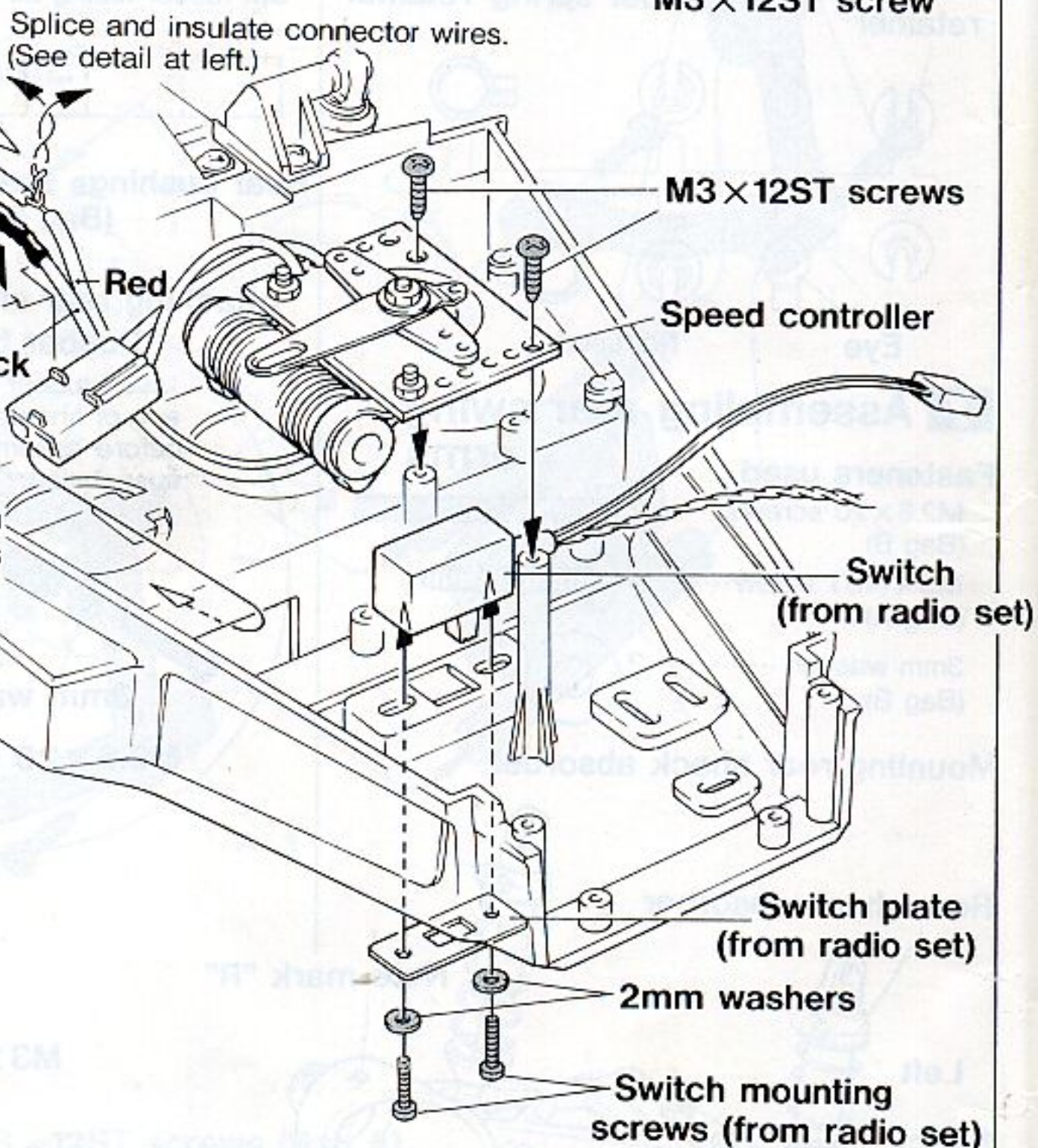
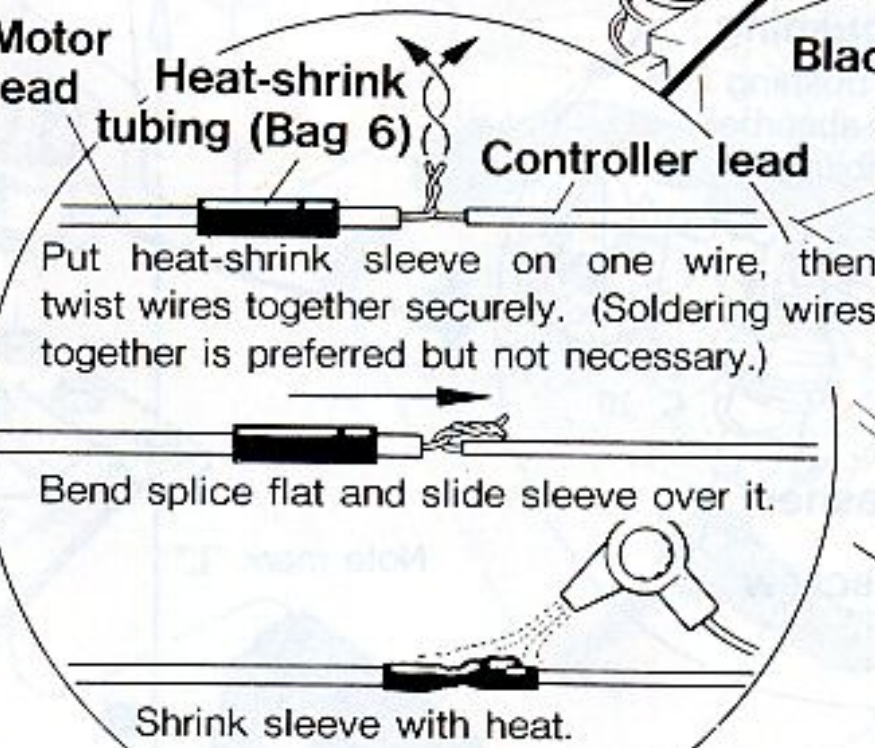
9 ASSEMBLING SERVO SAVER



10 MOUNTING SPEED CONTROLLER

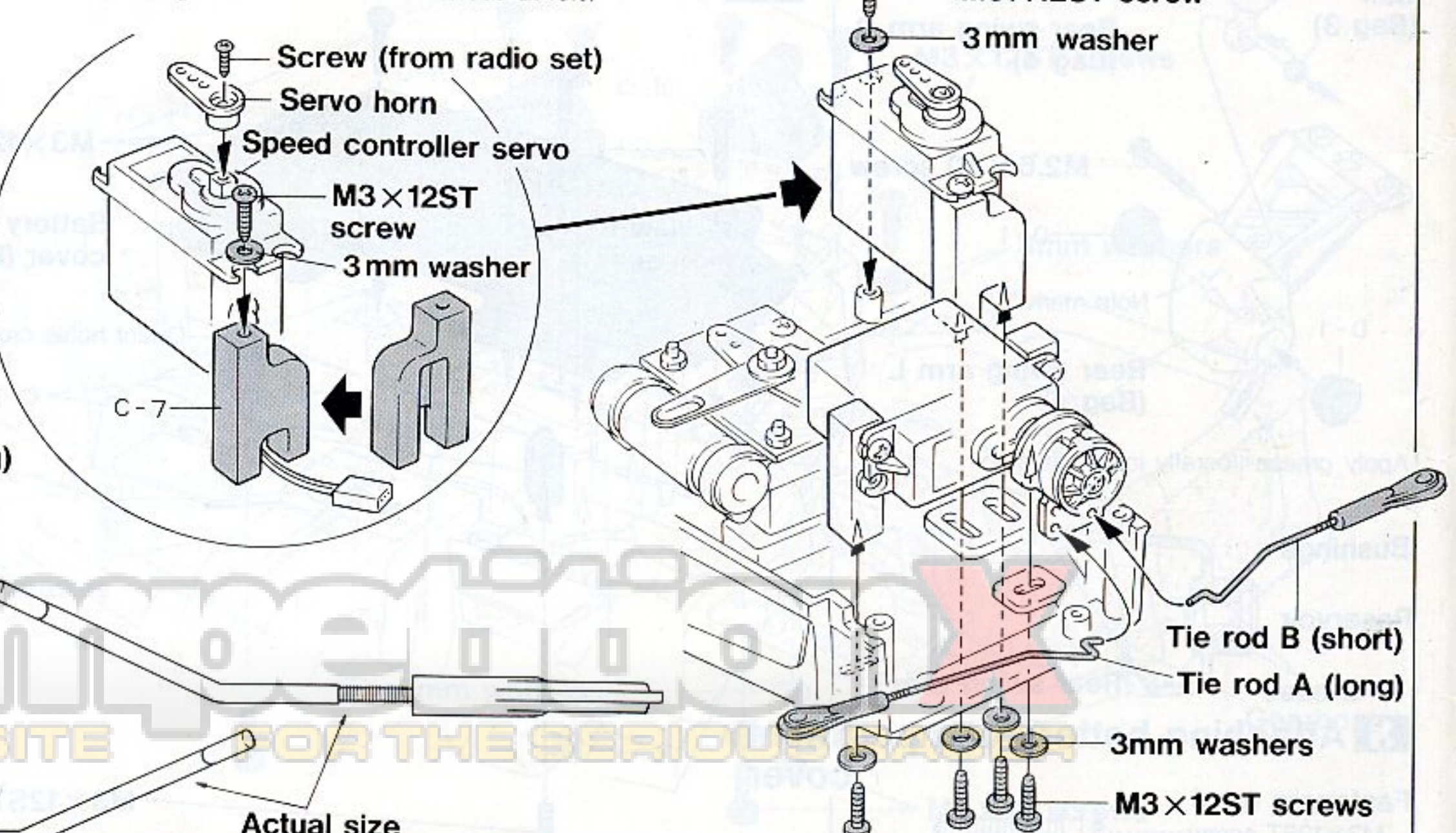
Splice speed controller leads to motor leads of the same color.

Splicing motor and speed controller leads



11 MOUNTING SERVOS

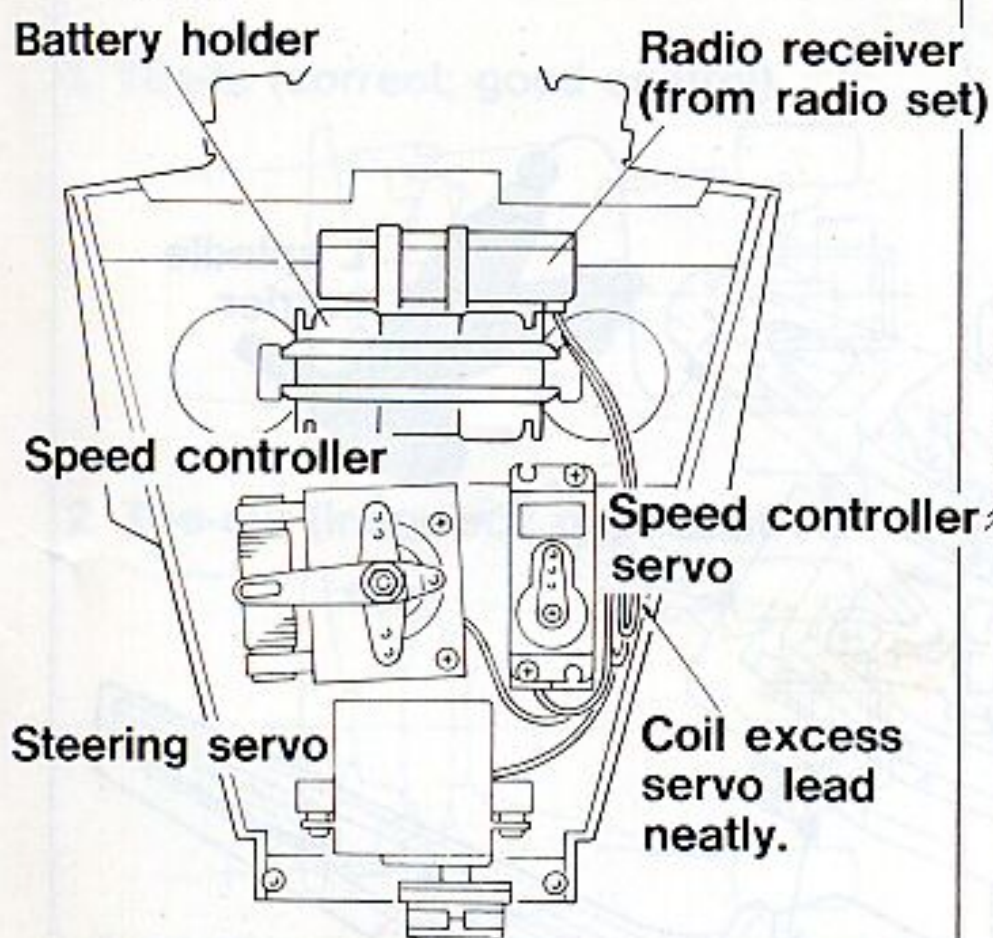
Mount steering servo horn as described at left.



12 Installing radio equipment

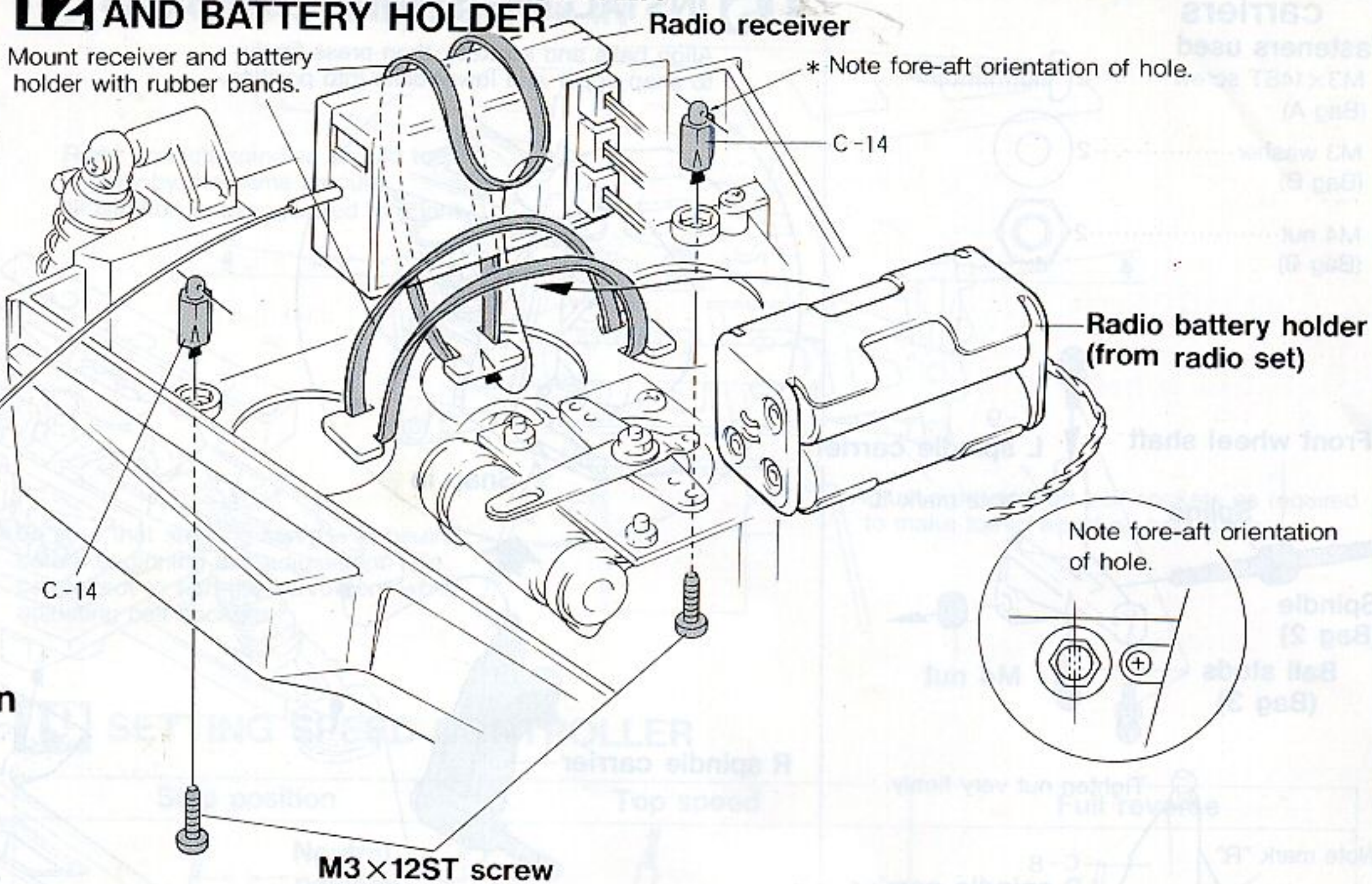
Fasteners used

M3×12ST screw.....2
(Bag A)



12 INSTALLING RADIO RECEIVER AND BATTERY HOLDER

Mount receiver and battery holder with rubber bands.



13 Assembling front suspension

Fasteners used

M2.6×5CS screw.....8

(Bag B)

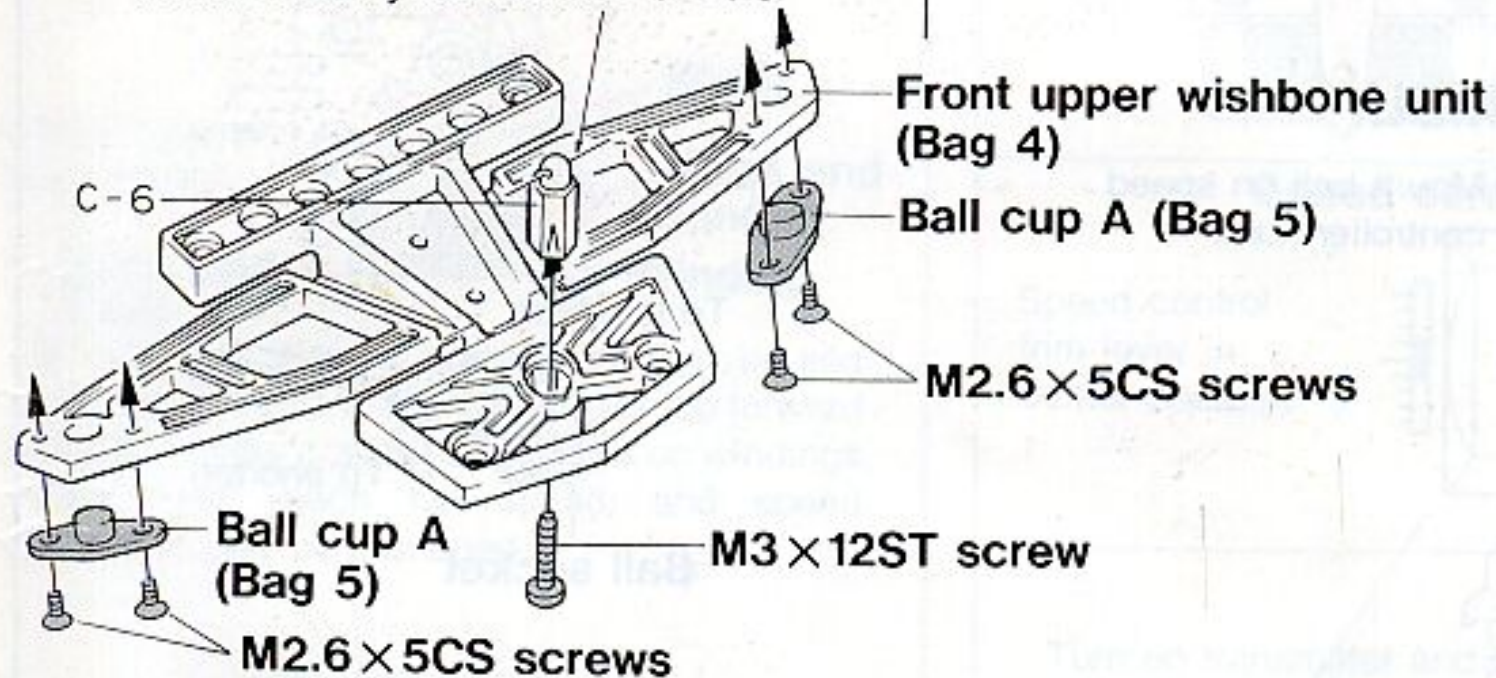
M3×12ST screw.....1

(Bag A)

M3×14ST screw.....2

(Bag A)

* Note sideways orientation of hole.



Assembling front upper wishbone unit

M2.6×5CS screws

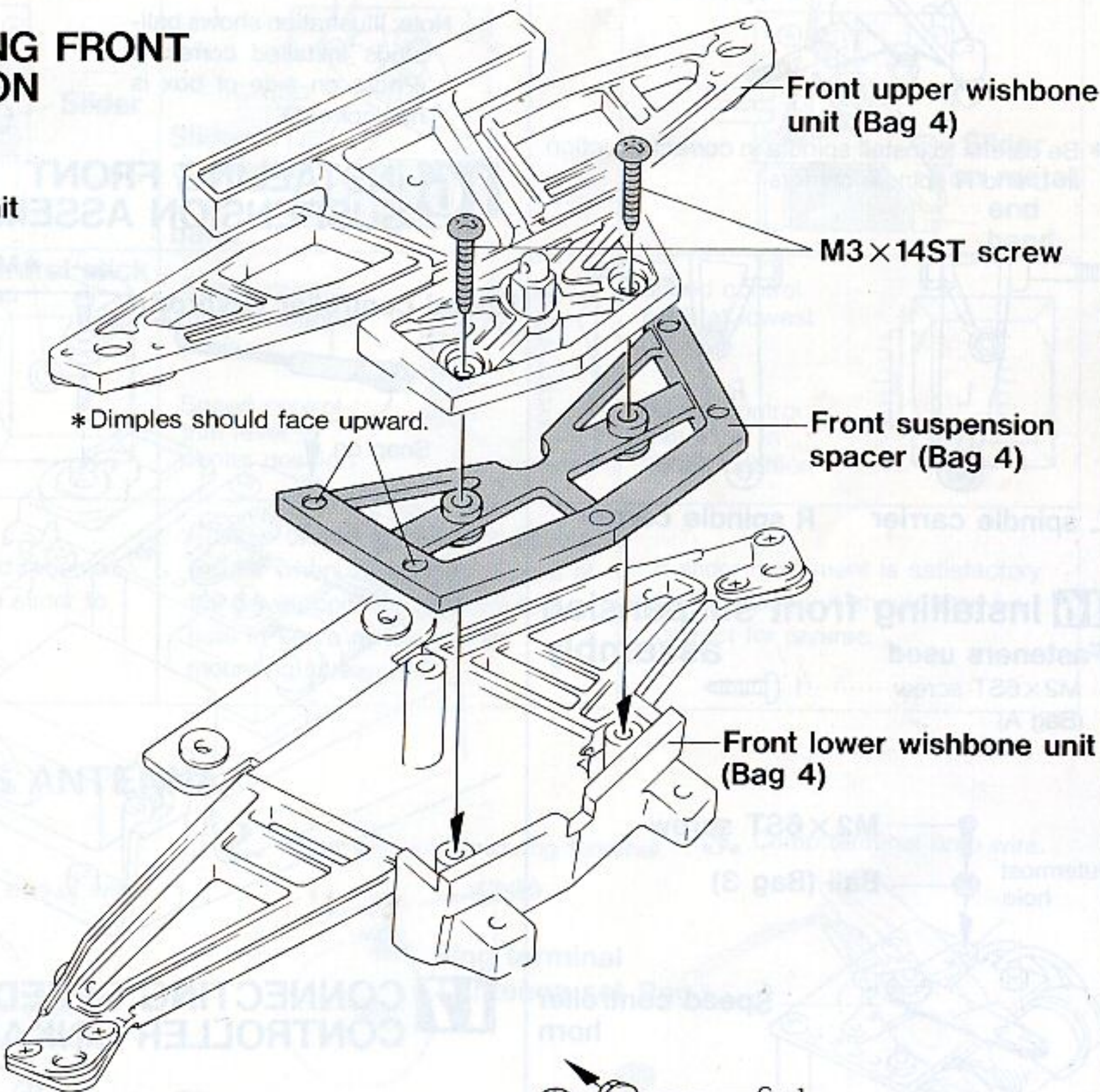
Ball cup B (Bag 5)

M2.6×5CS screws

Ball cup B (Bag 5)

Install cups before assembling front end.

13 ASSEMBLING FRONT SUSPENSION



14 Preparing front shock absorbers

Fasteners used

M3×12ST screw.....2
(Bag A)

M3×14 screw.....2
(Bag B)

M2.6×20 screw.....2
(Bag B)

5mm

Rubber bushing from step 7

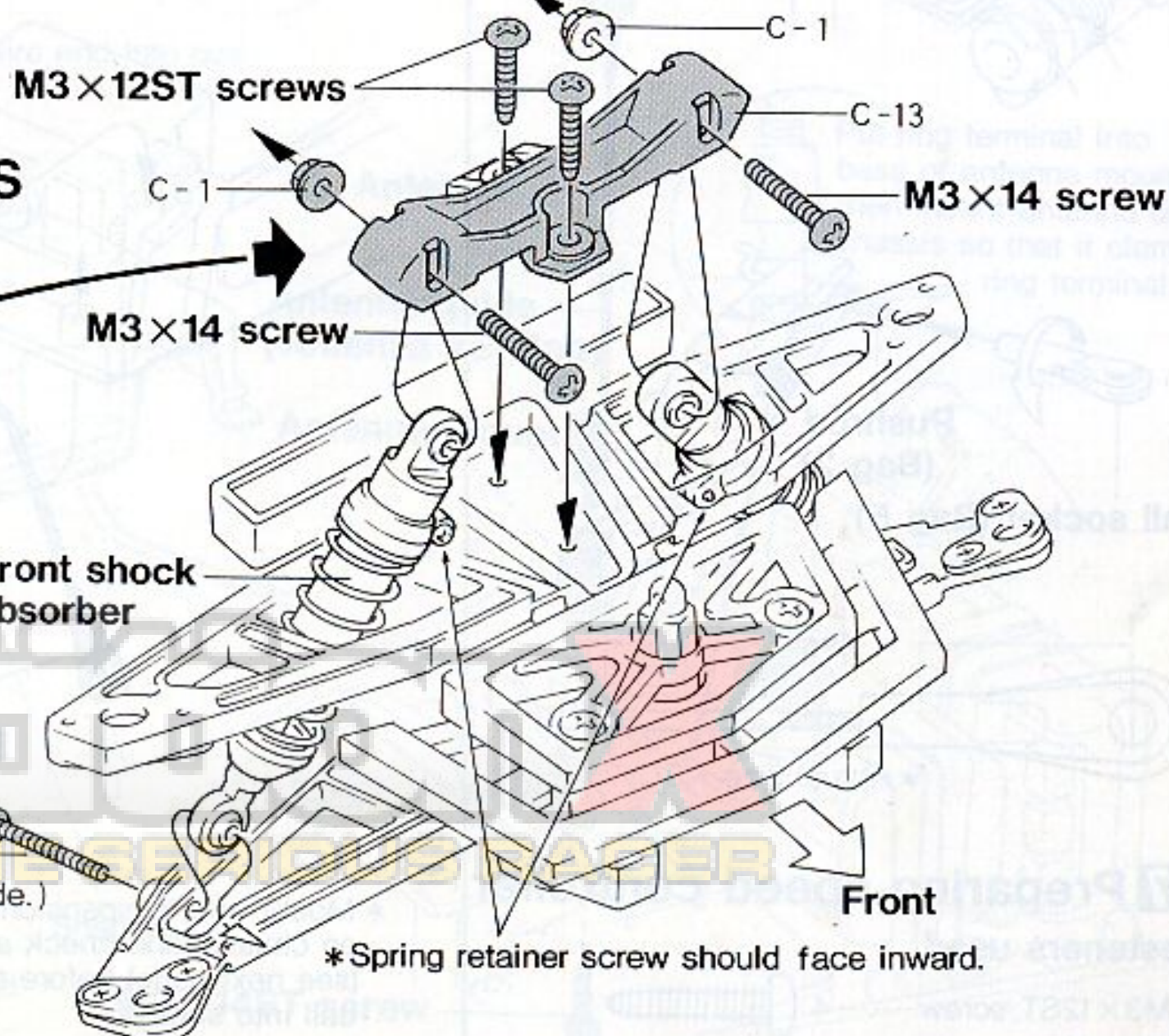
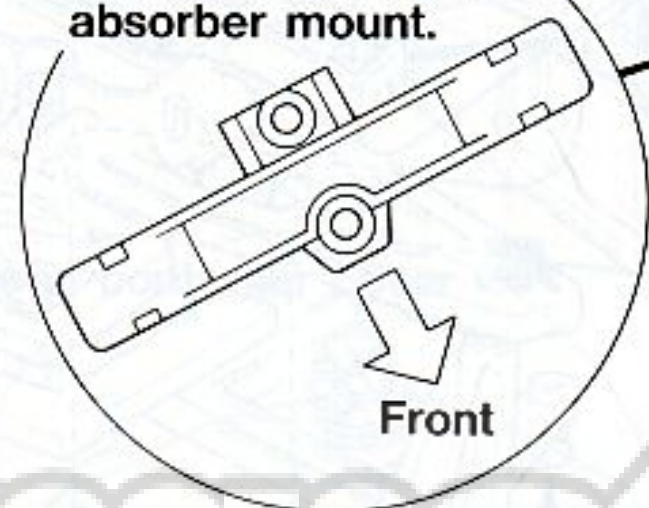
Front shock absorber (short)

Snap ball into socket.

Ball (Bag 3)

14 MOUNTING FRONT SHOCK ABSORBERS

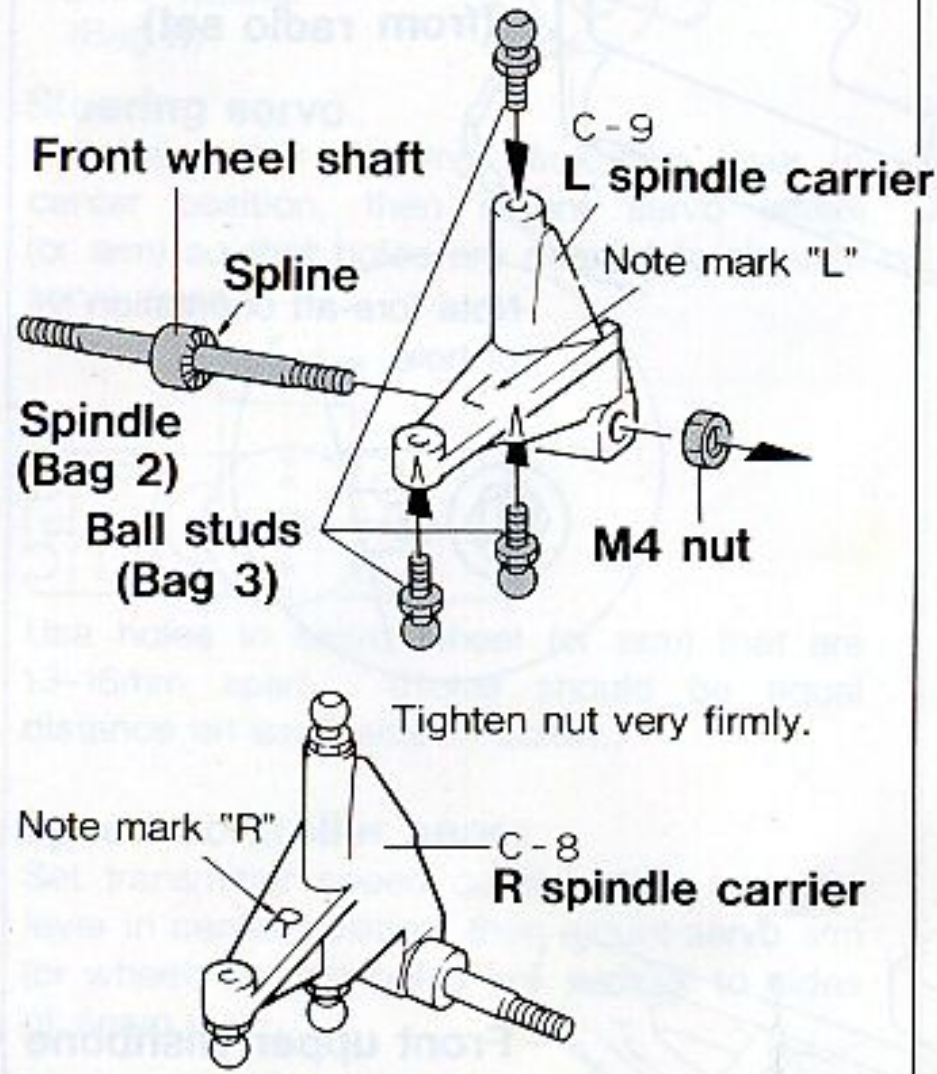
Top view of shock absorber mount.



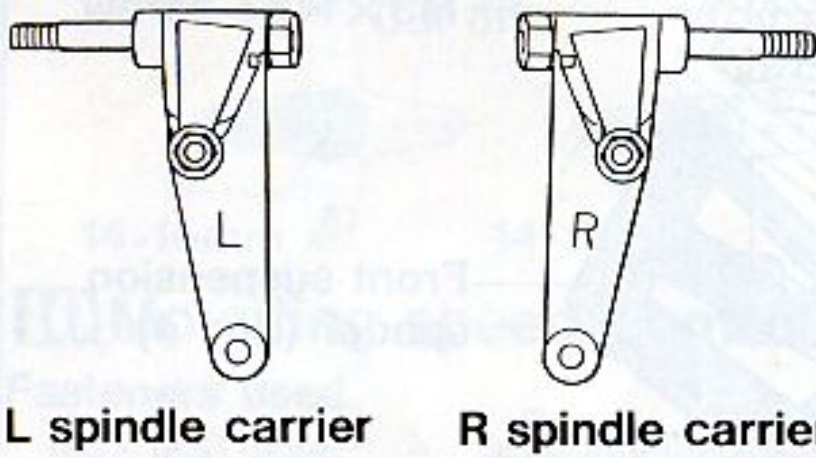
15 Assembling spindle carriers

Fasteners used

- M3×14ST screw.....2 (Bag A)
- M3 washer.....2 (Bag B)
- M4 nut.....2 (Bag B)



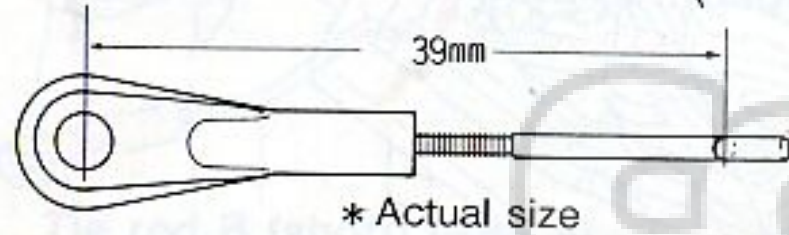
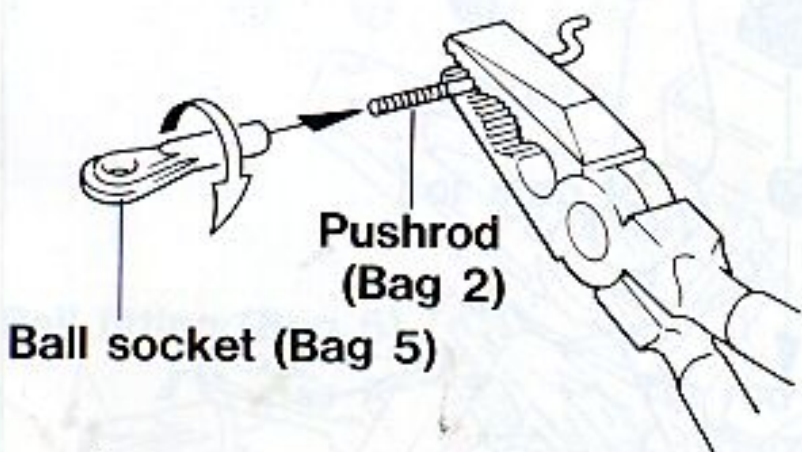
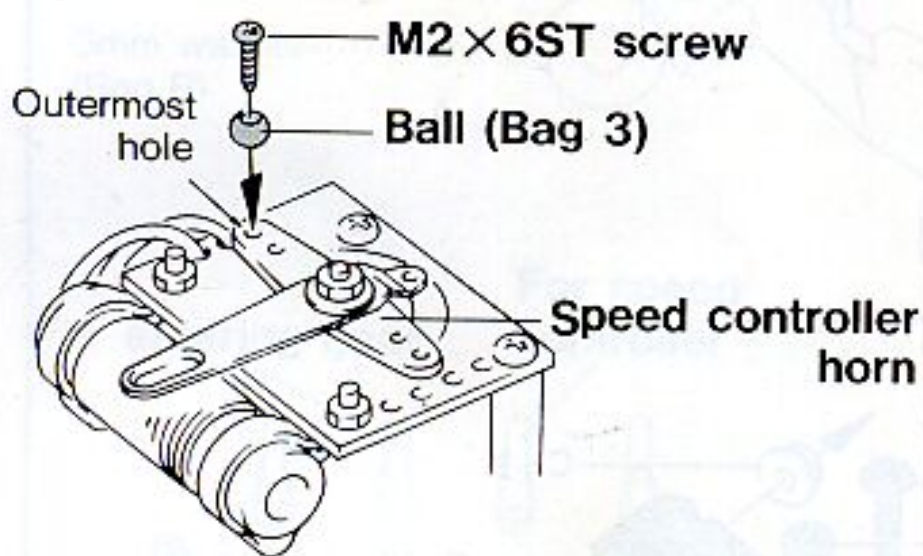
* Be careful to install spindle in correct direction in L and R spindle carriers.



16 Installing front suspension assembly

Fasteners used

- M2×6ST screw.....1 (Bag A)



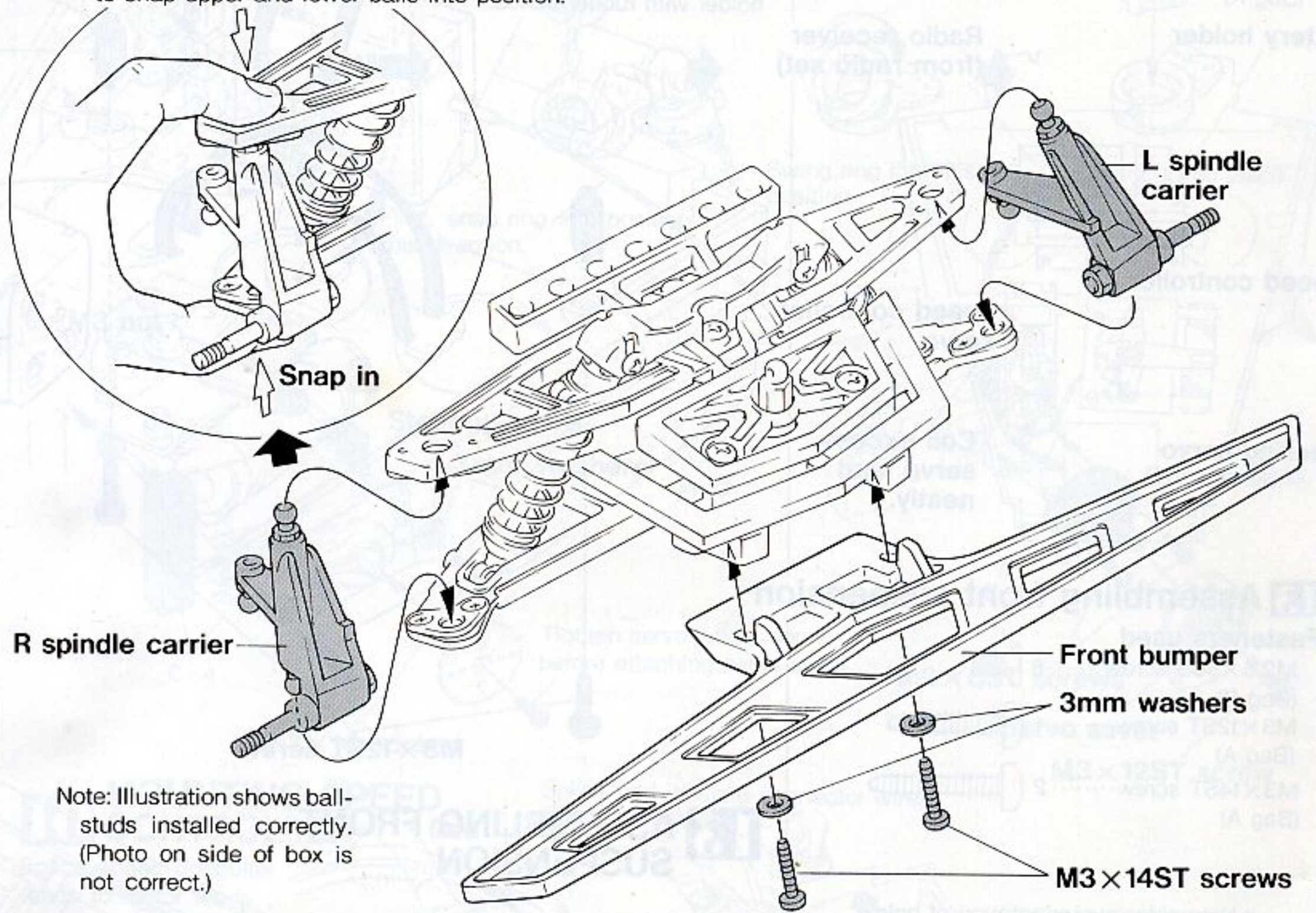
17 Preparing speed controller

Fasteners used

- M3×12ST screw.....4 (Bag A)

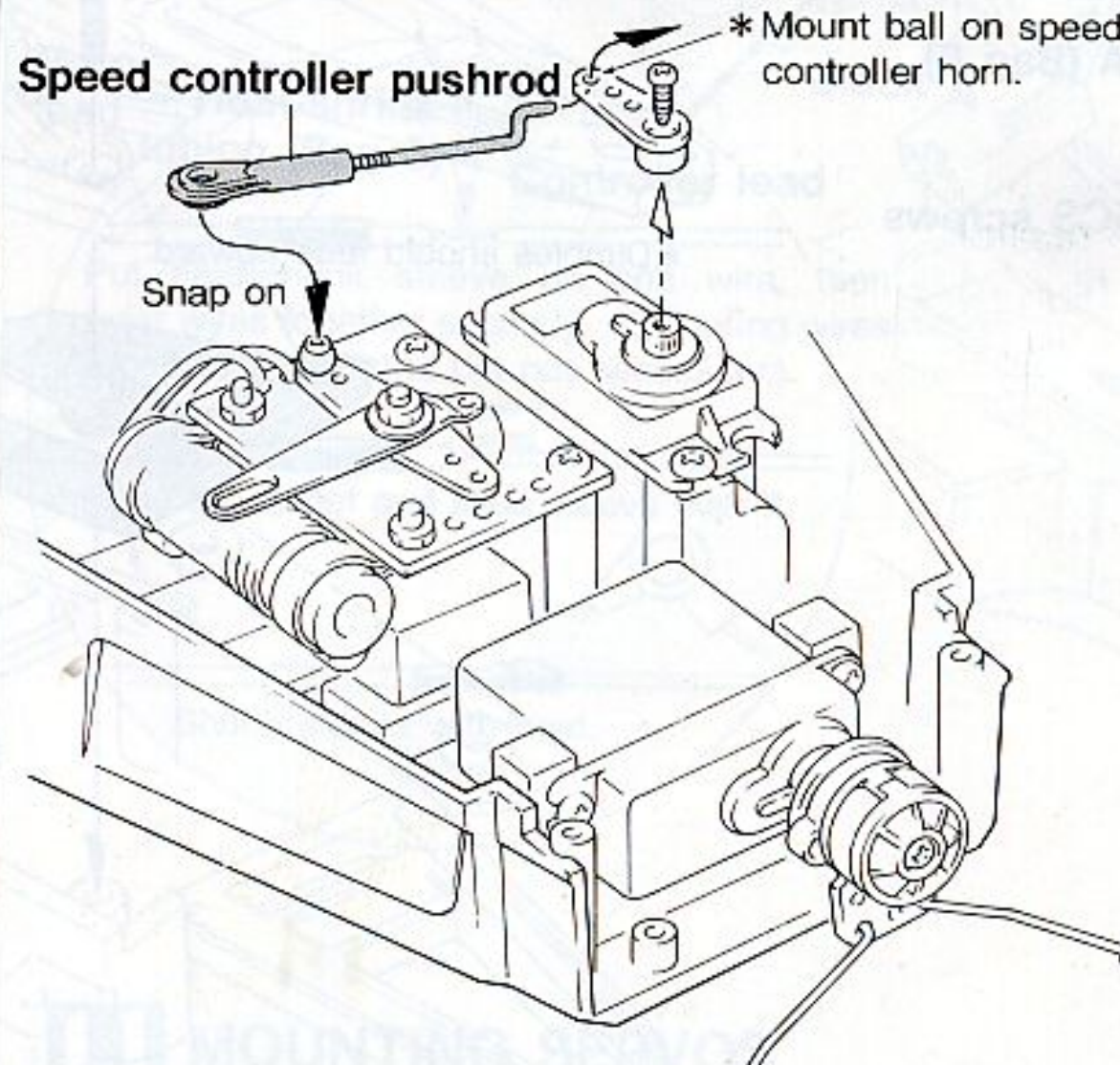
15 INSTALLING SPINDLE CARRIERS

Align balls and sockets, then press firmly to snap upper and lower balls into position.

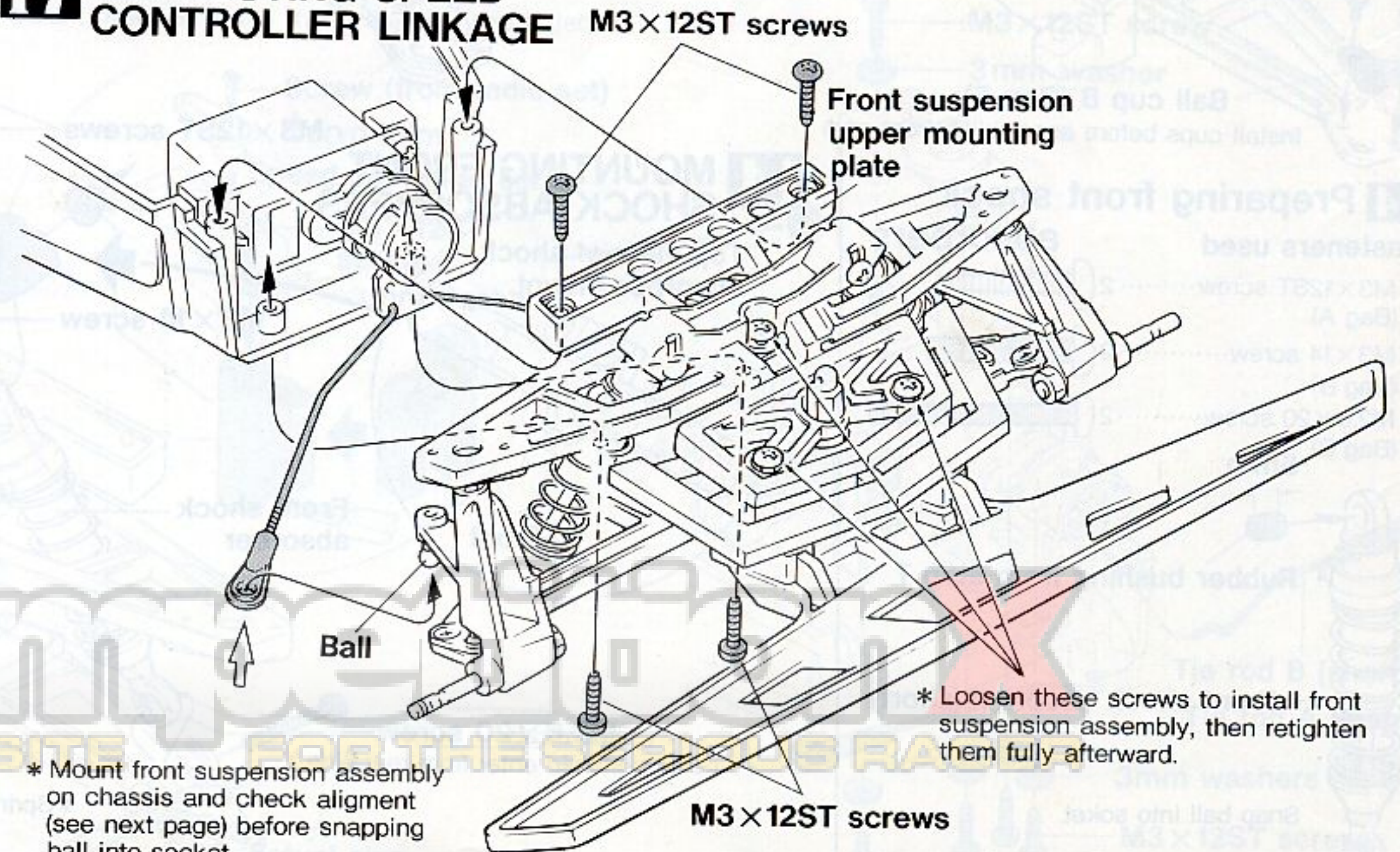


Note: Illustration shows ball-studs installed correctly. (Photo on side of box is not correct.)

16 INSTALLING FRONT SUSPENSION ASSEMBLY



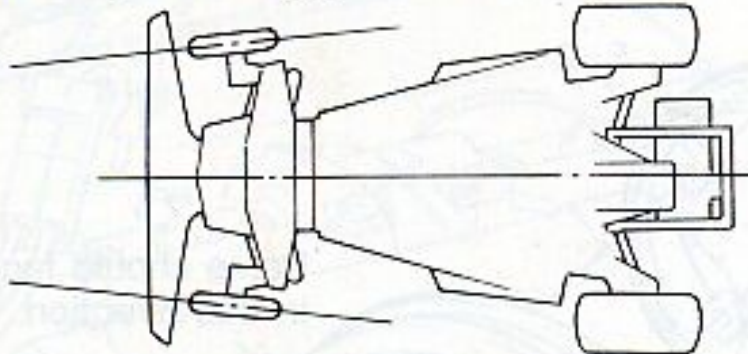
17 CONNECTING SPEED CONTROLLER LINKAGE



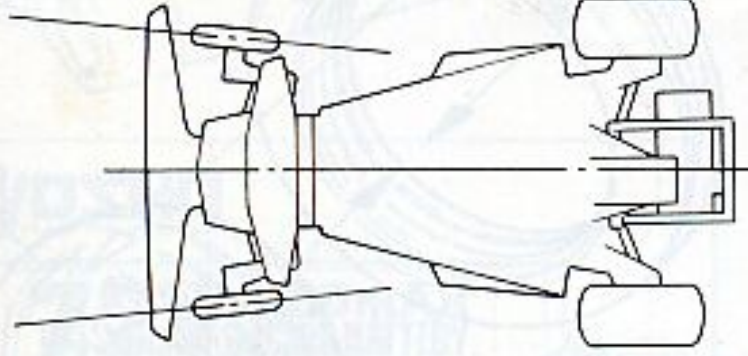
* Mount front suspension assembly on chassis and check alignment (see next page) before snapping ball into socket.

18 Notes on steering adjustments

1. Toe-in (correct; good control)



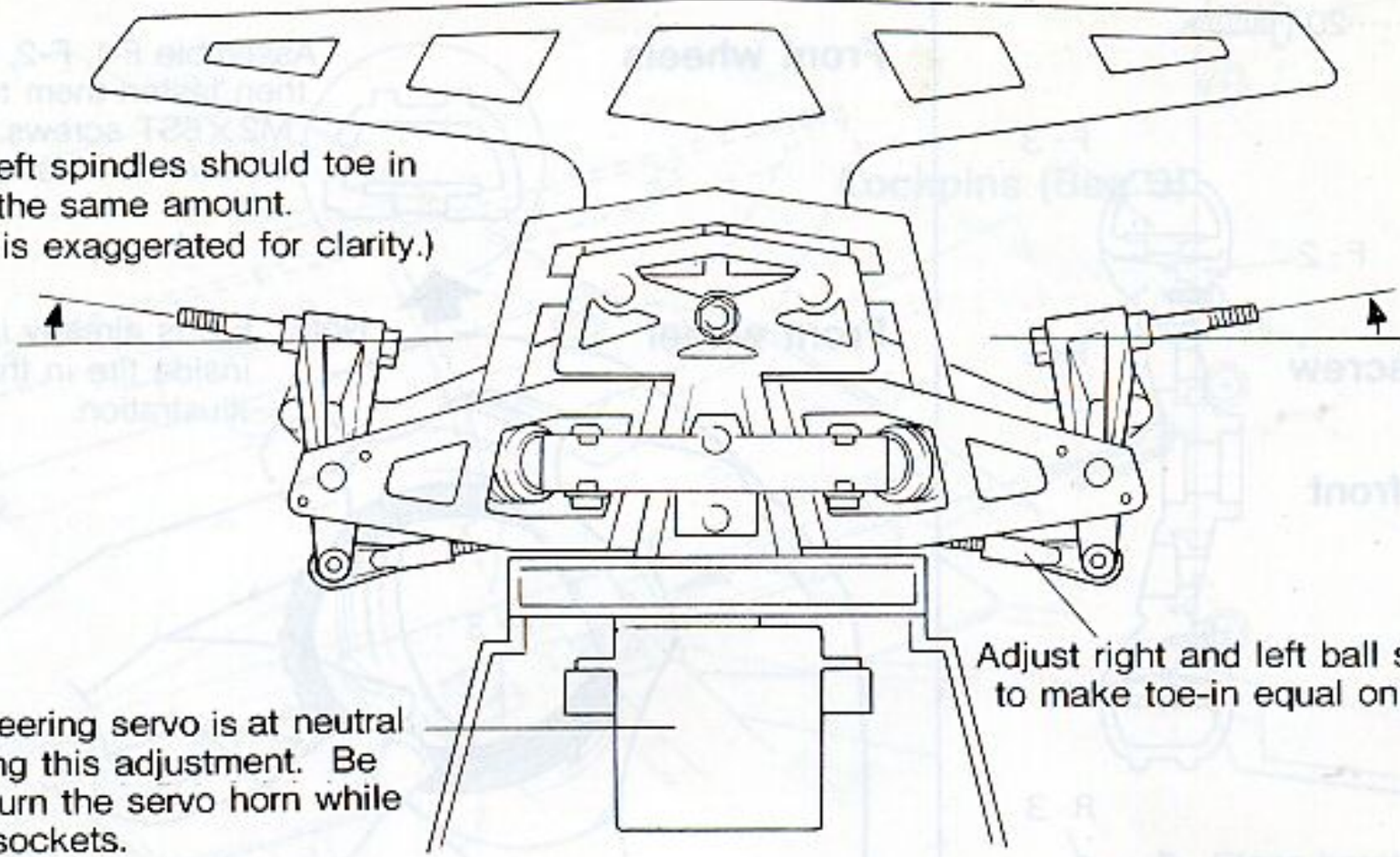
2. Toe-out (incorrect; poor control)



A small amount of toe-in is needed for directional stability.

18 SETTING STEERING TOE-IN

Right and left spindles should toe in slightly by the same amount. (Illustration is exaggerated for clarity.)



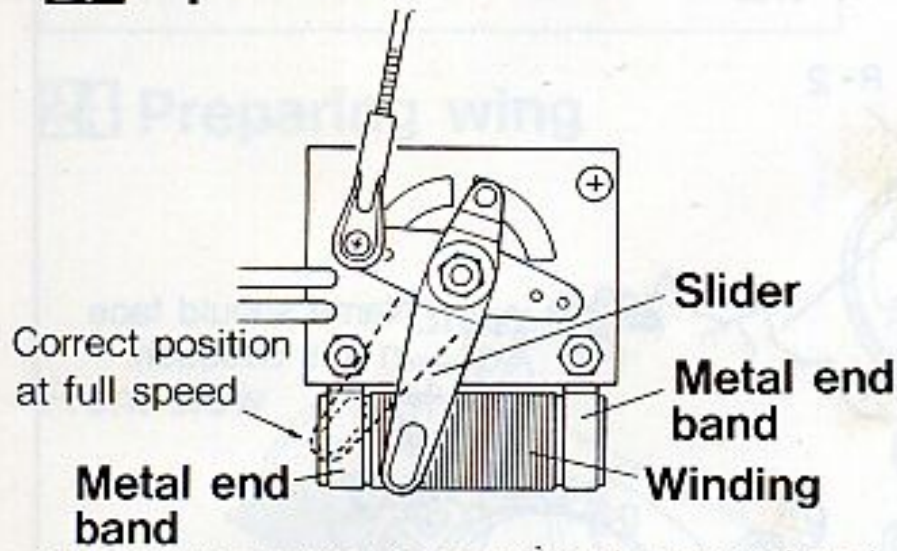
Adjust right and left ball sockets as required to make toe-in equal on both sides.

*Be sure that steering servo is at neutral before beginning this adjustment. Be careful not to turn the servo horn while adjusting ball sockets.

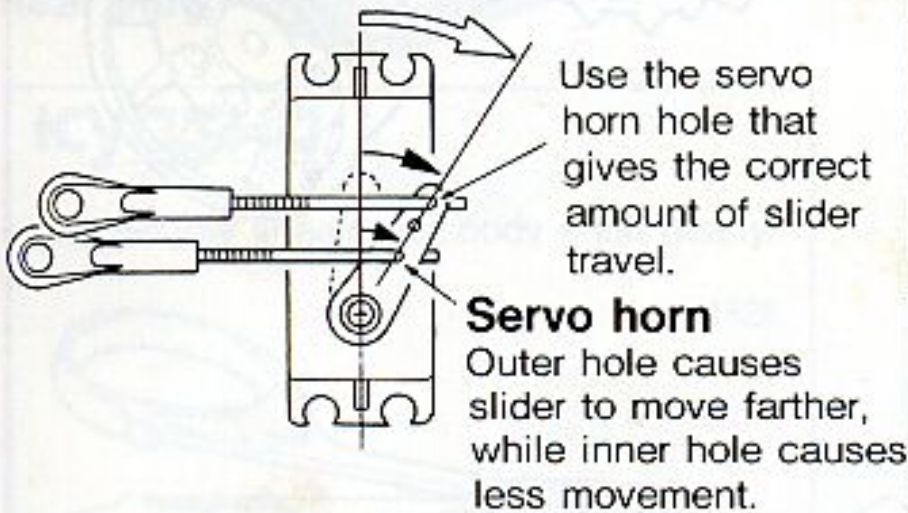
19 SETTING SPEED CONTROLLER

Stop position	Top speed	Full reverse
<p>Neutral position</p> <p>Slider</p>	<p>Slider on metal end band</p>	<p>Slider on metal end band</p>
<p>Speed control trim lever in center position</p>	<p>Speed control stick at highest position</p> <p>Speed control trim lever in center position</p>	<p>Speed control stick at lowest position</p> <p>Speed control trim lever in center position</p>
<p>Turn on transmitter and receiver, then set stick and trim slider to center position.</p>	<p>If slider of speed controller travels too far when transmitter stick is at full travel, connect pushrod to a hole in servo arm closer to mounting screw.</p>	<p>If slider movement is satisfactory for top speed, it should also be correct for reverse.</p>

19 Speed controller



Be sure that slider is positioned on metal end band when servo is at full travel for top forward speed. If slider constantly remains on windings, car cannot reach full speed, and speed controller may be damaged.

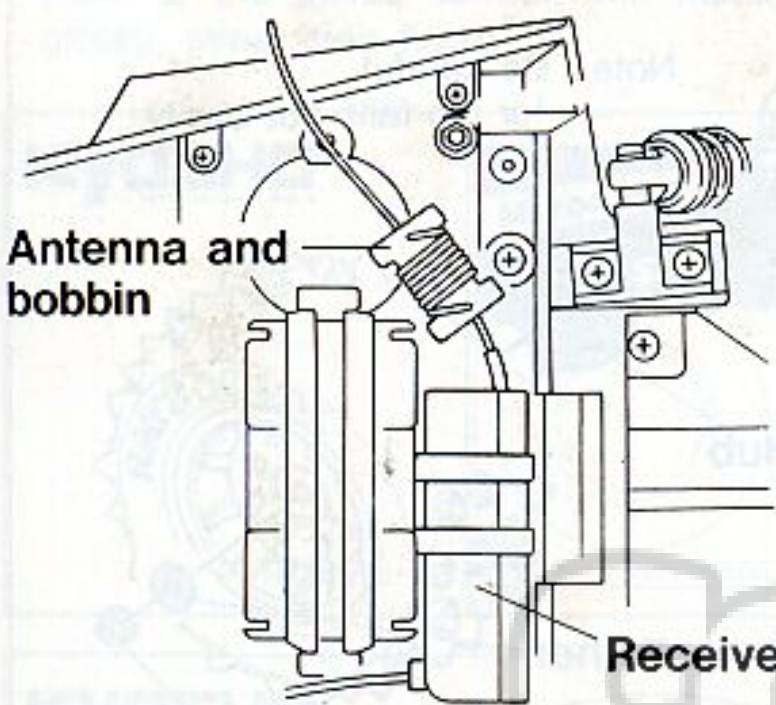


20 Installing antenna

Fasteners used

M3X14ST screw..... 1

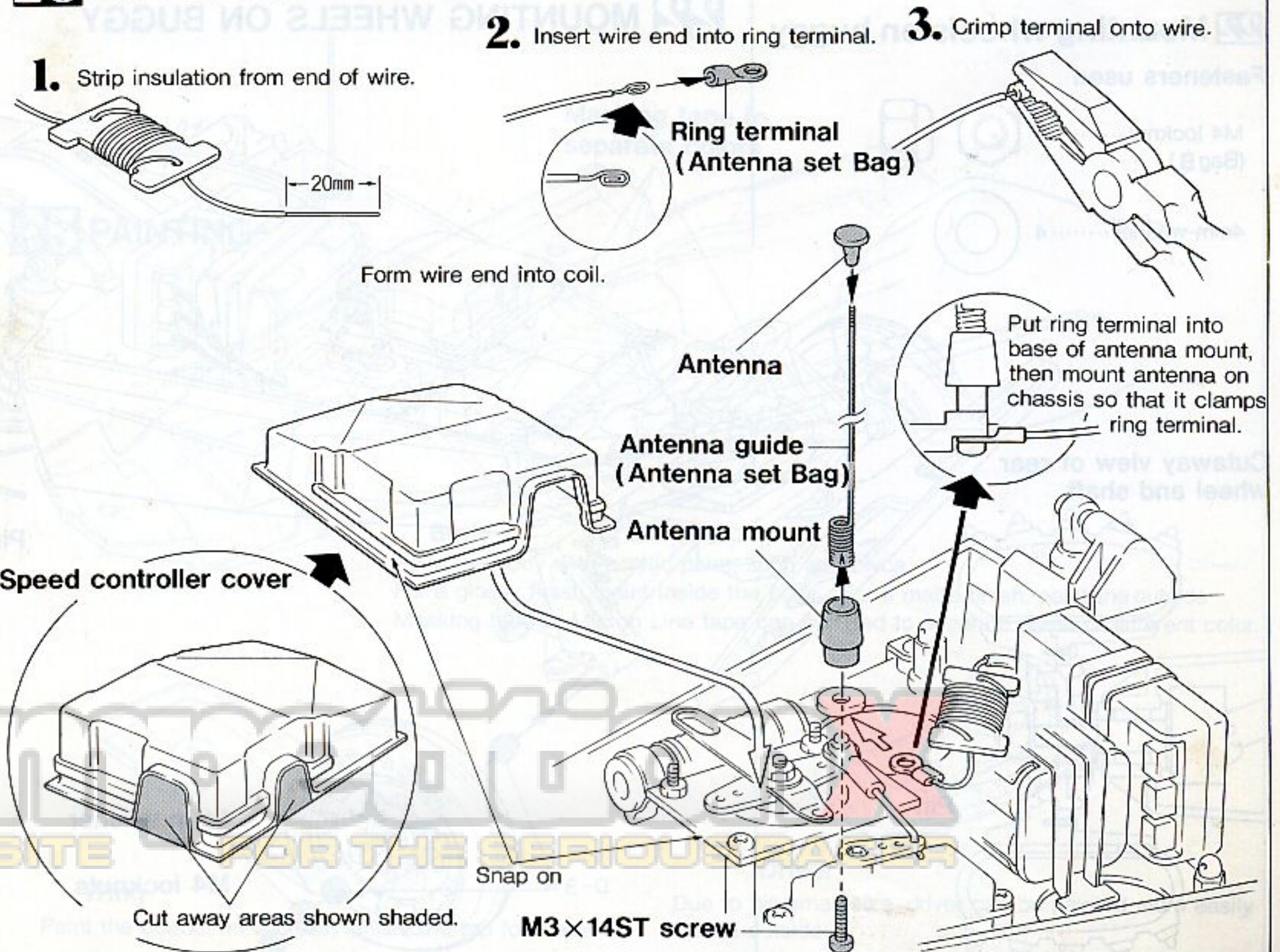
View of completed antenna installation



Wind antenna on bobbin.



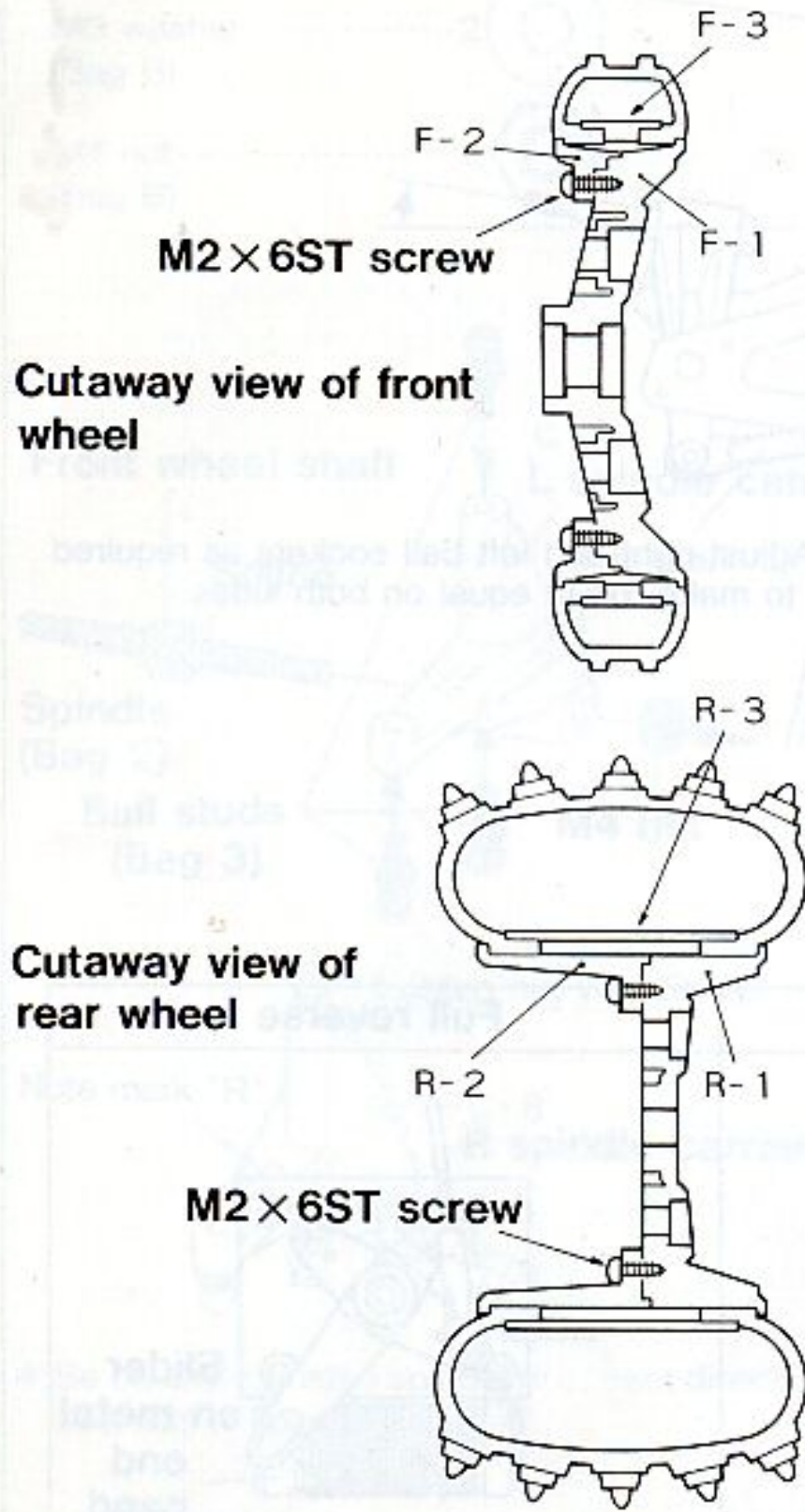
20 INSTALLING ANTENNA



21 Assembling wheels

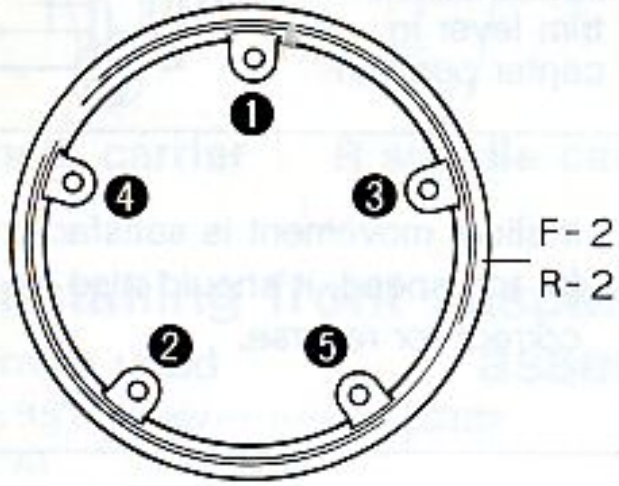
Fasteners used

M2 × 6ST screw.....20
(Bag A)



Assembling wheels

Tighten wheel assembly screws a little at a time in the order shown below. Do not tighten one screw completely while the others are loose.

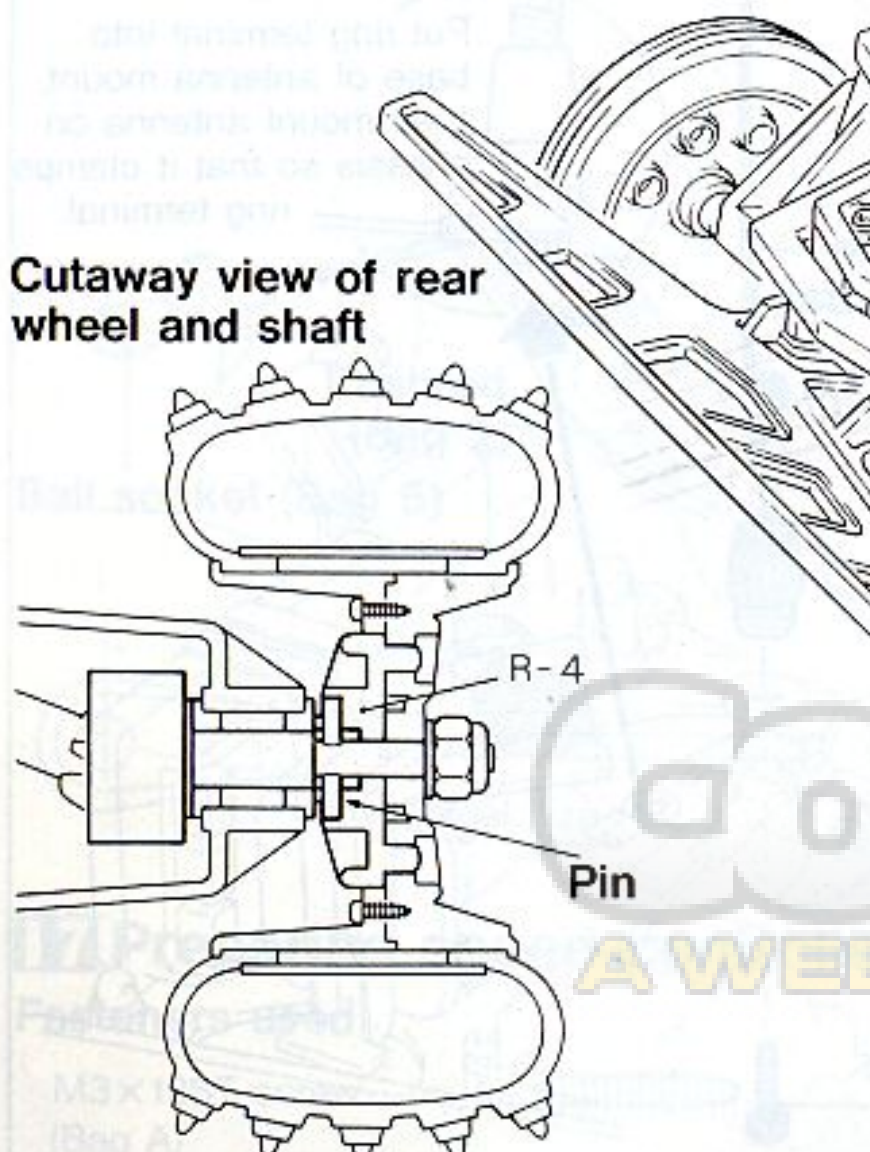


22 Mounting wheels on buggy

Fasteners used

M4 locknut.....4
(Bag B)

4mm washer.....4

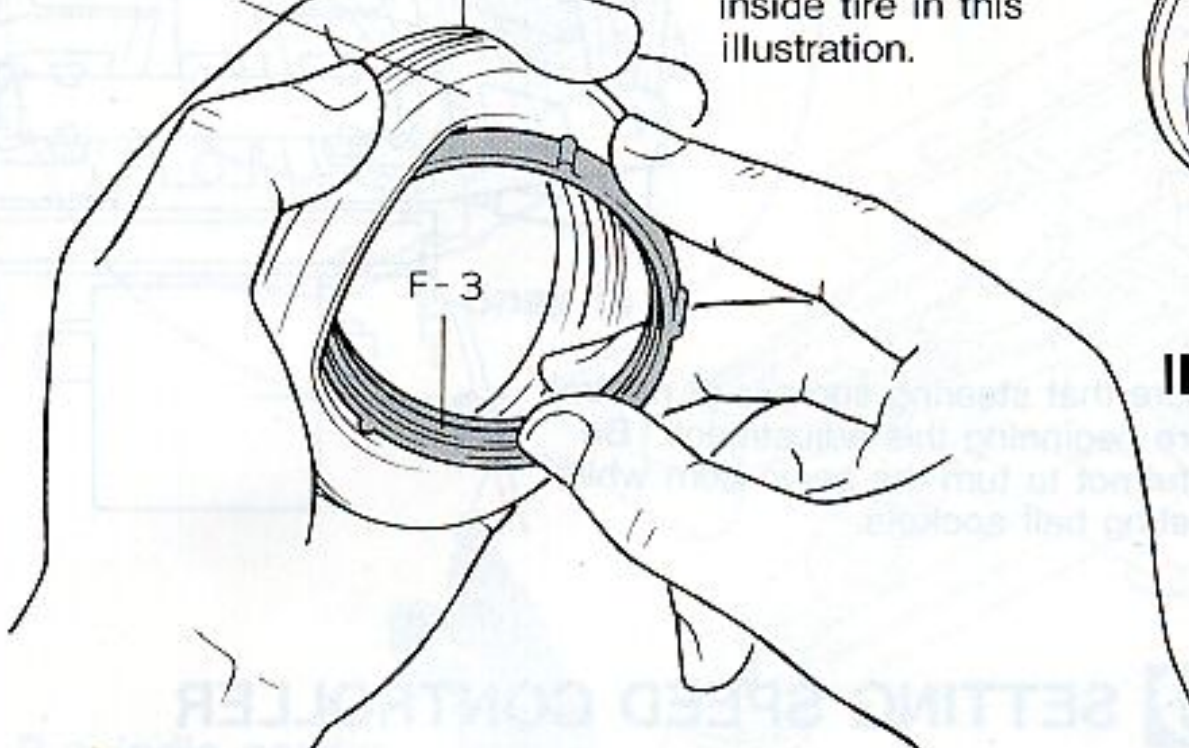


21 MOUNTING TIRES ON WHEELS

Front wheels

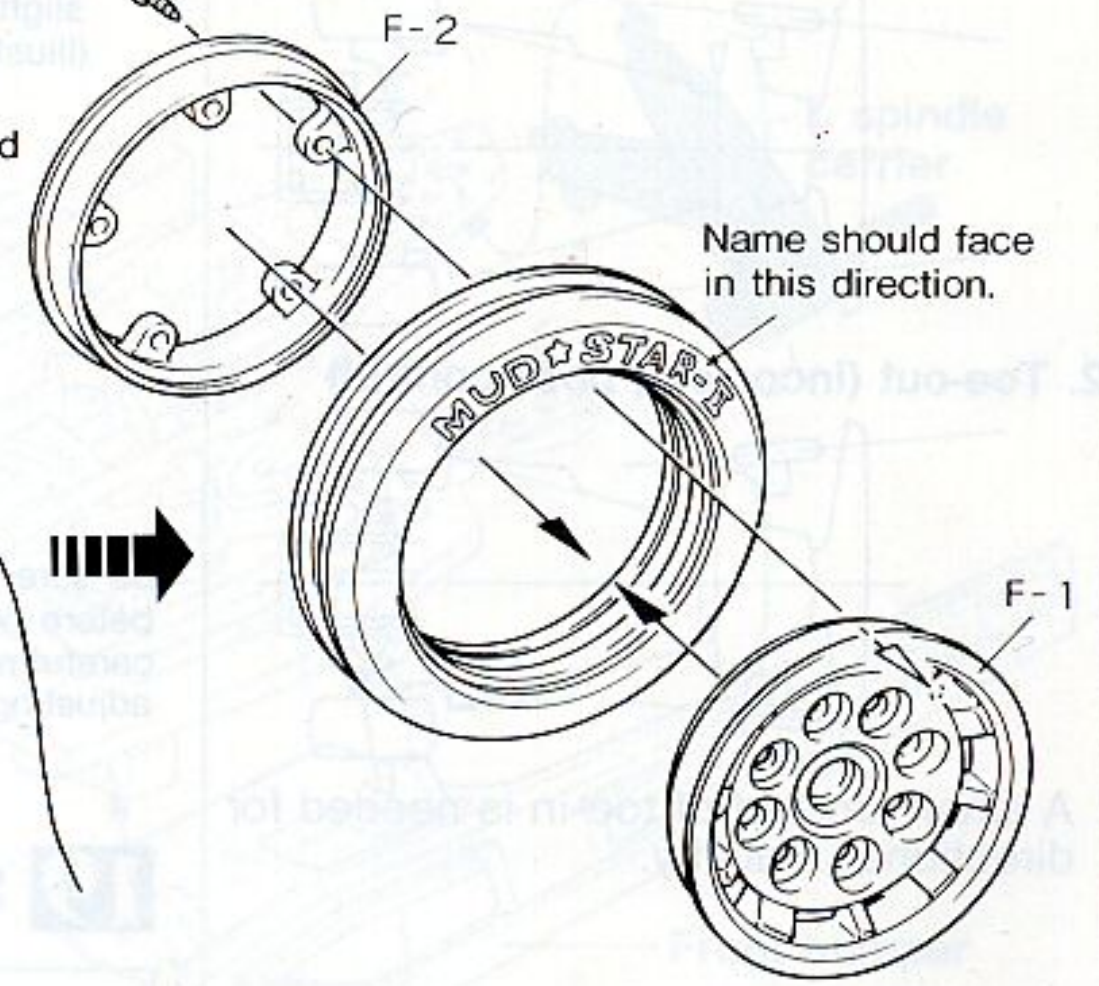
Assemble F-1, F-2, and the tire, then fasten them together with M2 × 6ST screws. Tighten the screws as illustrated to lower left.

Front wheel



Install ring F-3 inside tire by rolling tire back to permit entry. (Do not distort ring.)

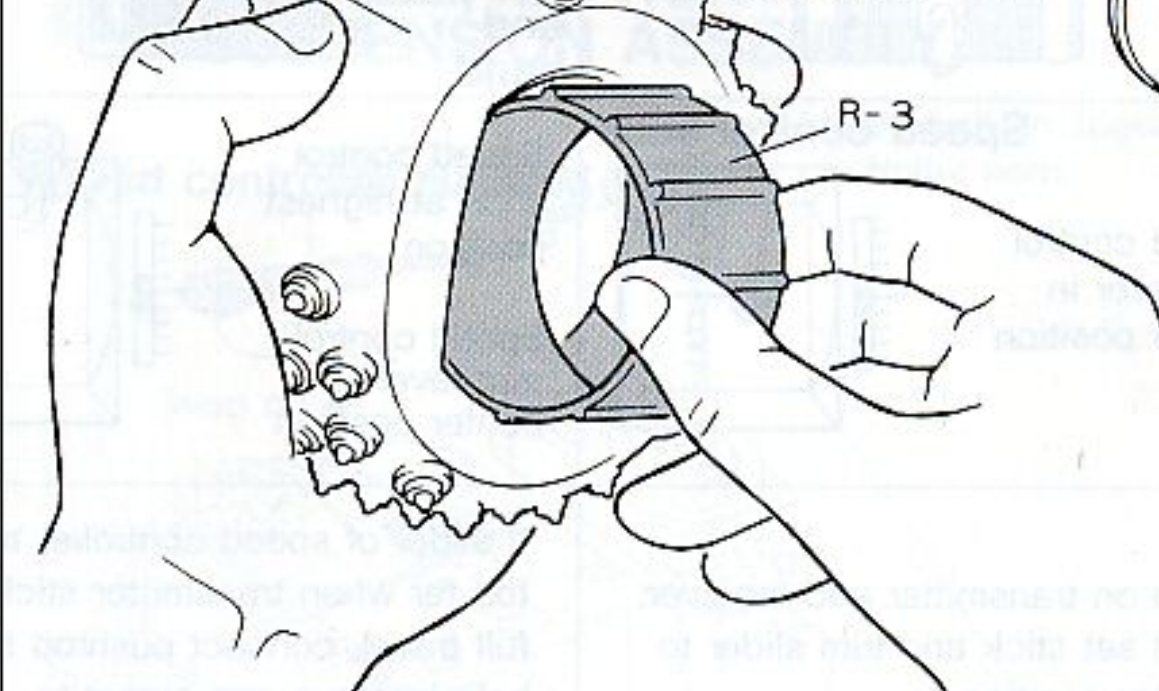
M2 × 6ST screw



Rear wheels

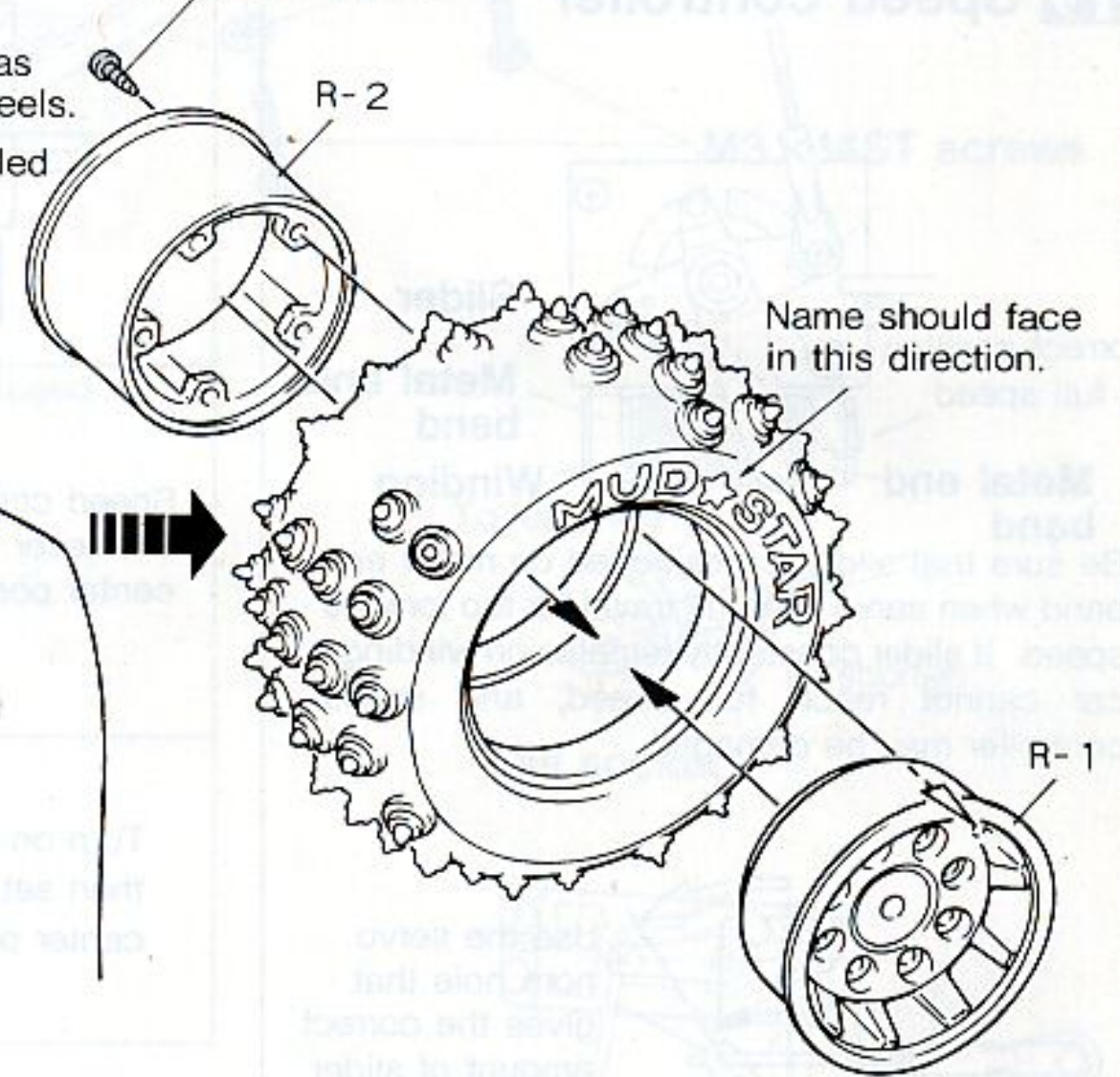
Assemble R-1, R-2, and the tire as described above for the front wheels.

Note: R-3 is already installed inside tire in this illustration.

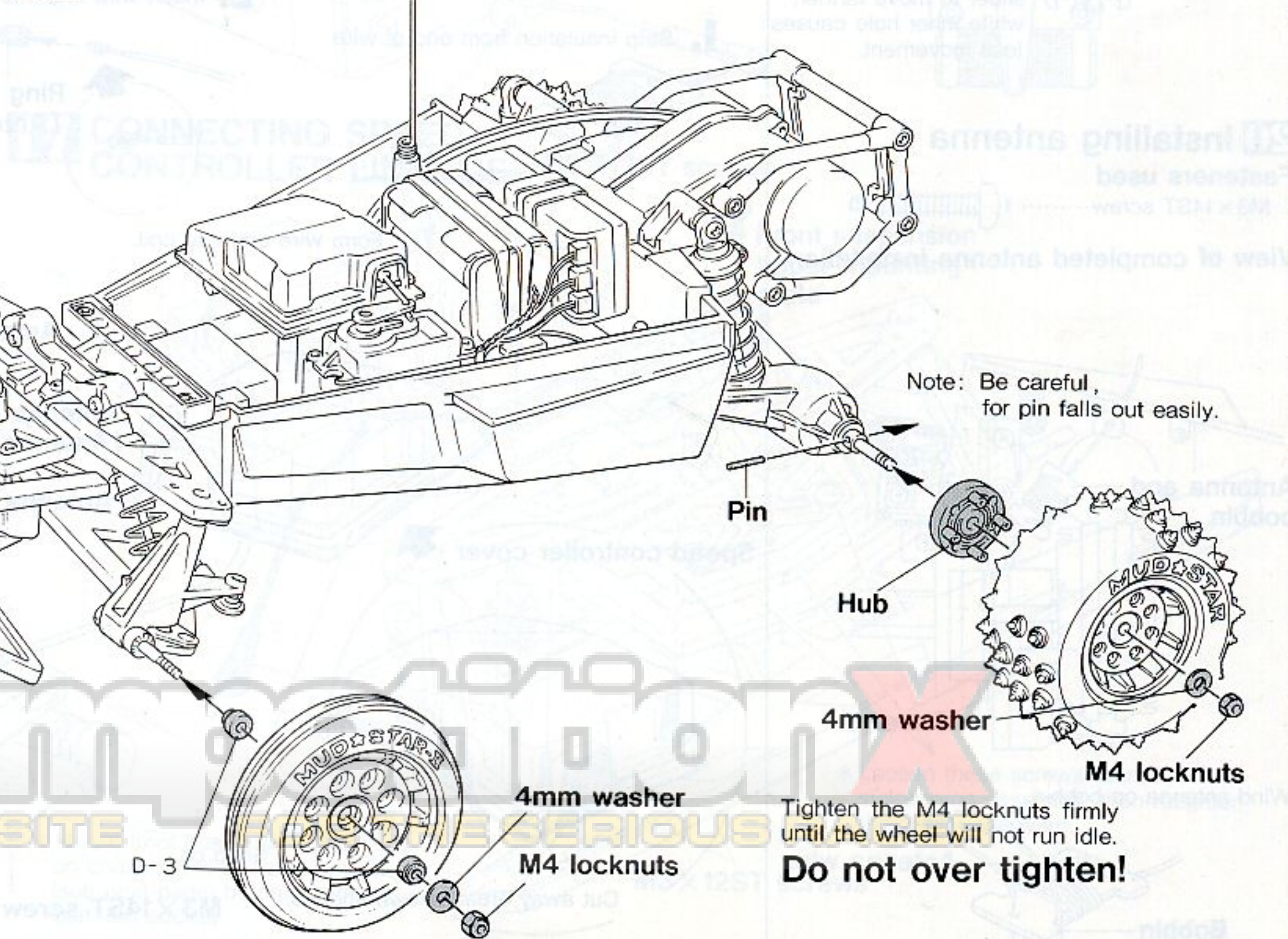


Install ring R-3 inside tire as described above for front tire.

M2 × 6ST screw

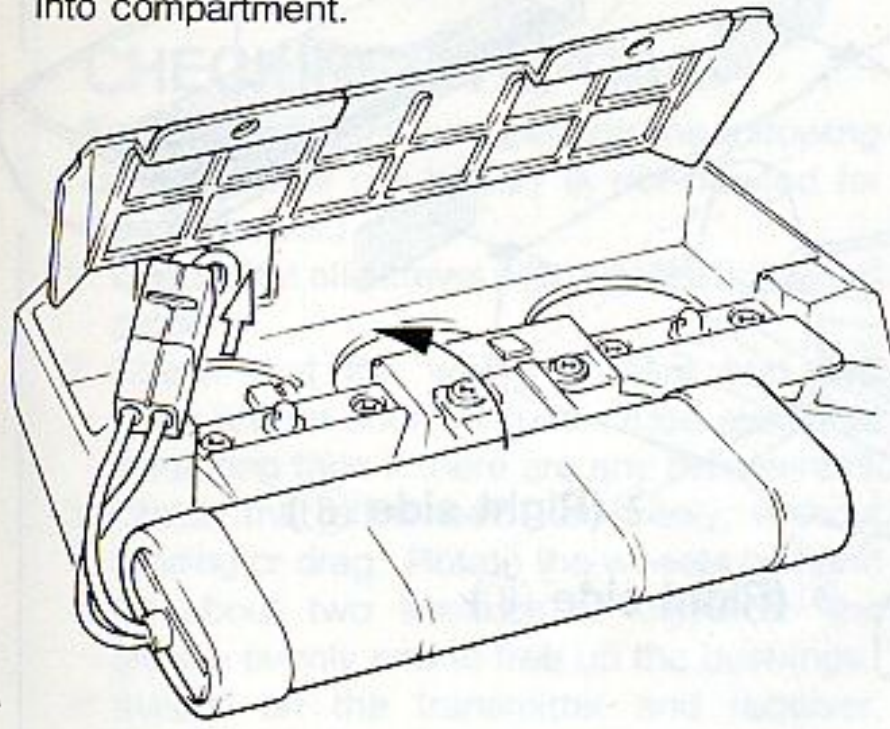


22 MOUNTING WHEELS ON BUGGY



23 Installing battery pack

Join connector halves, then fit battery into compartment.



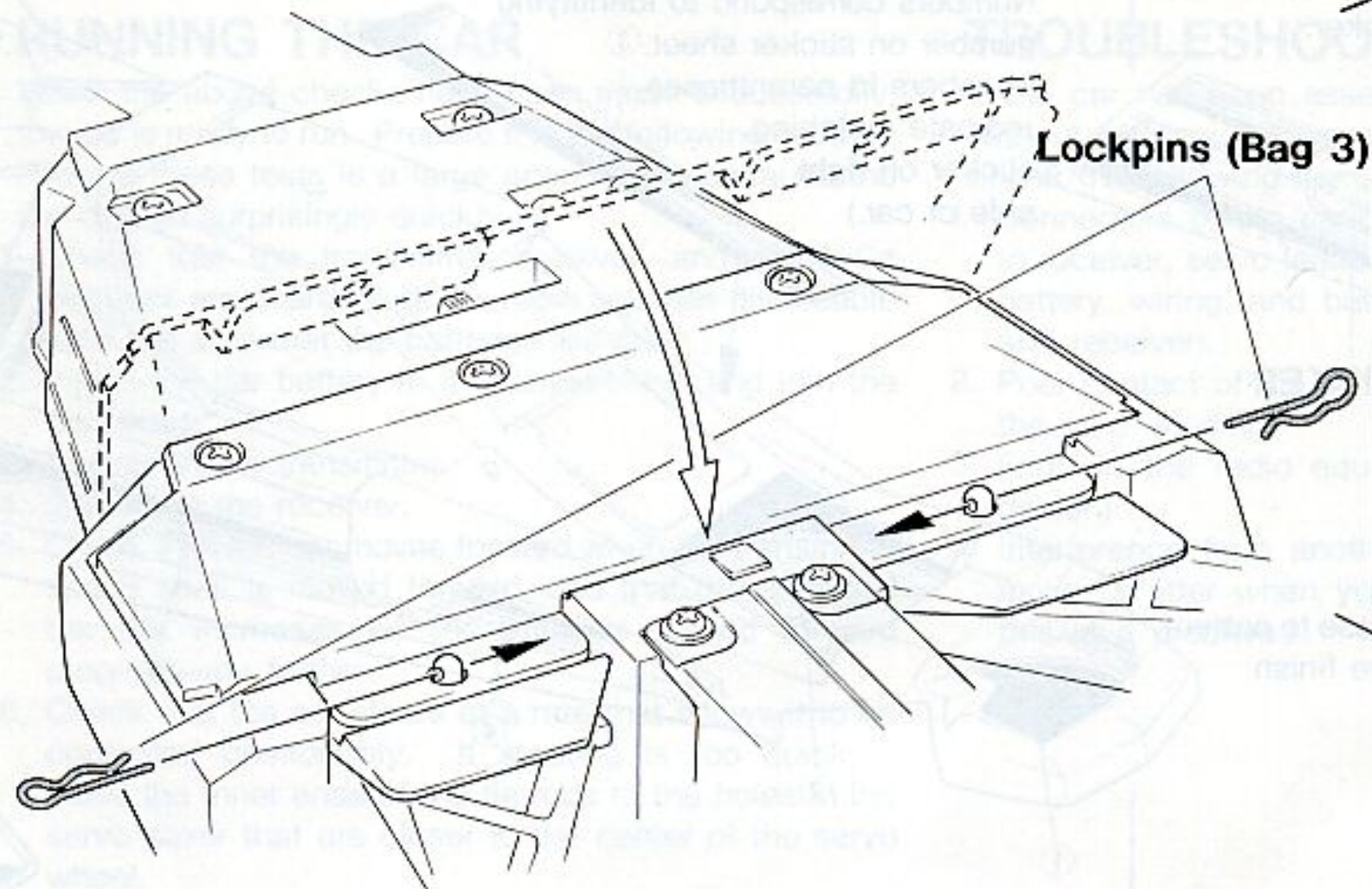
KYOSHO
THE FIRST RACE CONTROL MODEL



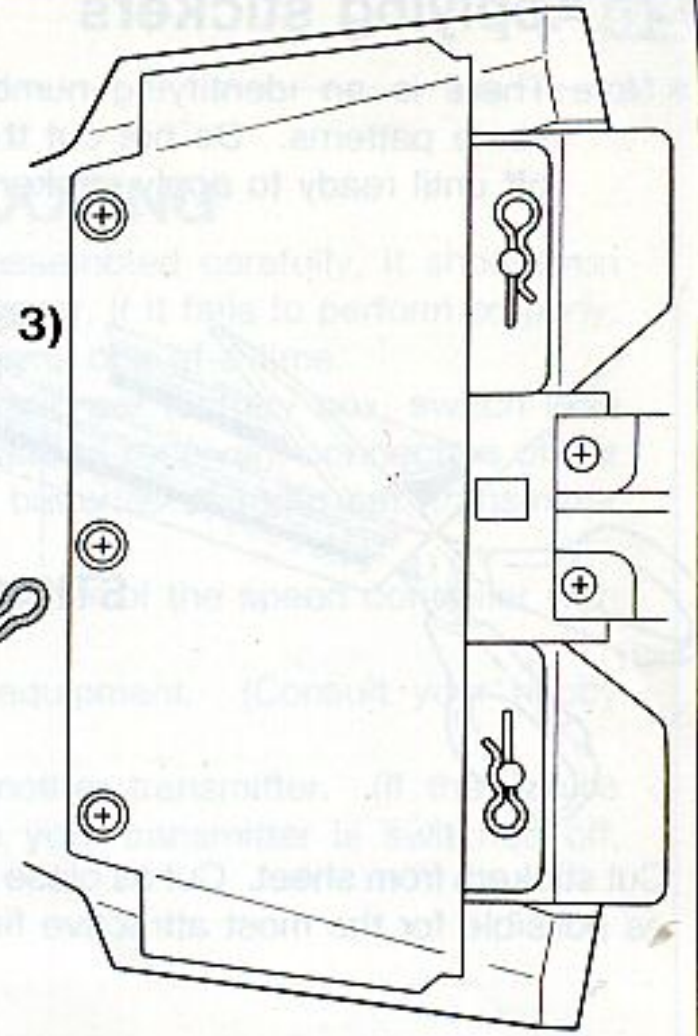
7.2-1200mAh NiCd racing battery pack
(obtained separately; not included in kit)

No.2218

23 INSTALLING BATTERY PACK



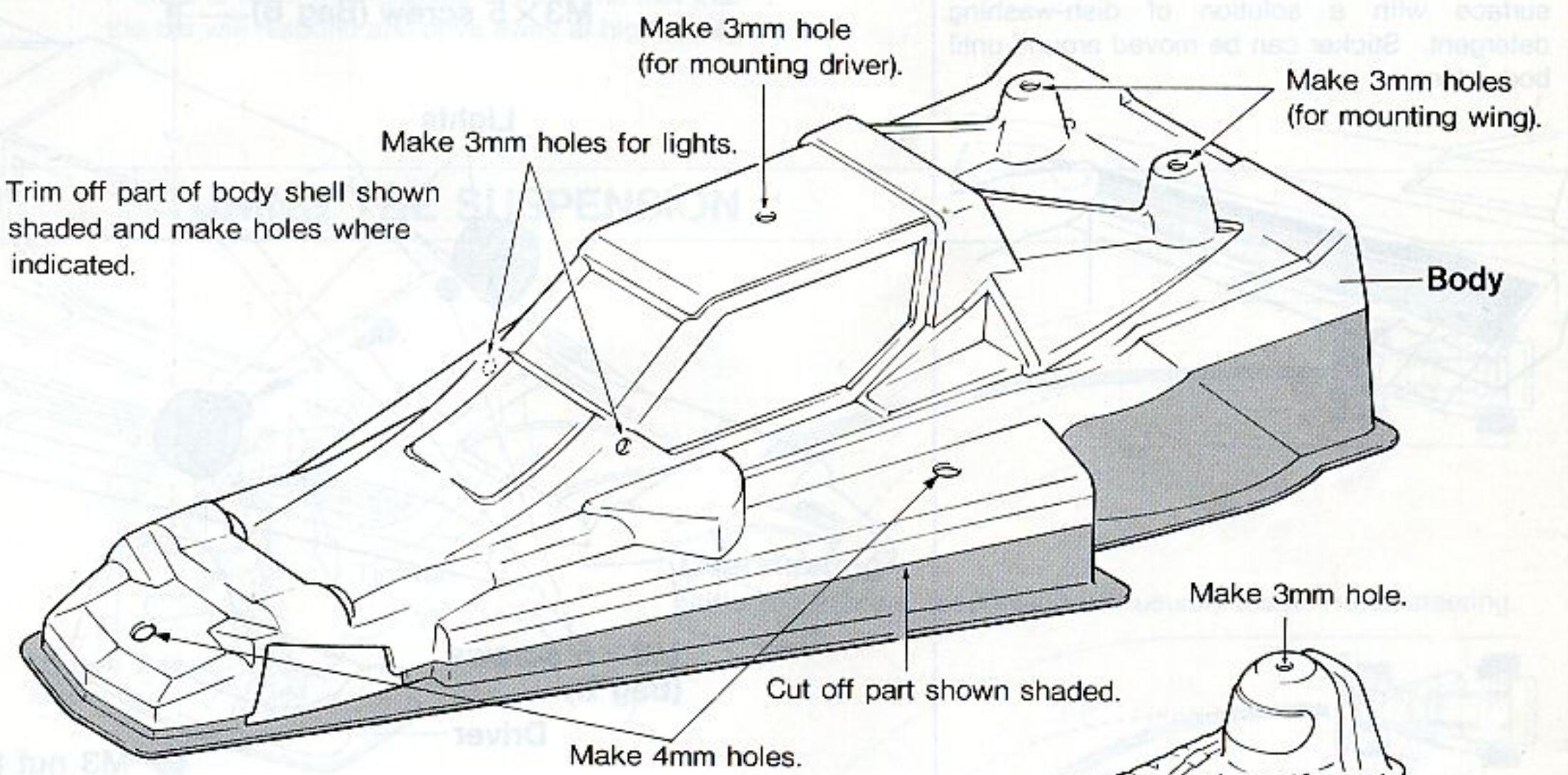
Lockpins (Bag 3)



Close hatch and insert lockpins to hold it closed.

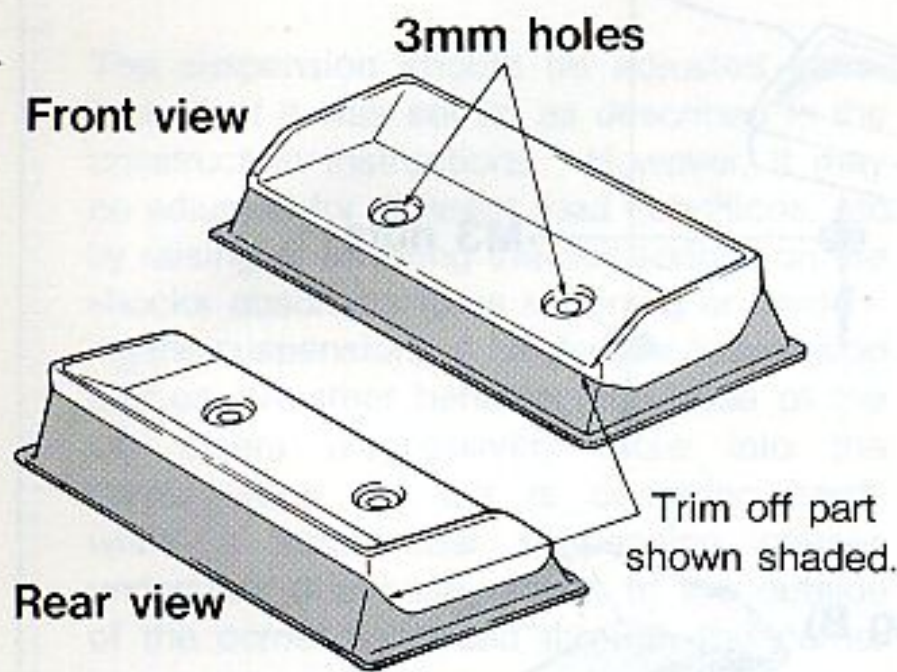
24 PREPARING BODY

Trim off part of body shell shown shaded and make holes where indicated.



Driver figure (Bag 6)

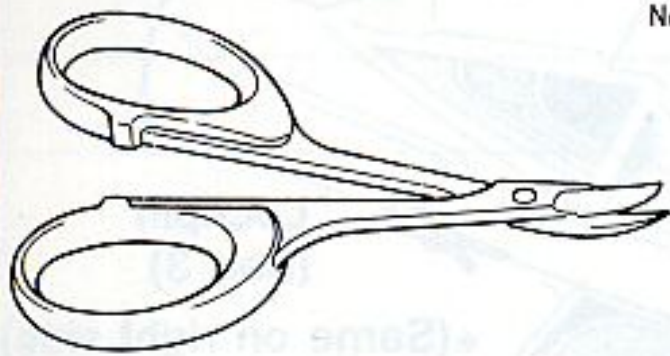
24 Preparing wing



KYOSHO
THE FIRST RACE CONTROL MODEL

Curved-jaw shears cut body shell neatly.

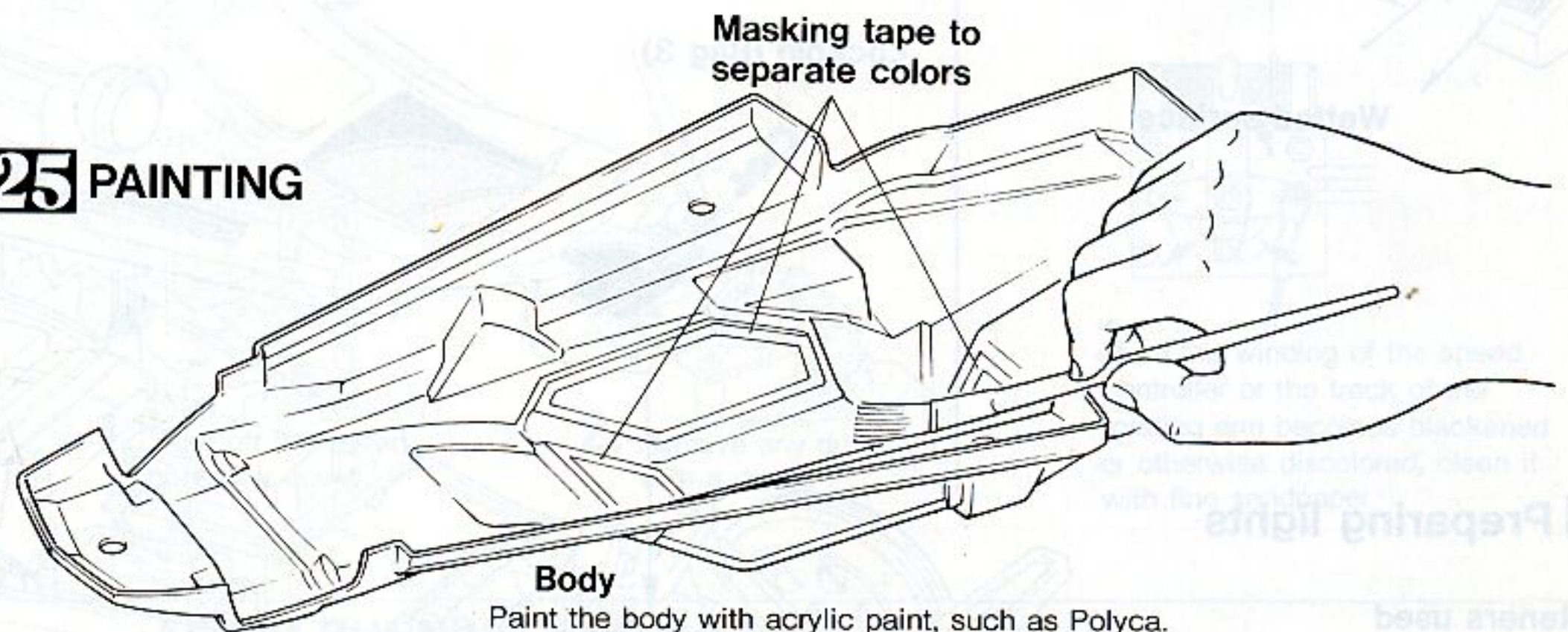
No.1828



25 Notes on painting

*The body shell, wing, and driver are polycarbonate and may be painted using acrylic paint, such as Kyosho Polyca. Applying the paint to the inside surface will result in a glossy, streak-free finish.

25 PAINTING



Paint the body with acrylic paint, such as Polyca. For a glossy finish, paint inside the body. For a matte finish, paint the outside. Masking tape or Micron Line tape can be used to separate areas of different color.

KYOSHO
THE FIRST RACE CONTROL MODEL

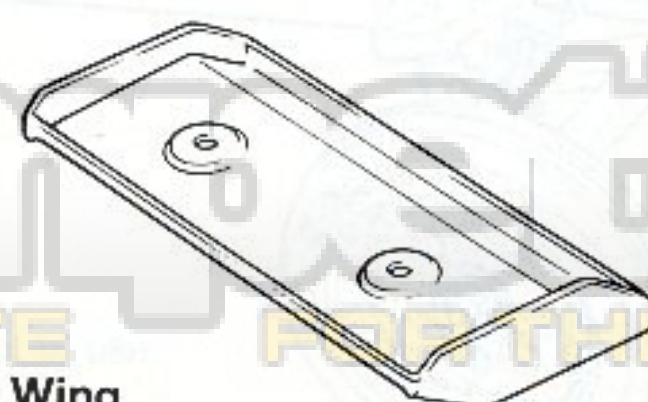


No.1841~3

KYOSHO
THE FIRST RACE CONTROL MODEL

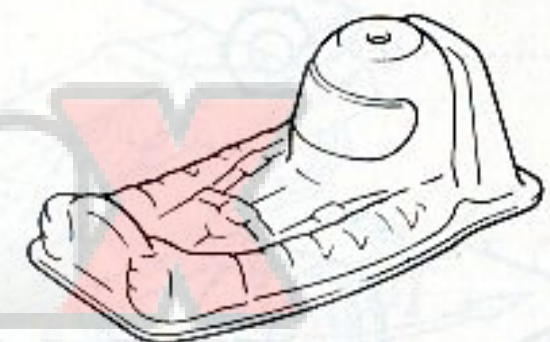


No.2230



Wing

Paint the bottom for a glossy finish, the top for matte.

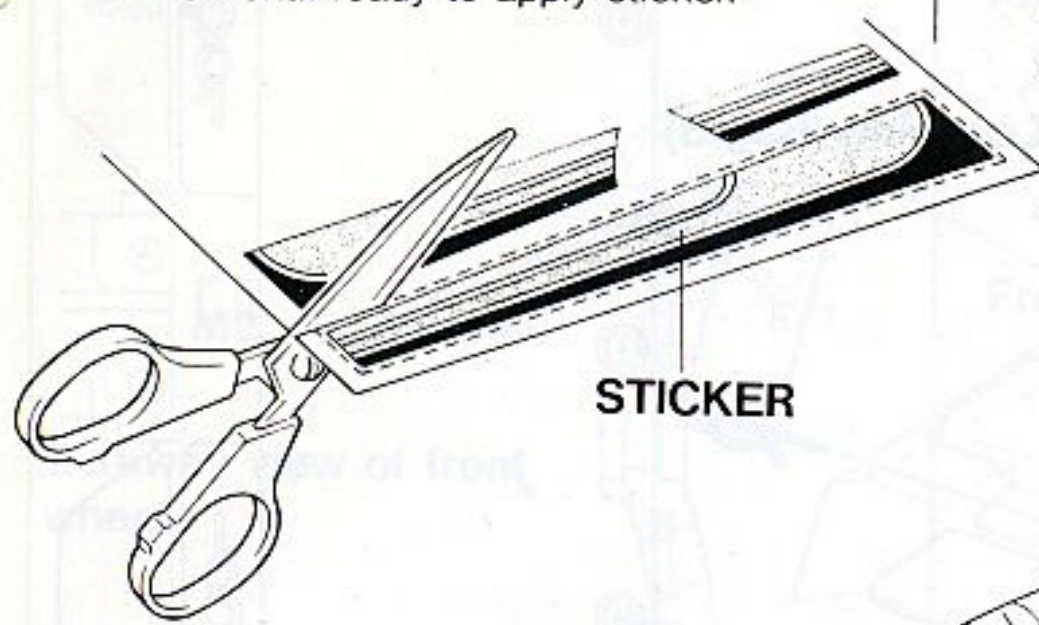


Driver

Due to his small size, driver can be painted more easily on the outside.

26 Applying stickers

* Note: There is an identifying number beside some patterns. Do not cut this number off until ready to apply sticker.

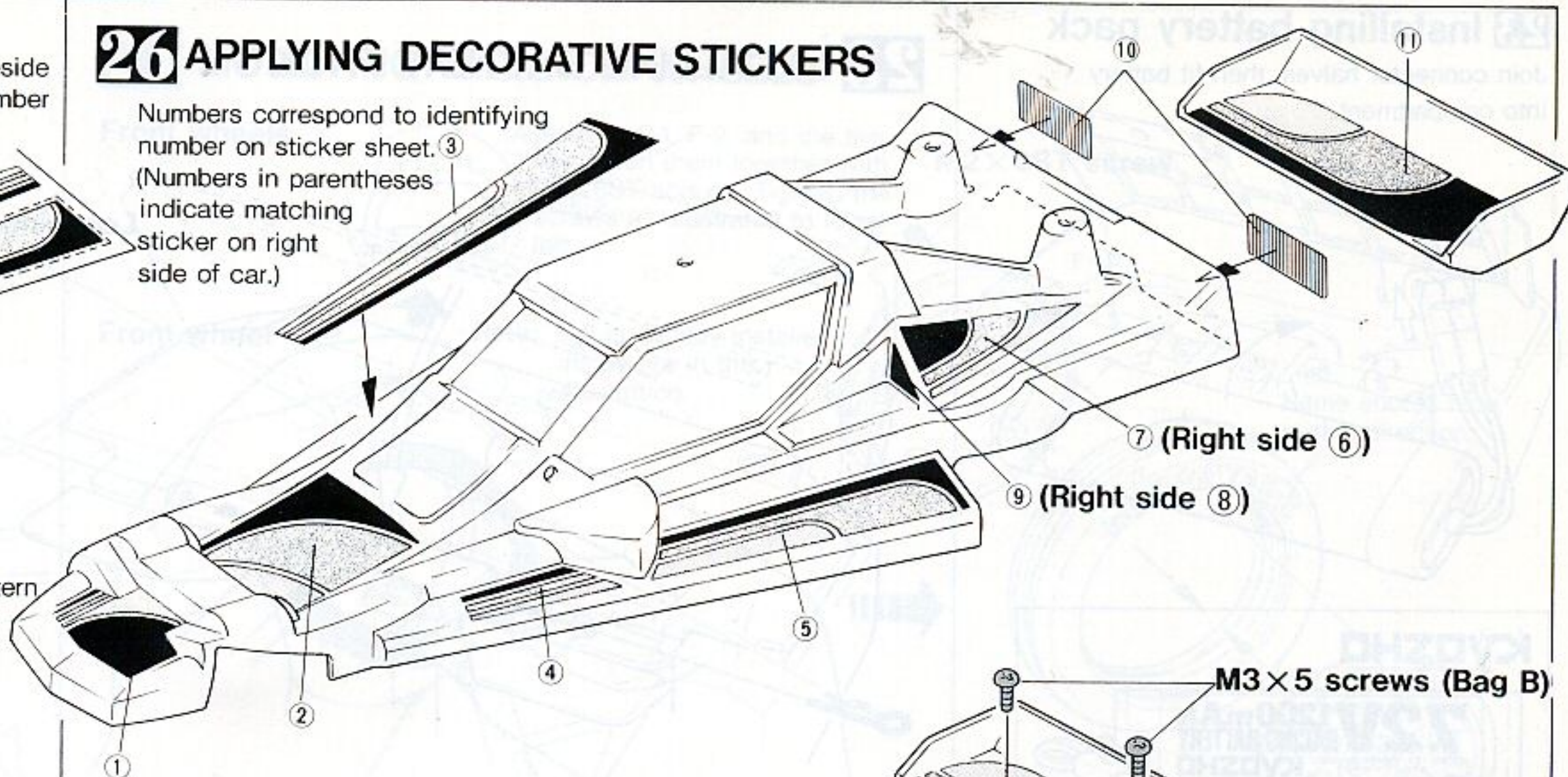


STICKER

Cut stickers from sheet. Cut as close to pattern as possible for the most attractive finish.

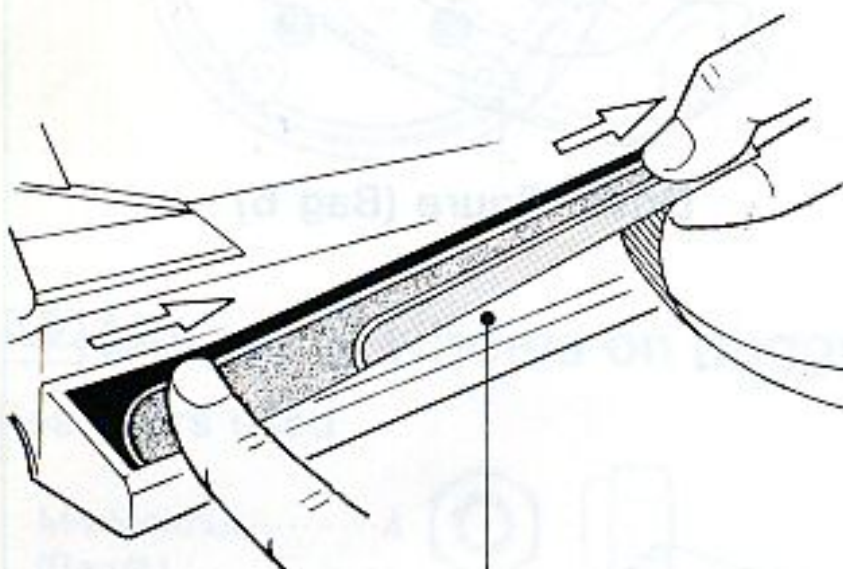
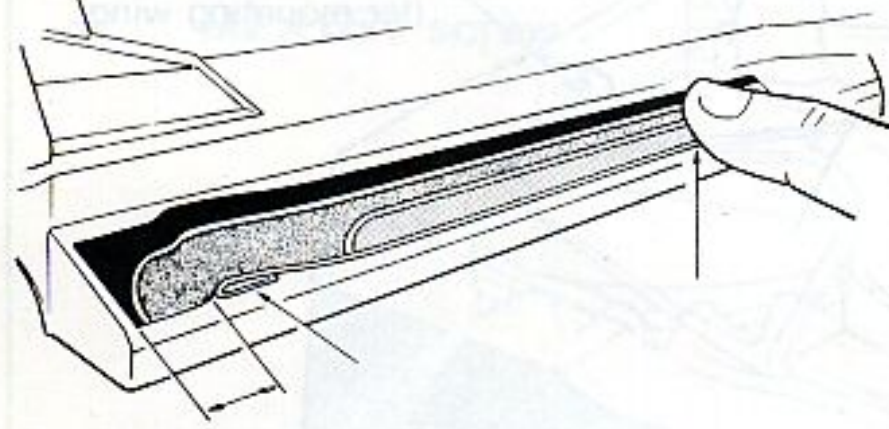
26 APPLYING DECORATIVE STICKERS

Numbers correspond to identifying number on sticker sheet. (3) (Numbers in parentheses indicate matching sticker on right side of car.)

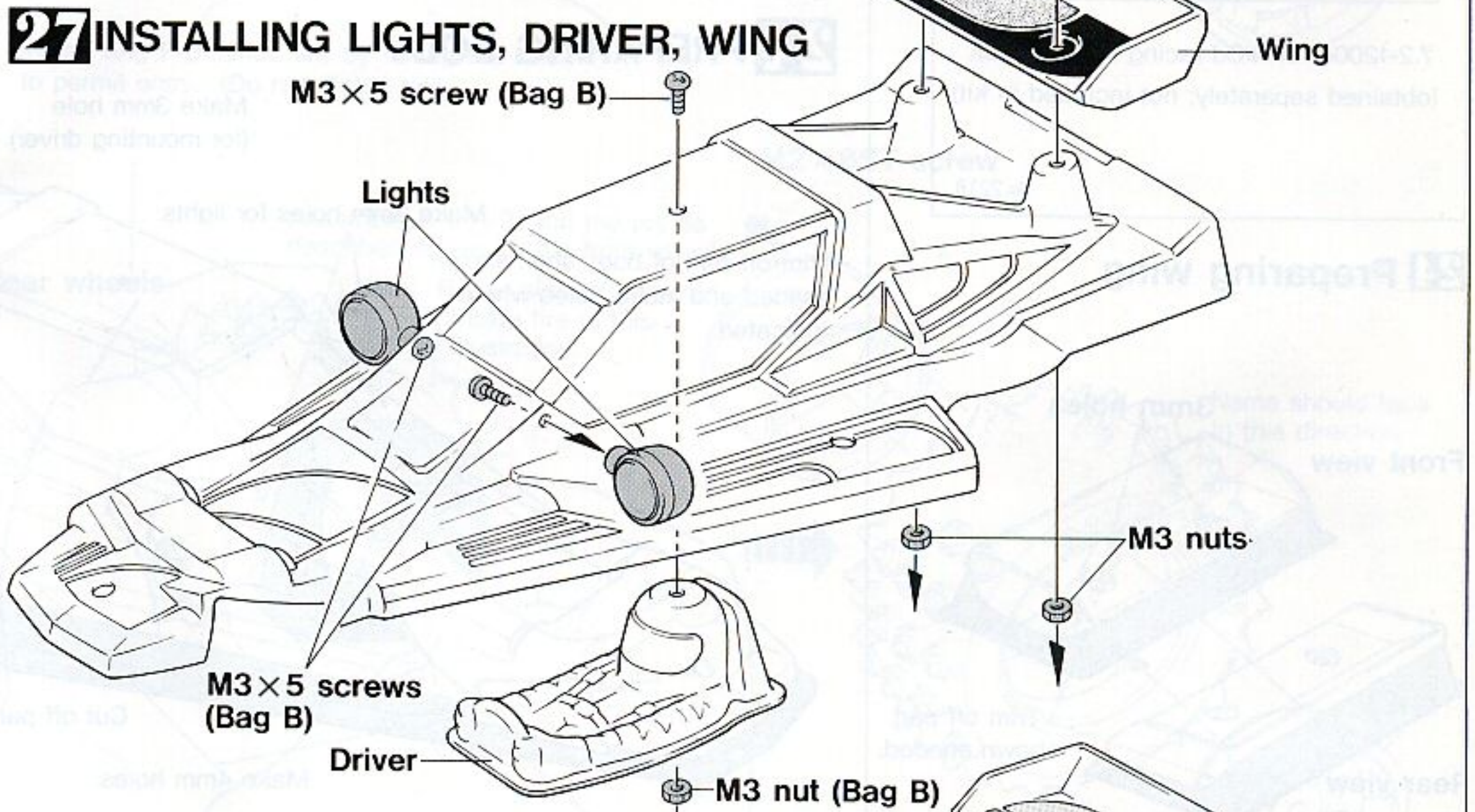


27 INSTALLING LIGHTS, DRIVER, WING

Before applying large stickers, wipe body surface with a solution of dish-washing detergent. Sticker can be moved around until body dries.



Wetted surface

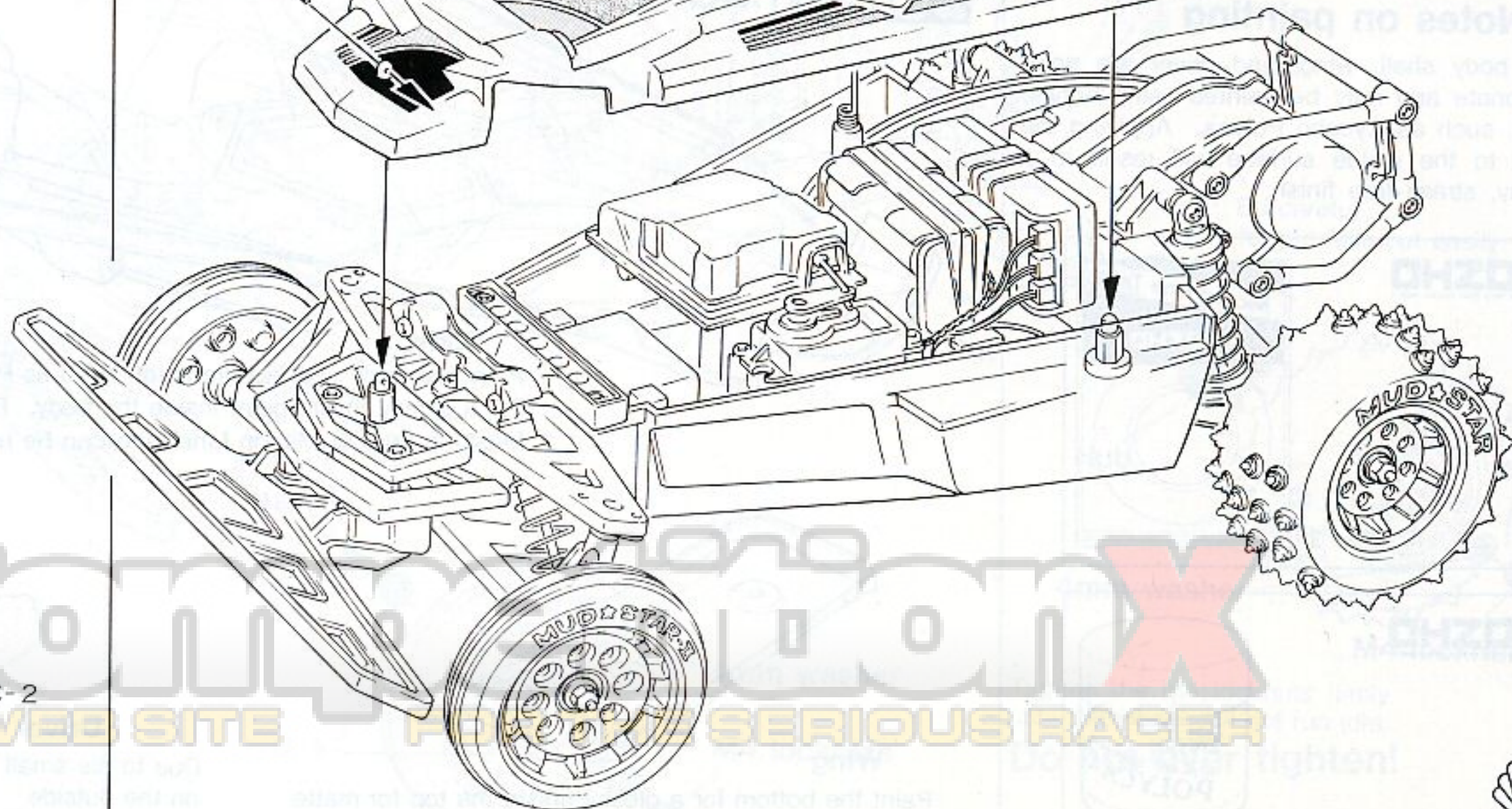


28 INSTALLING BODY

Lockpin (Bag 3)

Lockpin (Bag 3)

*(Same on right side)

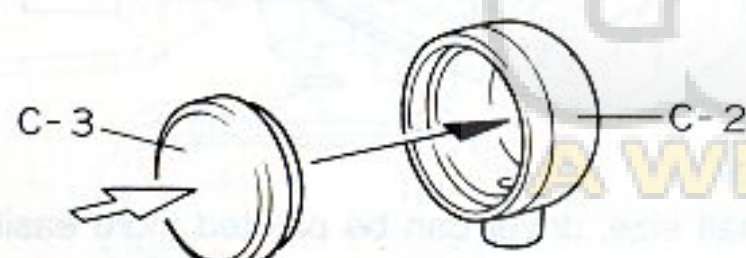


27 Preparing lights

Fasteners used

M3 x 5 screw..... 5

M3 nut..... 3



Snap lens into holder.

CHECKING THE CAR

CHECKING THE CAR

Before running the car, perform the following checks. (The car battery is not needed for these checks.)

1. Check that all screws and nuts are tightened properly.
2. Check that the wiring is neat and that there are no short circuits. (Use electrical insulating tape if there are any bare wires.)
3. Check that all wheels turn freely, without binding or drag. Rotate the wheels by hand for about two seconds to distribute the grease evenly and to free up the bushings.
4. Switch on the transmitter and receiver, then check that the wheels turn right when the steering control is operated for a right turn. Check that the wheels turn an equal distance right and left. If they do not, adjust the linkage.
5. Check that the speed controller slider moves the full distance and in the right direction when the transmitter speed control stick is moved fully forward, then check the same for reverse by moving the stick backward. If slider movement is not correct, adjust the linkage.

After the check, switch off the receiver, then the transmitter, in that order.

RUNNING THE CAR

When the above checks have been made successfully, the car is ready to run. Prepare it in the following manner. Perform these tests in a large open space because the car can go surprisingly quickly.

1. Check that the transmitter, receiver, and car NiCd batteries are charged. (If the radio set uses disposable cells, be sure that the batteries are fresh.)
2. Install the car battery in its compartment and join the connector.
3. Switch on the transmitter.
4. Switch on the receiver.
5. Check that the car moves forward when the transmitter speed stick is moved forward, and that the speed of the car increases as the stick is moved forward progressively farther.
6. Check that the car steers at a rate that allows it to be controlled comfortably. If steering is too quick, move the inner ends of the tie rods to the holes in the servo saver that are closer to the center of the servo wheel.
7. When you have finished running the car, switch off the receiver, then the transmitter.

NOTE: Never switch off the transmitter before the receiver. If there is radio interference, there is the risk that the car will respond and drive away at high speed.

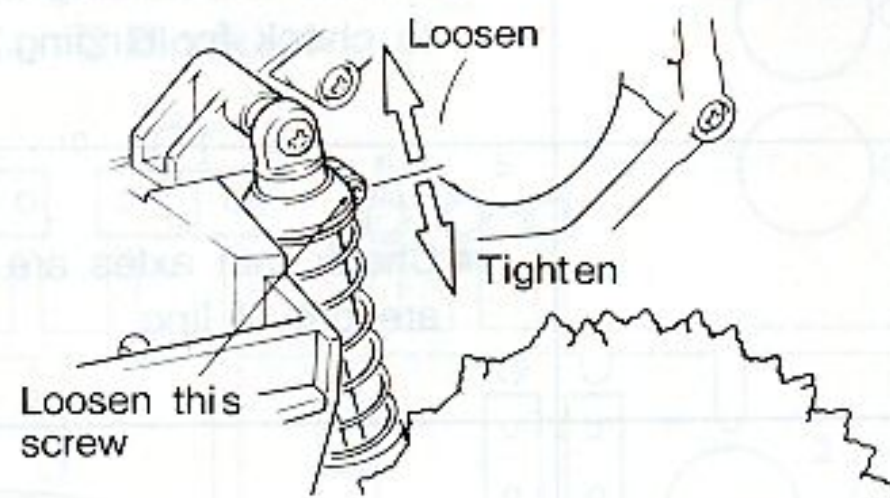
TROUBLESHOOTING

If the car has been assembled carefully, it should run without problem. However, if it fails to perform properly, check the following items one at a time.

1. Connectors of the radio set (battery box, switch lead to receiver, servo leads to receiver), connectors of car battery, wiring, and batteries of radio set (transmitter and receiver).
2. Poor contact of the slider of the speed controller with the wire winding.
3. Fault in the radio equipment. (Consult your hobby dealer.)
4. Interference from another transmitter. (If the servos move or jitter when your transmitter is switched off, this is a problem.)

TUNING THE SUSPENSION

The suspension should be adjusted satisfactorily if it was set up as described in the construction instructions. However, it may be adjusted for different road conditions, etc., by raising or lowering the coil springs on the shocks absorbers (thus softening or hardening the suspension). A harder rear suspension causes oversteer behavior (the nose of the car steers progressively more into the corner when the car is cornering hard), while a softer rear suspension causes understeer (the nose moves to the outside of the corner as speed through the corner increases).



Oversteering

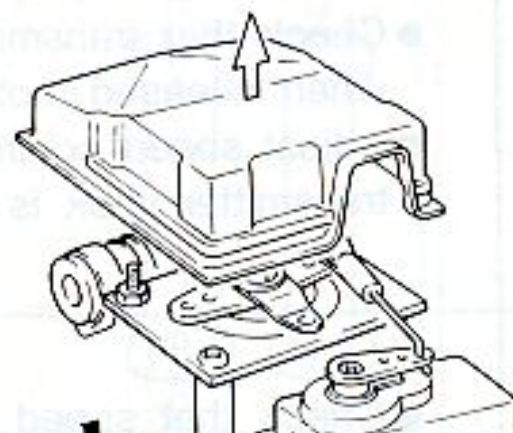
Stiffening the rear suspension will usually result in oversteering.

Understeering

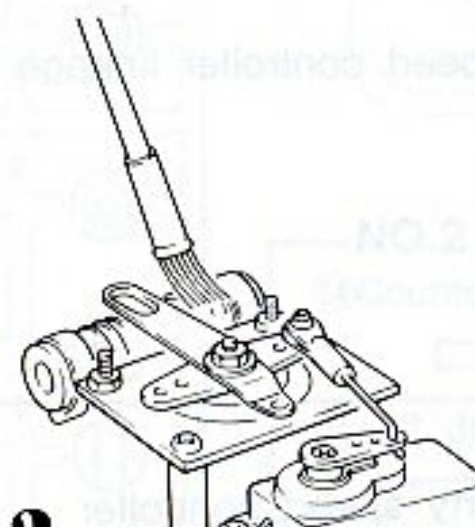
Softening the rear suspension will usually result in understeering.

MAINTENANCE OF SPEED CONTROLLER

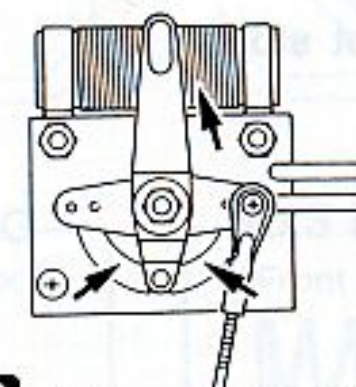
The cover of the speed controller is designed to keep out dirt. However, after running Pegasus in dusty conditions, some dust may have entered and may affect operation (intermittent, unsmooth, etc.). It is advisable to remove the cover regularly and clean off the windings and to oil the pivot of the slider if it becomes stiff and difficult to turn.



1. Take off the speed controller cover.



2. Remove any dust with a brush.

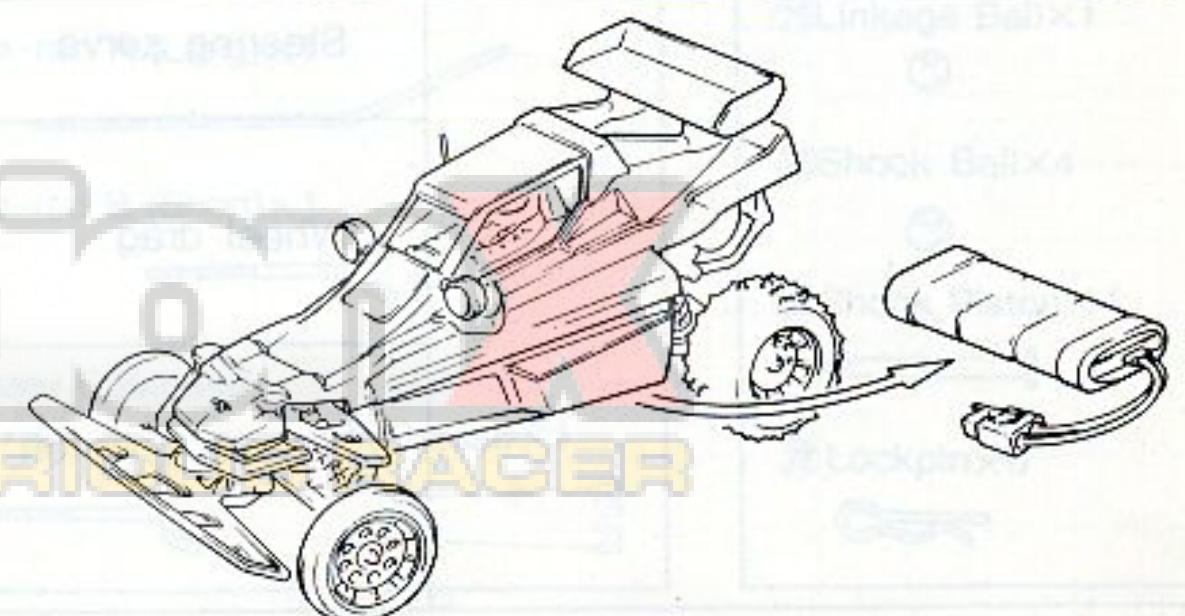


3. If the winding of the speed controller or the track of the rotating arm becomes blackened or otherwise discolored, clean it with fine sandpaper.

AFTER RUNNING THE CAR

- ① Remove NiCd battery.
- ② Clean dirt off car and motor.
- ③ Check that screws are tight.

* Remove the NiCd battery from the car when it is not in use.

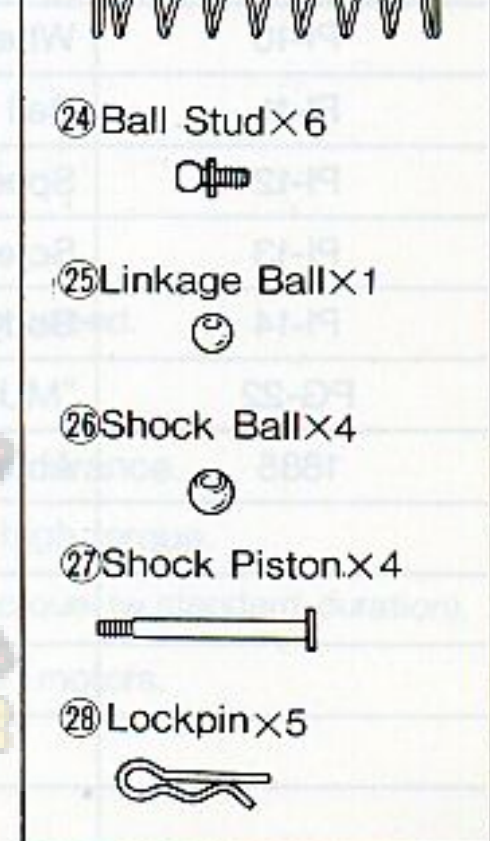
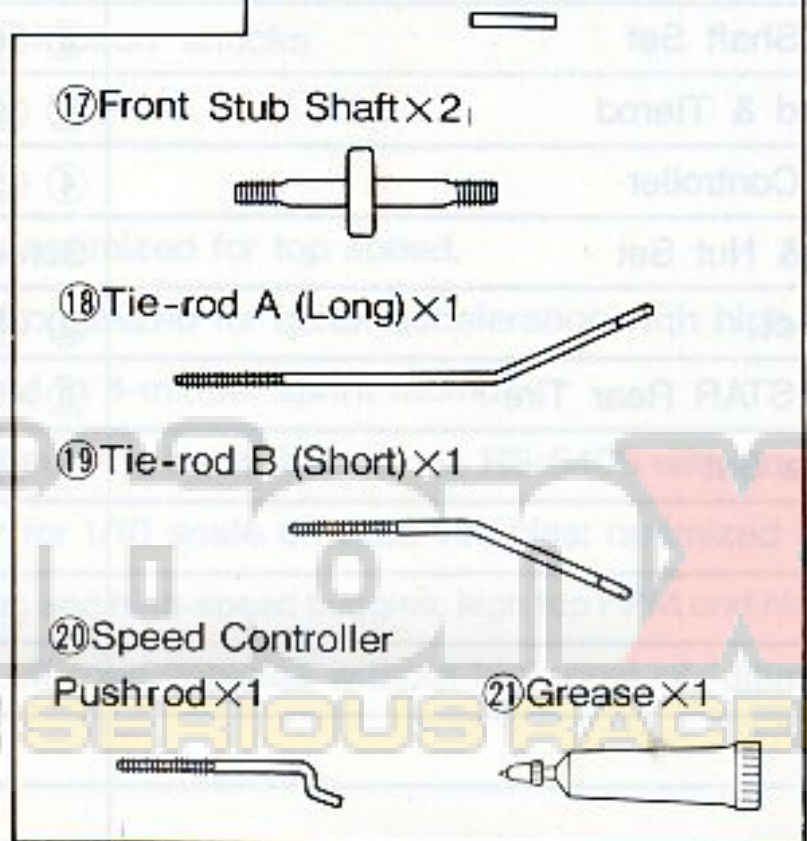
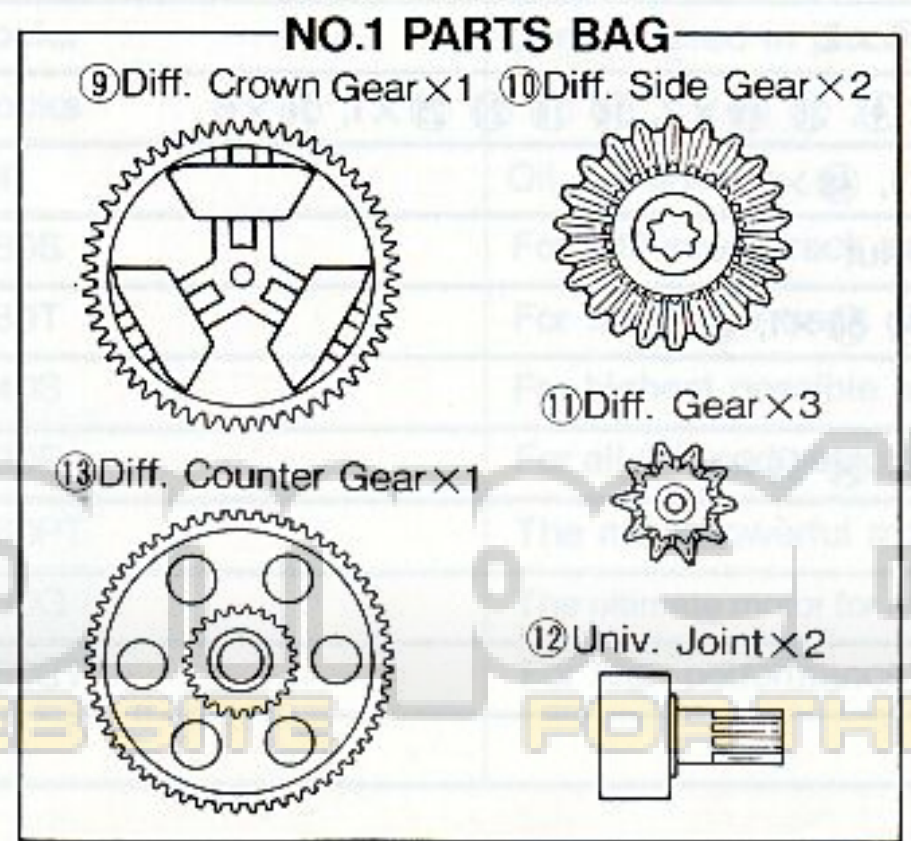
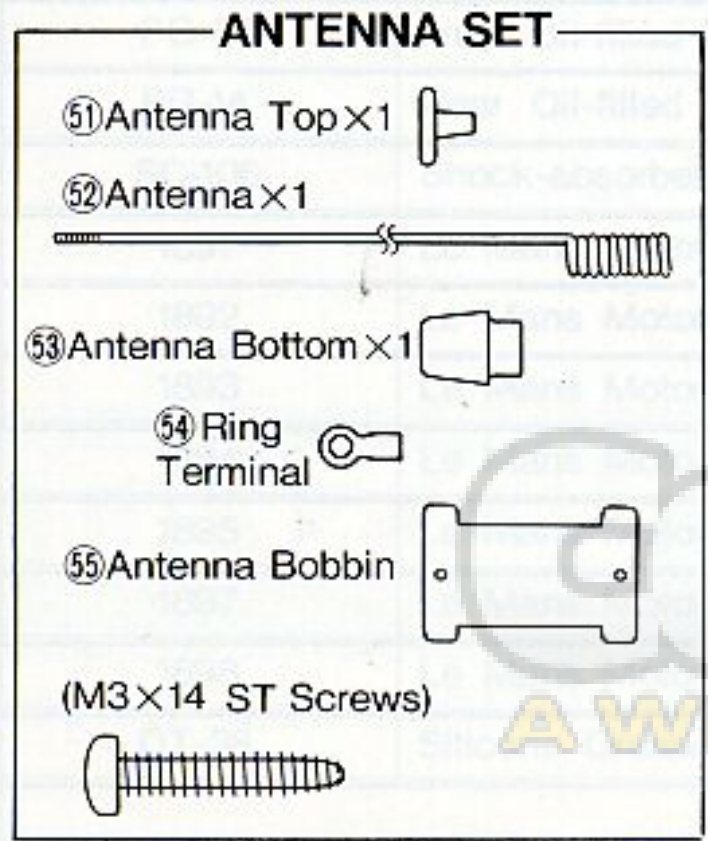
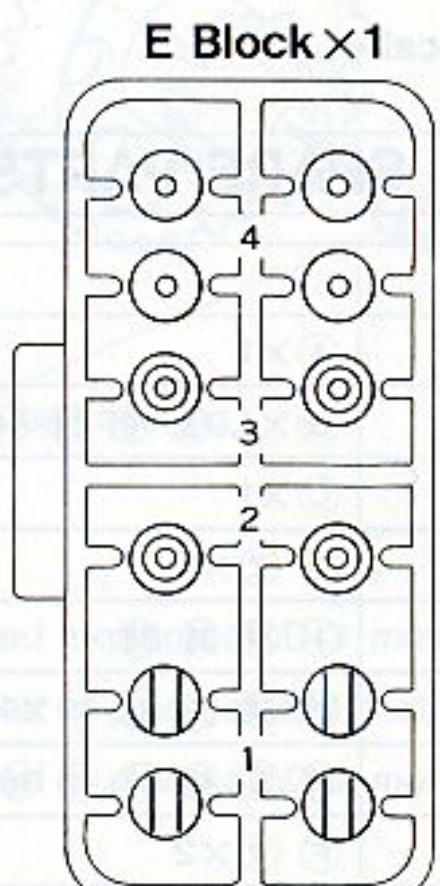
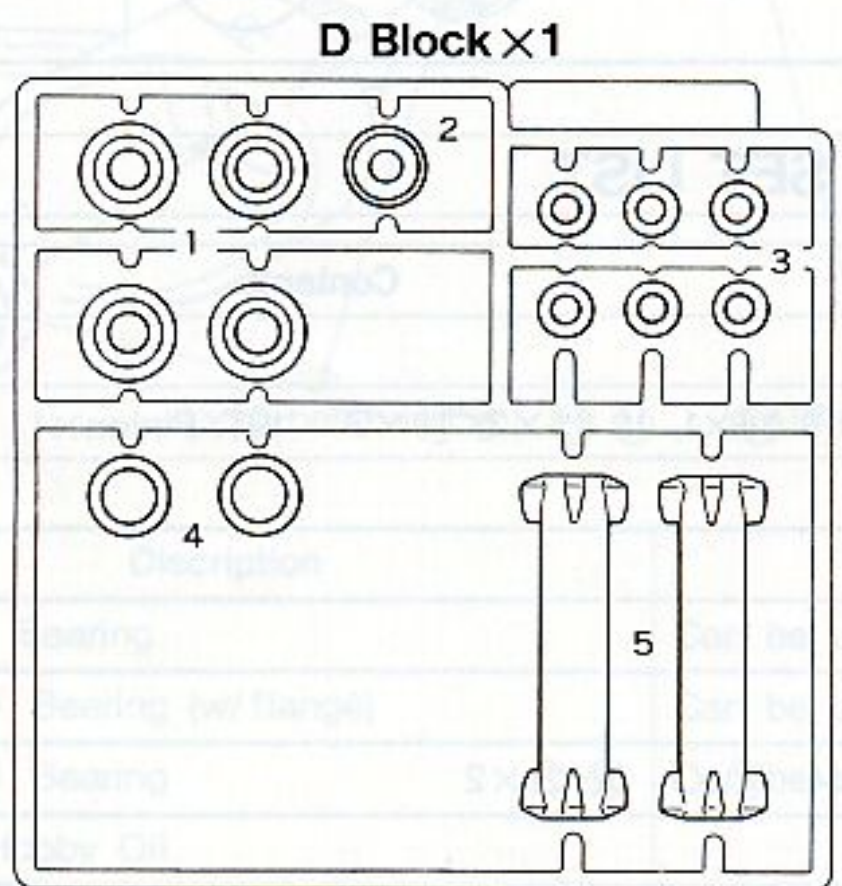
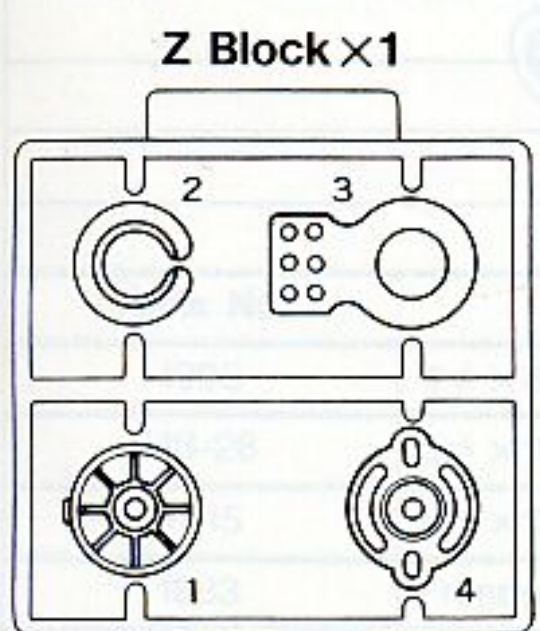
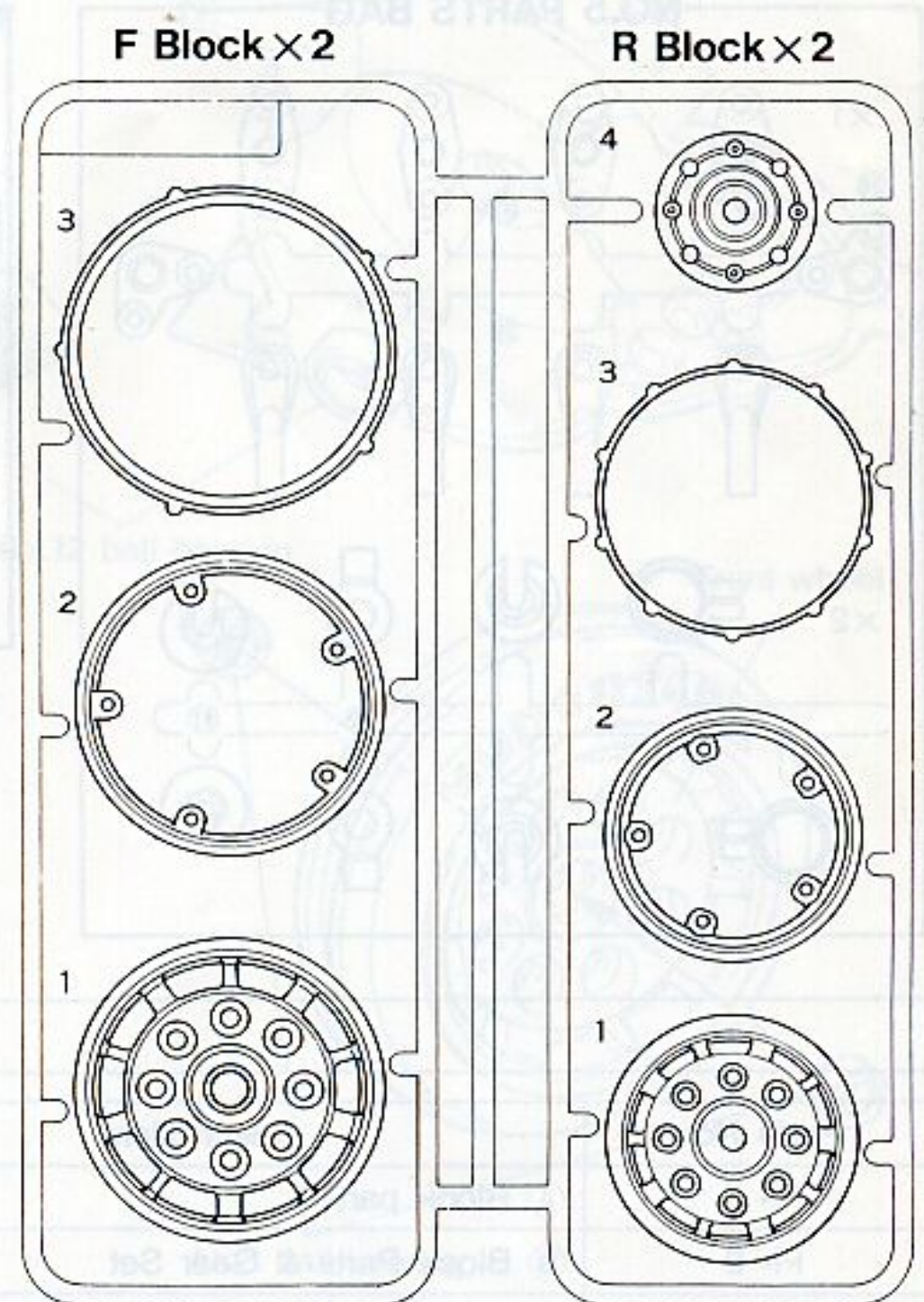
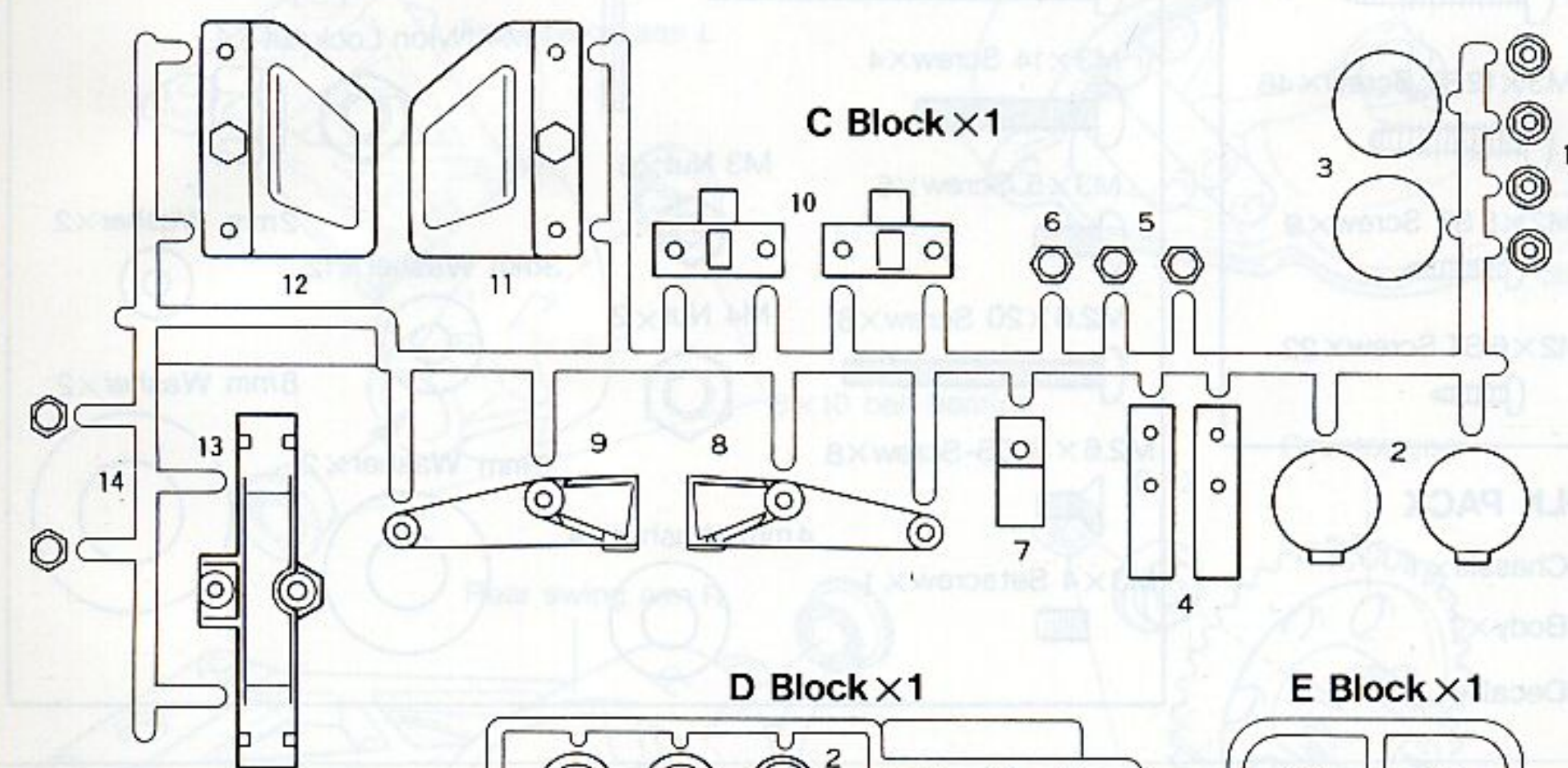
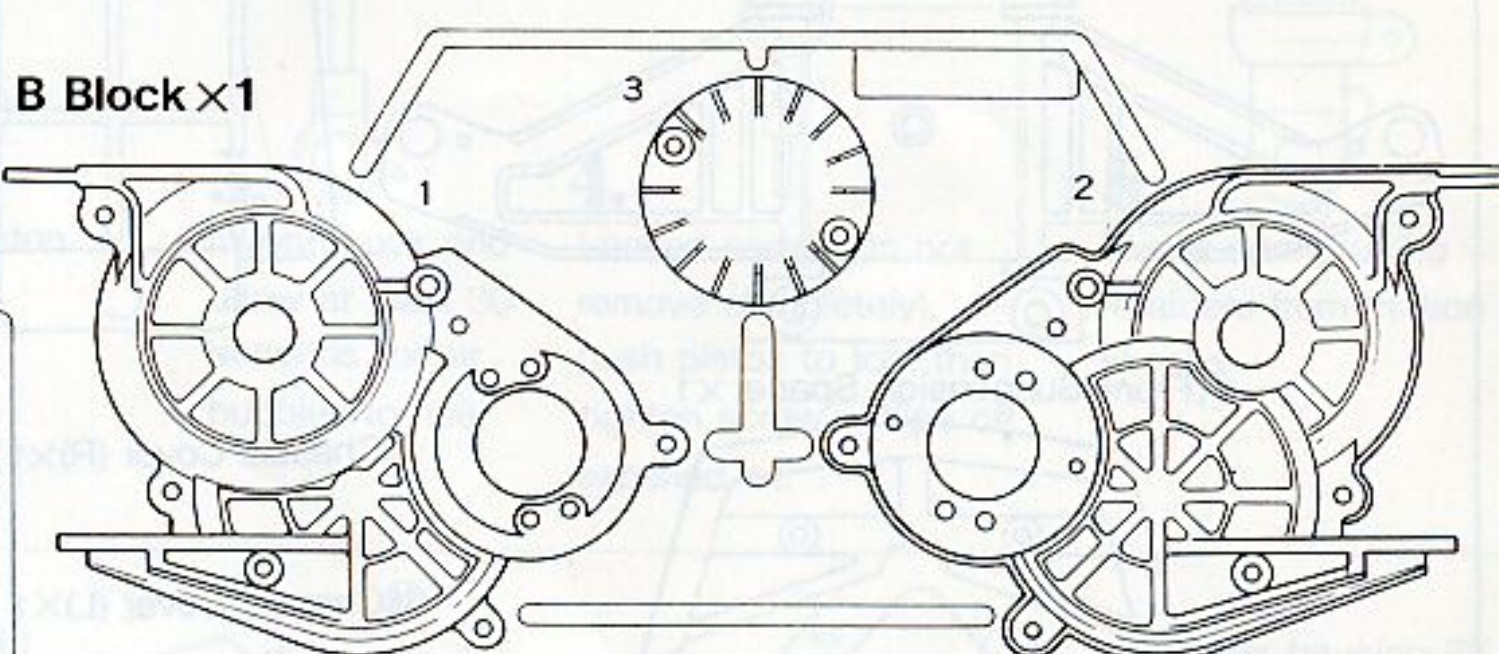
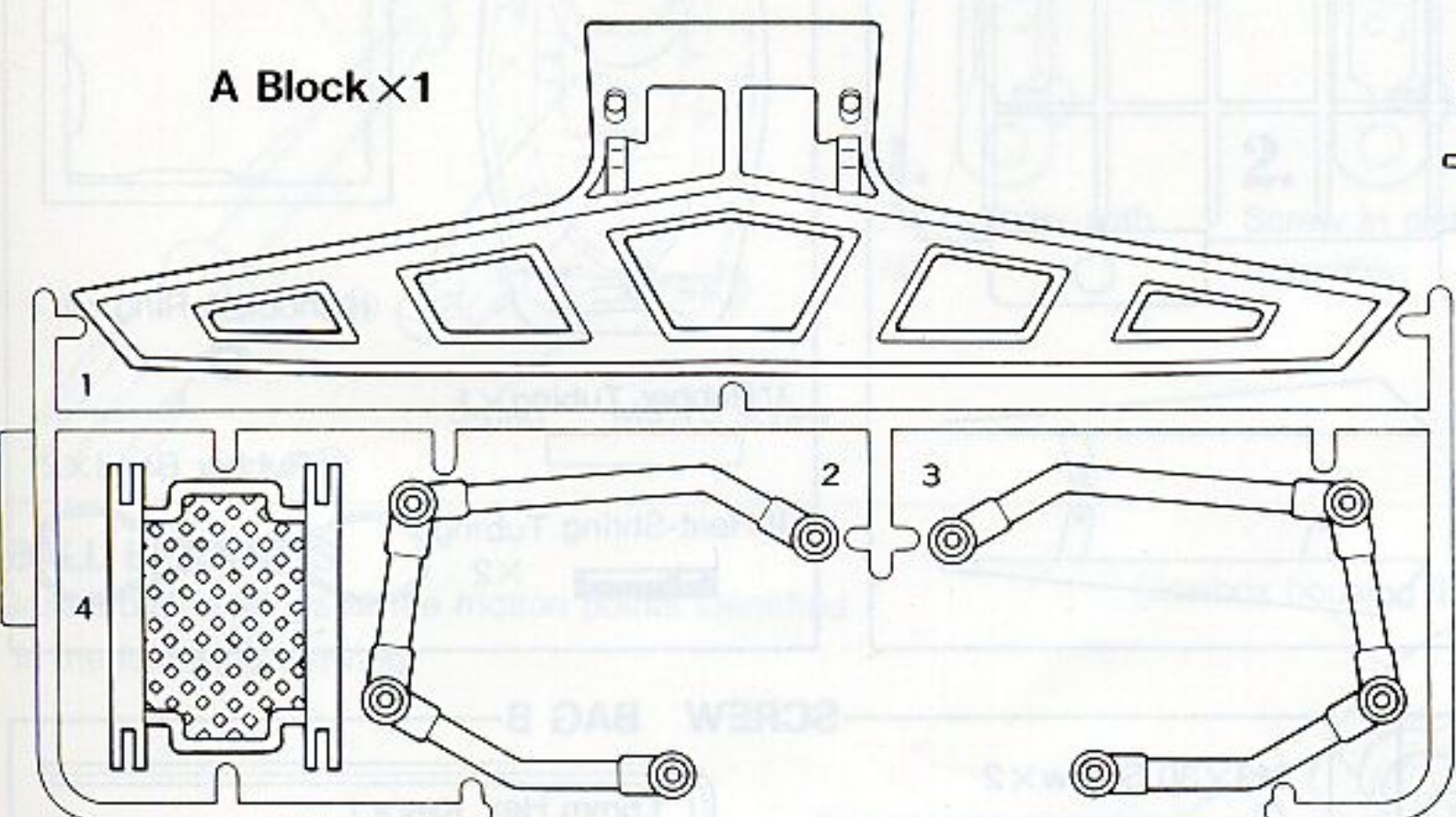
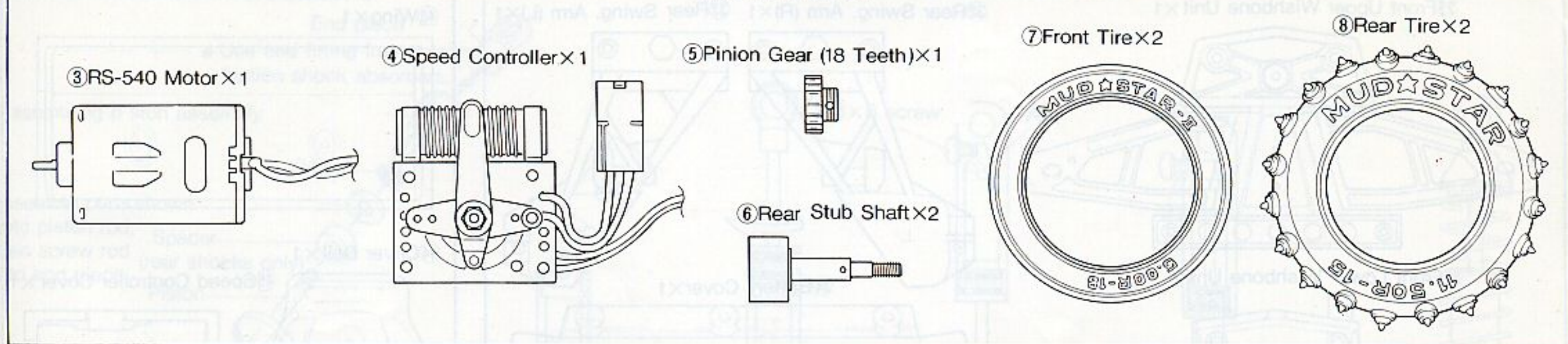


TROUBLE SHOOTING

Problem	Probable cause	Remedy
Servo does not operate	<ul style="list-style-type: none"> ● Weak transmitter or receiver battery ● Fault in radio control set 	<ul style="list-style-type: none"> ● Change/recharge transmitter and receiver batteries. ● Have radio control set checked.
Car stops while running	Discharged car battery	<ul style="list-style-type: none"> ● Recharge battery.
Car stops while running	Bad wiring	<ul style="list-style-type: none"> ● Check all splices and wiring.
Car runs but does not gain speed	Loose pinion on motor shaft (motor spins but car does not move)	<ul style="list-style-type: none"> ● Tighten setscrew of motor pinion.
	Malfunction of speed controller	<ul style="list-style-type: none"> ● Clean the slider and winding of controller. ● Check wiring on back of controller.
	Loose connectors	<ul style="list-style-type: none"> ● Check that all connectors are joined securely.
	Tight axle nuts	<ul style="list-style-type: none"> ● Check nuts holding wheels on axles. (Turn front and rear wheels to check for binding.)
	Bent axles, etc.	<ul style="list-style-type: none"> ● Check that axles are straight and that no other important parts are out of line.
	Malfunction of speed controller	<ul style="list-style-type: none"> ● Check that slider of speed controller moves fully to end of winding when transmitter is set for full speed. ● Check that speed controller slider and winding are free of dirt and corrosion.
	Deterioration of motor, battery	<ul style="list-style-type: none"> ● Replace faulty item.
Car does not stop	Speed controller linkage	<ul style="list-style-type: none"> ● Eliminate free play in speed controller linkage. ● Check that transmitter speed control stick is in center position when released (not offset by trim lever). ● Adjust speed controller linkage so that slider is in center when transmitter stick is in neutral position.
	Dirty speed controller	<ul style="list-style-type: none"> ● Check that speed controller slider and winding are free of dirt and corrosion.
Car does not run straight	Insufficient toe-in	<ul style="list-style-type: none"> ● Adjust length of tie rods as described in instructions.
	Steering servo	<ul style="list-style-type: none"> ● Horn on steering servo not centered. ● Trim lever on transmitter not centered.
	Wheel drag	<ul style="list-style-type: none"> ● Check if a wheel is binding, scraping, or dragging.
	Smaller tires on one side	<ul style="list-style-type: none"> ● Tires may have worn more on one side of car. Check diameter of tires and fit new ones if this is the cause of the problem.

PARTS LIST FOR 2WD RACING BUGGY "PEGASUS"

BLISTER PACK



PARTS LIST (2)

No.4 PARTS BAG

②⑨ Front Upper Wishbone Unit ×1

③② Rear Swing. Arm (R) ×1 ③③ Rear Swing. Arm (L) ×1

③① Front Lower Wishbone Unit ×

③④ Battery Cover ×1

③⑤ Chassis Cover (R) ×1

③⑥ Chassis Cover (L) ×1

③① Front Suspension Spacer ×1

NO.6 PARTS BAG

④③ Wing ×1

④④ Driver Doll ×1

④⑤ Speed Controller Cover ×1

④⑥ Shock O Ring ×4

④⑦ Rubber Tubing ×1

④⑧ Heat-Shring Tubing ×2

④⑨ Rubber Band ×2

NO.5 PARTS BAG

×1

×2

SCREW BAG A

M3×14 ST Screw ×9

M3×12 ST Screw ×46

M2×8 ST Screw ×9

M2×6 ST Screw ×22

BULK PACK

- ① Chassis ×1
- ② Body ×1
- ⑤ Decal ×1

SCREW BAG B

M3×30 Screw ×2

M3×14 Screw ×4

M3×5 Screw ×5

M2.6×20 Screw ×6

M2.6×5 CS-Screw ×8

M3×4 Setscrew ×1

M3 Nut ×5

M4 Nut ×2

4mm Washer ×4

1.5mm Hex Key ×1

M4 Nylon Locknut ×4

2mm Washer ×2

3mm Washer ×12

6mm Washer ×2

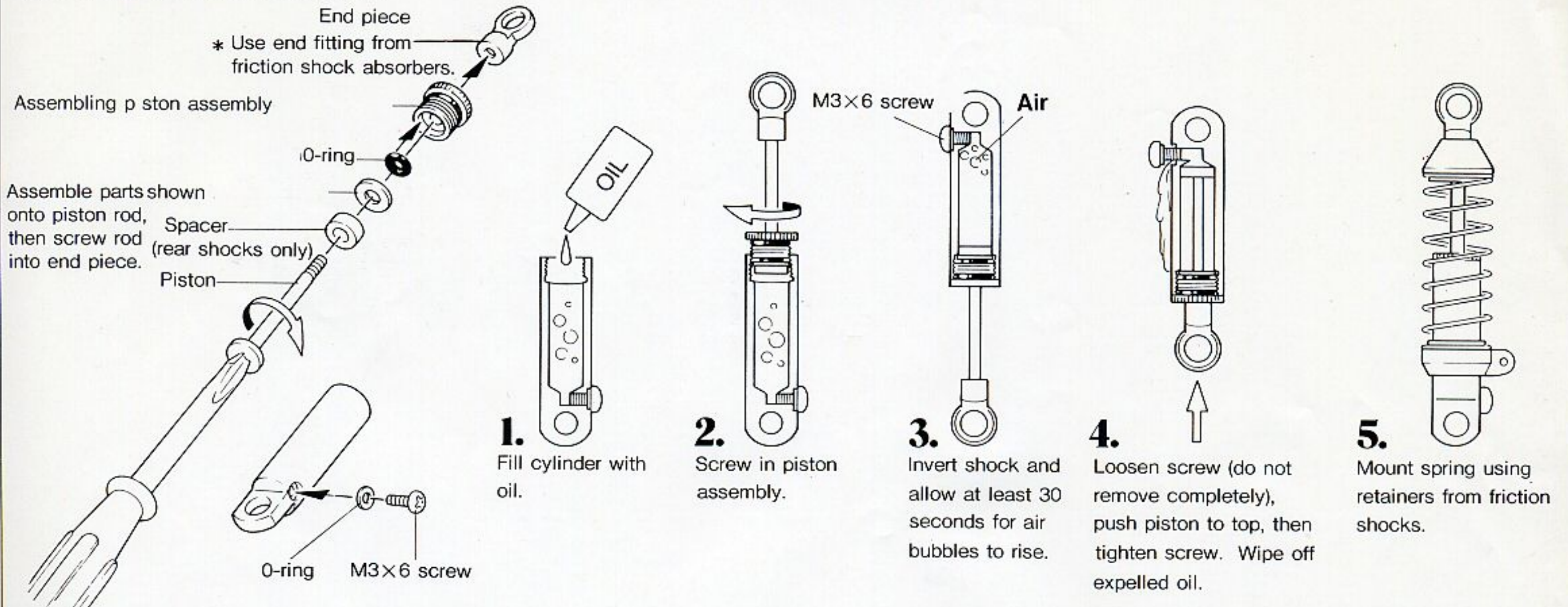
8mm Washer ×2

SPARE PARTS SET LIST

Parts No.	Description	Contents
PI- 1	Ⓐ Block parts	Ⓐ ×1
PI- 2	Ⓑ Block Parts & Gear Set	Ⓑ ×1, ⑤ ⑨ ⑬ ⑭ ⑮ ⑰ ×1, ⑩ ⑫ ×2, ⑪ ×3 19T. Pinion ×1
PI- 3	Ⓒ Block Parts	Ⓒ ×1
PI- 4	Ⓓ ② Block Parts	Ⓓ ② ×1
PI- 5	Chassis Set	① ③④ ③⑤ ③⑥ ×1
PI- 6	Suspension Set	②⑨ ③① ③② ③③ ×1
PI- 7	Friction Shock Set	②⑥ ②⑦ ④① ④② ④⑥ ×4 ⑤ ×1 ②② ②③ ×2
PI- 8	Wheel Set	Ⓕ ④ ×2
PI- 9	"MUD" STAR-II Front Tire	⑦ ×2
PI-10	Wheel Shaft Set	⑥ ⑬ ⑰ ×2
PI-11	Ball end & Tierod	③⑦ ③⑨ ×④, ③⑧ ④⑨ ×2, ⑱ ⑲ ⑳ ㉑ ×1, ㉒ ×6
PI-12	Speed Controller	④ ④⑤ ×1, ④⑧ ×2
PI-13	Screw & Nut Set	Screw, Nut
PI-14	Body Set	② ④③ ④④ ⑤① ×1, ②⑧ ×5
PG-22	"MUD" STAR Rear Tire	⑧ ×2
1885	Antenna Set	⑤① ⑤② ⑤③ ⑤④ ⑤⑤ ×1

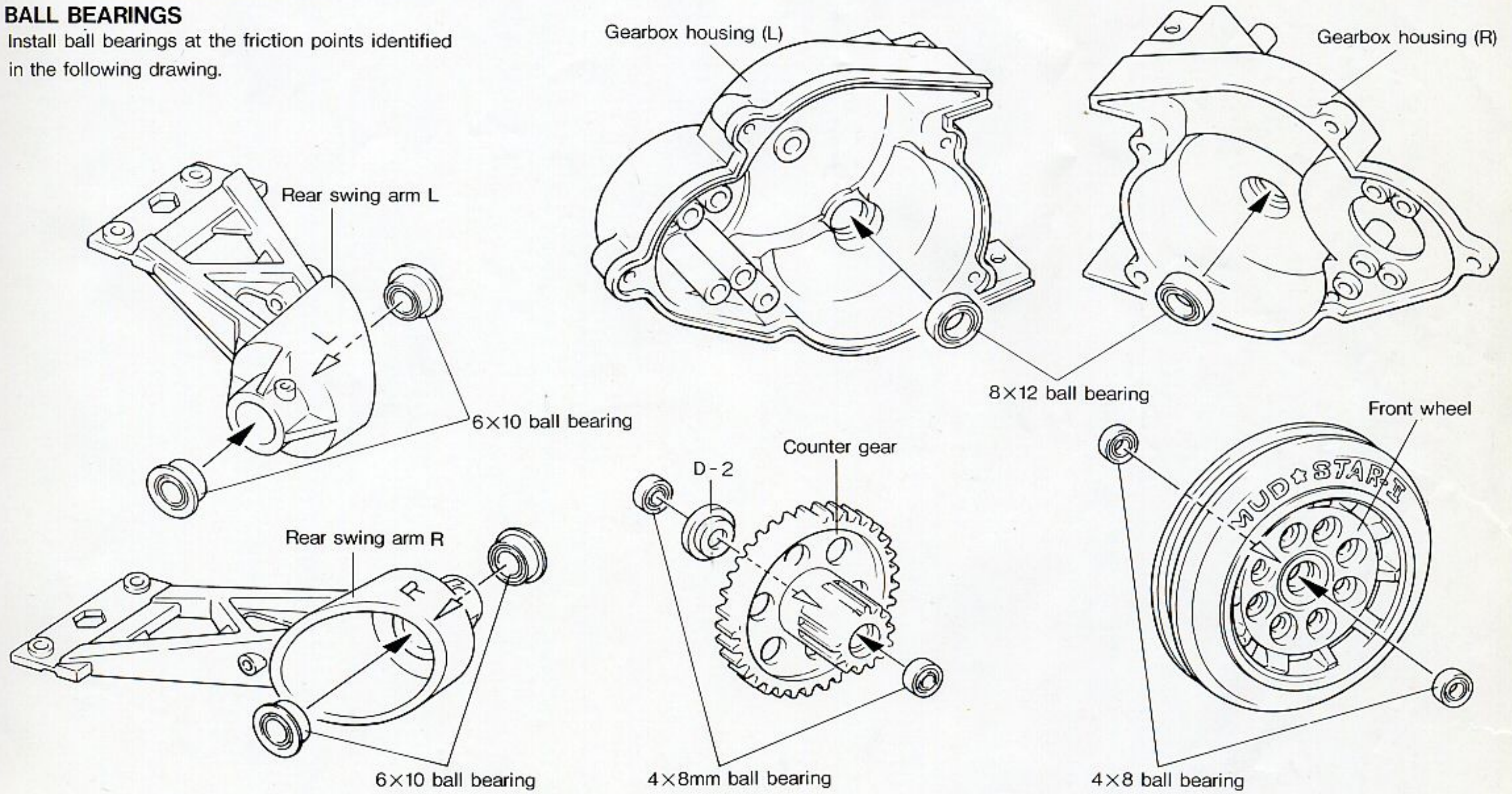
OPTIONAL PARTS

OIL-FILLED SHOCK ABSORBERS



BALL BEARINGS

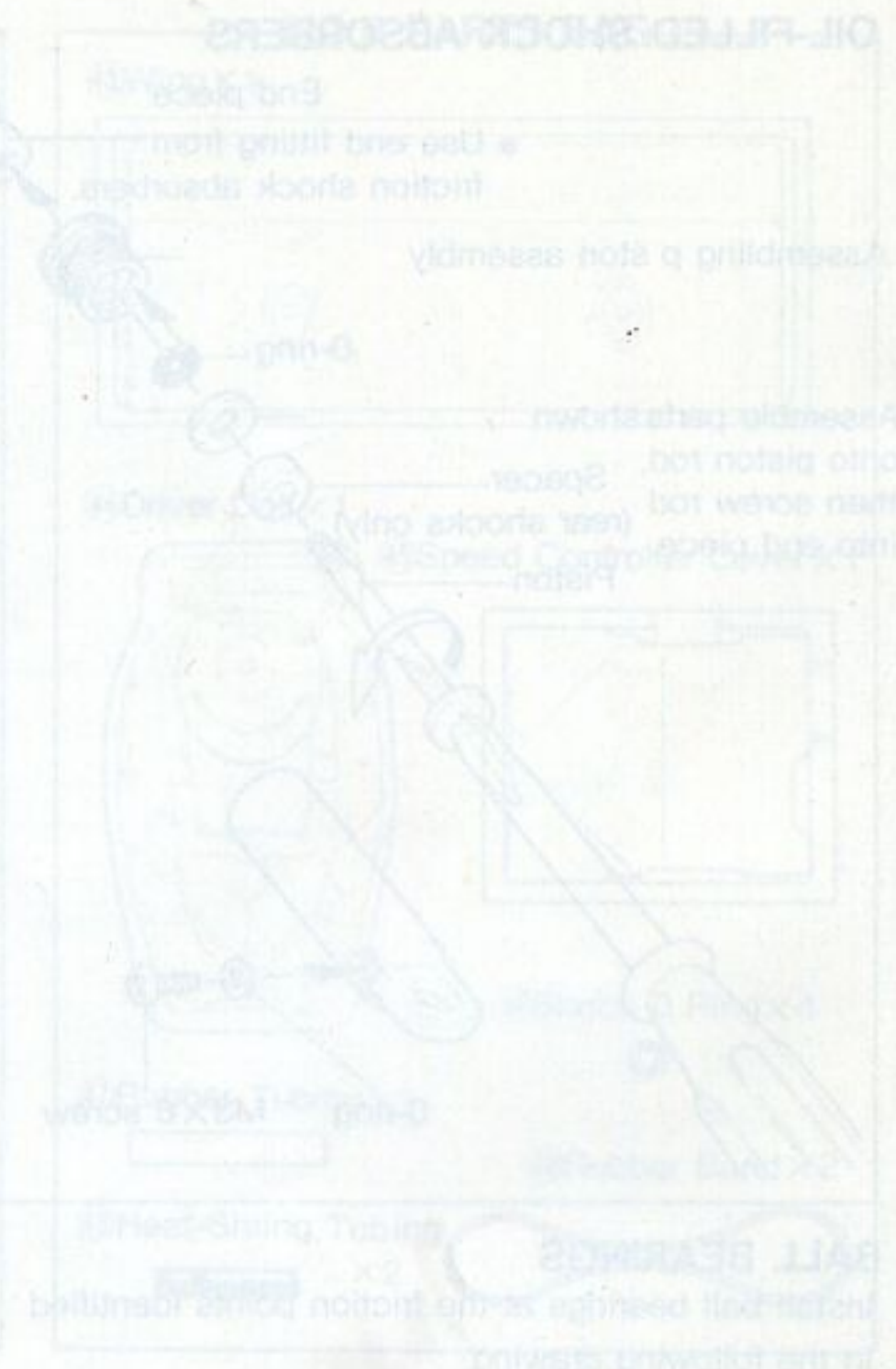
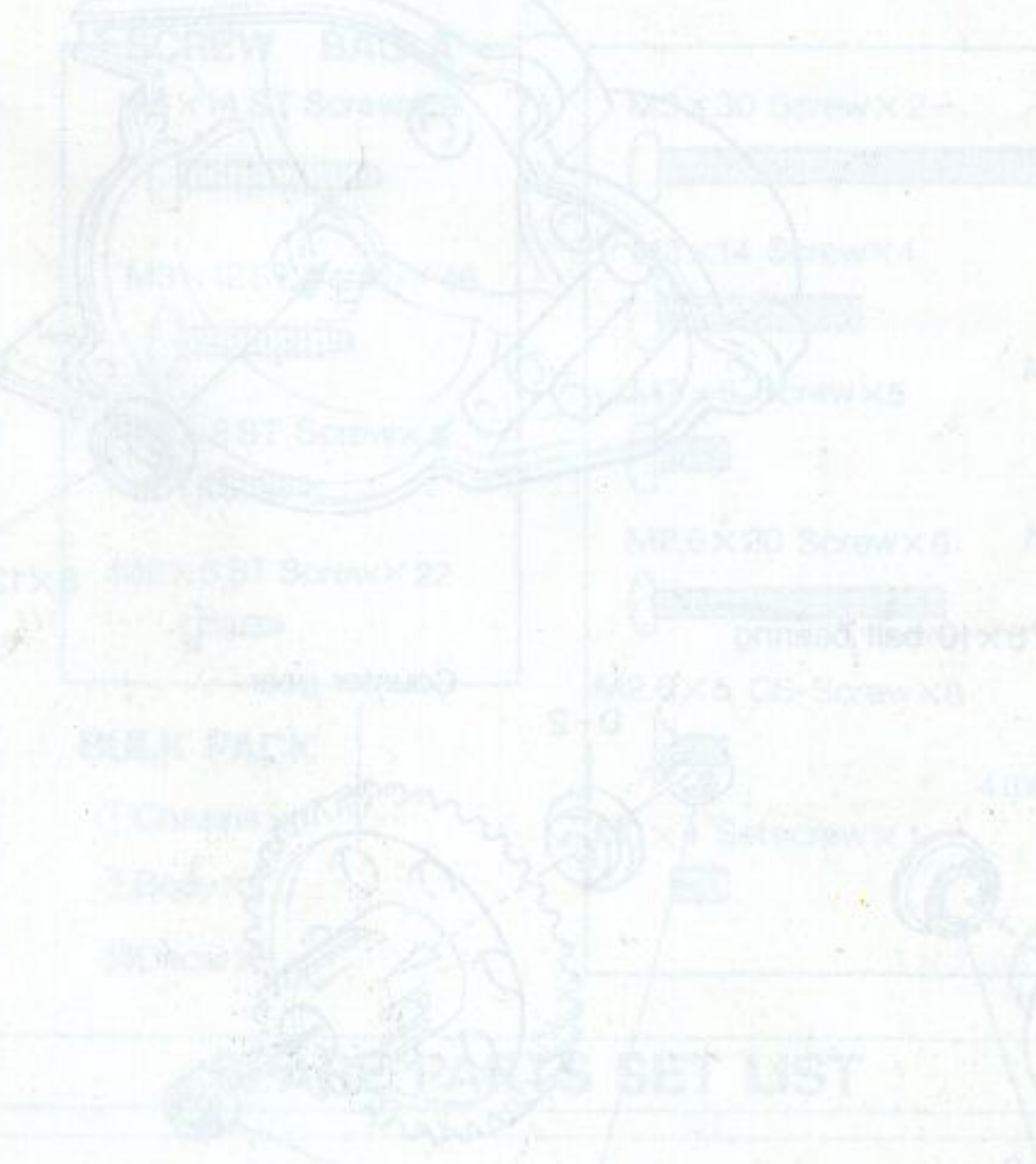
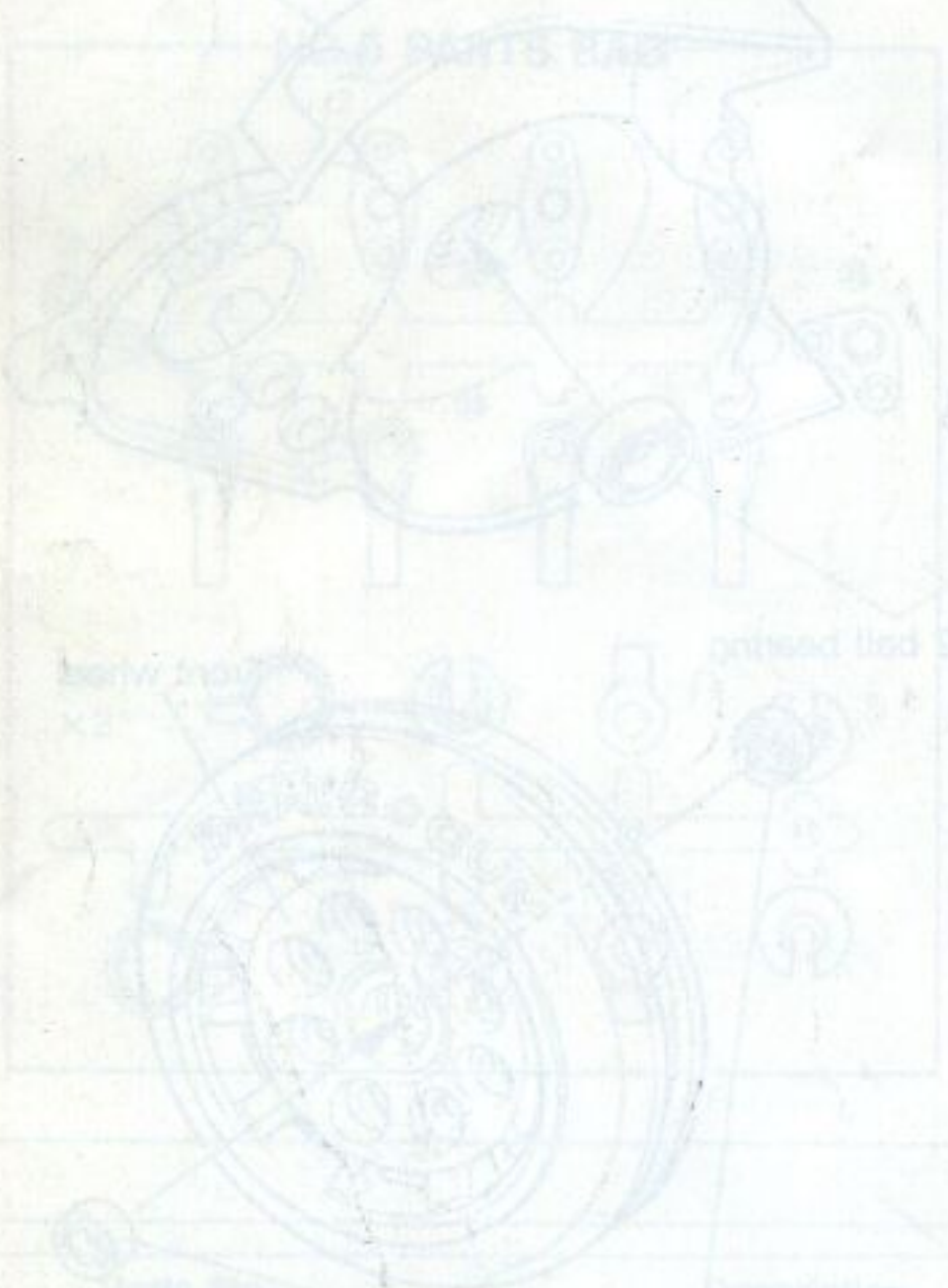
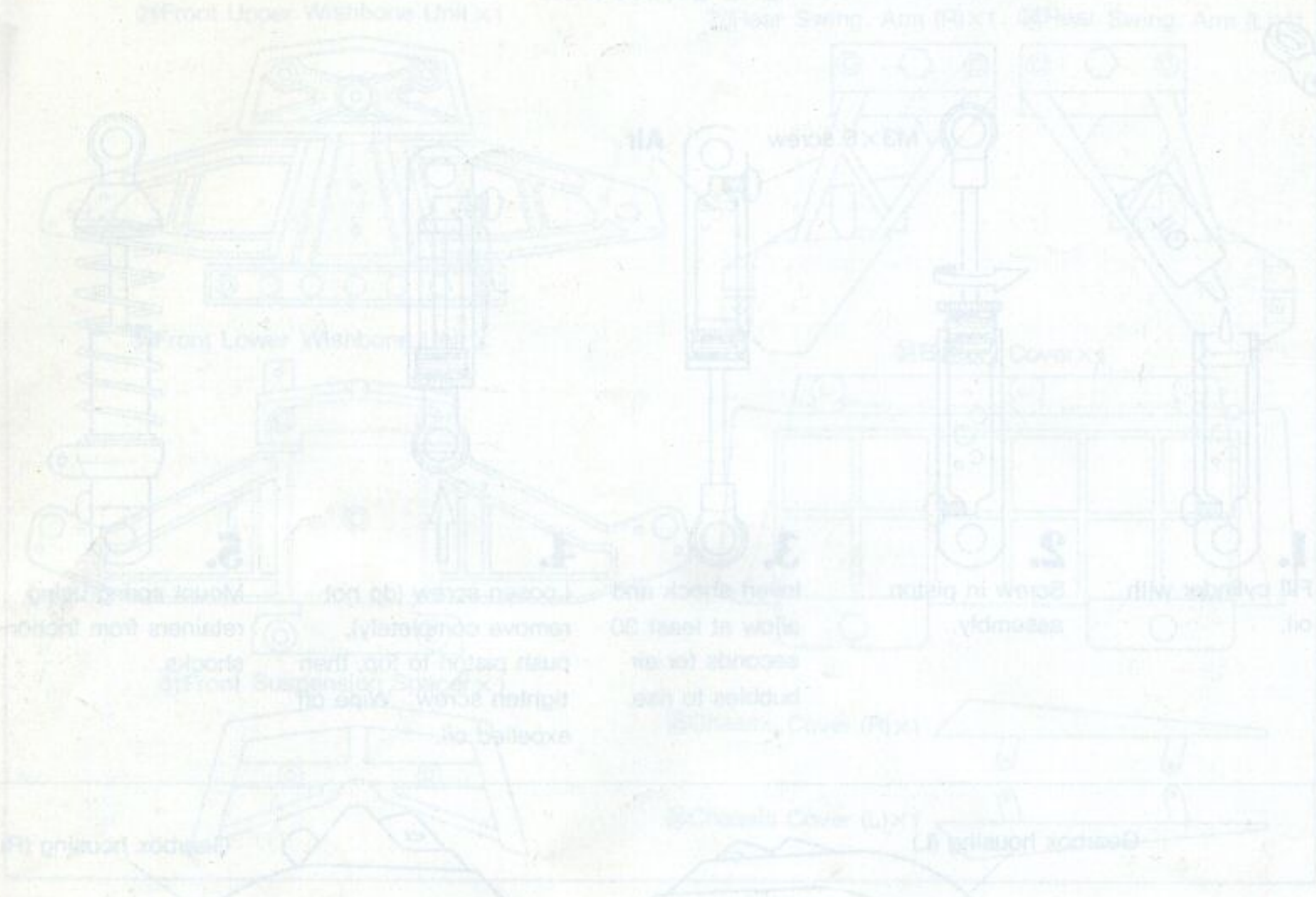
Install ball bearings at the friction points identified in the following drawing.



Parts No.	Description	Contents
1903	4 φ × 8 φ Bearing	Can be used in place of D-3 metal (2 pcs. required)
MS-26	6 φ × 10 φ Bearing (w/flange)	Can be used in place of D-1 metal (2 pcs. required)
PI-15	8 φ × 12 φ Bearing	Can be used in place of D-4 metal (2 pcs. required)
1883	Frontier Hobby Oil	
PG-63	Shim Set for Bearings	
PG-65	Front Oil-filled Shocks	Can be used in place of friction shocks
PG-14	Rear Oil-filled Shocks	//
SC-106	Shock-absorber Oil	Oil for shocks
1891	Le Mans Motor 480S	For 1/12 scale track cars; optimized for top speed.
1892	Le Mans Motor 480T	For 1/12 scale track cars; optimized for quick acceleration with high top speed.
1893	Le Mans Motor 240S	For highest possible speed in 4-minute sprint racing.
1894	Le Mans Motor 600E	For all off-road vehicles; performs better than stock RS-540S with good endurance.
1895	Le Mans Motor 360PT	The most powerful motor for 1/10 scale off-road vehicles; optimized for high torque.
1897	Le Mans Motor 480G	The ultimate motor for racing and high-speed buggies; high top RPM and high torque. (w standard duration).
1898	Le Mans Motor 360ST	For high performance in off-road vehicles without high cost of "ultimate" motors.
OT-38	Silicone Grease	

OPTIONAL PARTS

No. 4 PARTS BAG



Part No.	Description
PG-22	Front Wheel Hub
PG-21	Rear Wheel Hub
PG-20	Front Axle
PG-19	Rear Axle
PG-18	Front Wheel Bearing
PG-17	Rear Wheel Bearing
PG-16	Front Lower Wishbone
PG-15	Rear Lower Wishbone
PG-14	Front Upper Wishbone
PG-13	Rear Upper Wishbone
PG-12	Shock Absorber
PG-11	Oil-Filled Shock Absorbers

Part No.	Description	Contents
PG-22	Front Wheel Hub	1 x Front Wheel Hub
PG-21	Rear Wheel Hub	1 x Rear Wheel Hub
PG-20	Front Axle	1 x Front Axle
PG-19	Rear Axle	1 x Rear Axle
PG-18	Front Wheel Bearing	2 x Front Wheel Bearings
PG-17	Rear Wheel Bearing	2 x Rear Wheel Bearings
PG-16	Front Lower Wishbone	2 x Front Lower Wishbones
PG-15	Rear Lower Wishbone	2 x Rear Lower Wishbones
PG-14	Front Upper Wishbone	2 x Front Upper Wishbones
PG-13	Rear Upper Wishbone	2 x Rear Upper Wishbones
PG-12	Shock Absorber	2 x Shock Absorbers
PG-11	Oil-Filled Shock Absorbers	2 x Oil-Filled Shock Absorbers

COMPETITION

A WEB SITE FOR THE SERIOUS RACER



KYOSHO
THE FINEST RADIO CONTROL MODELS

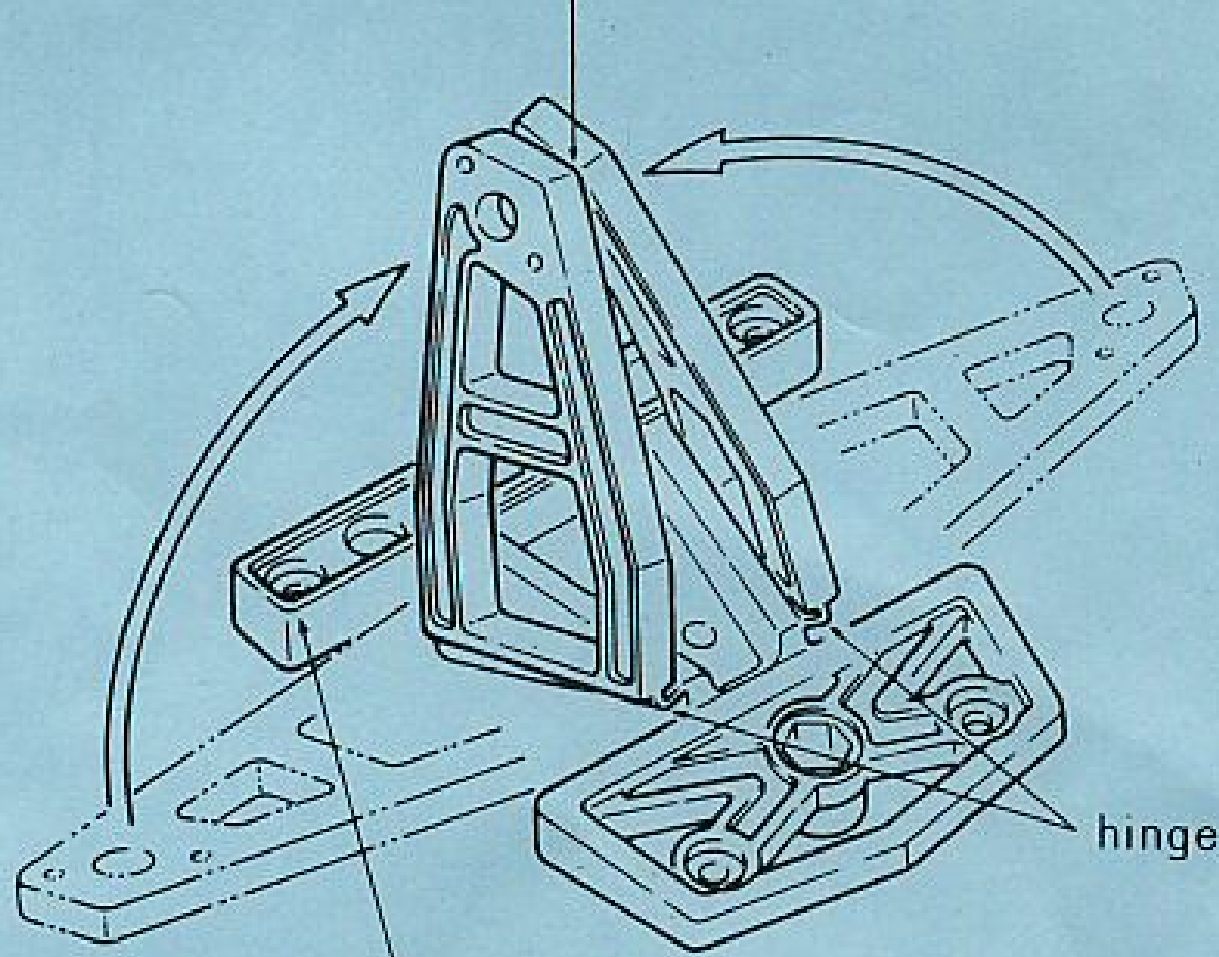
KYOSHO CORPORATION

BEFORE ASSEMBLY

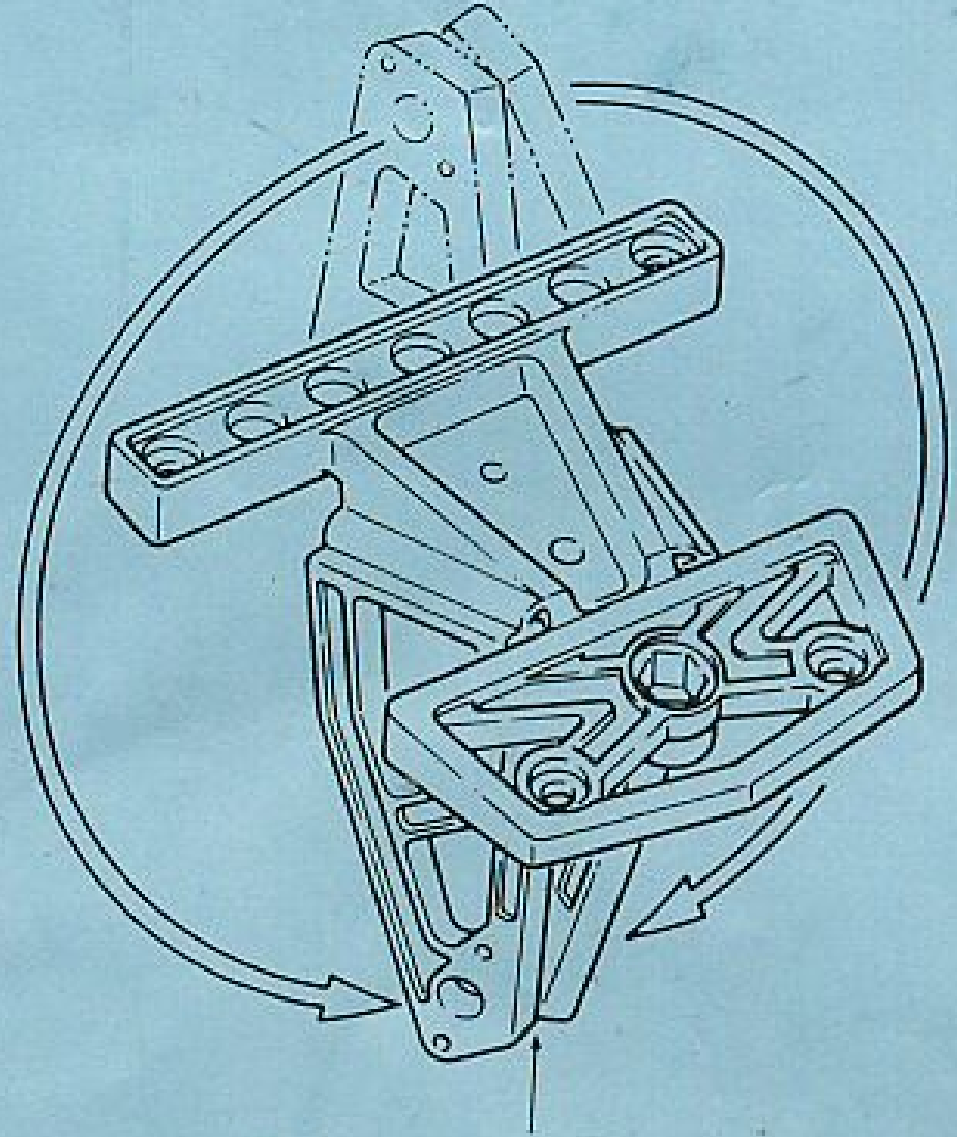
- Before assembly flex the hinges of the front suspension arms up and down at least five times as shown below.

① Front Upper Arm

Bend both arms up together until they touch.



The same as upward.

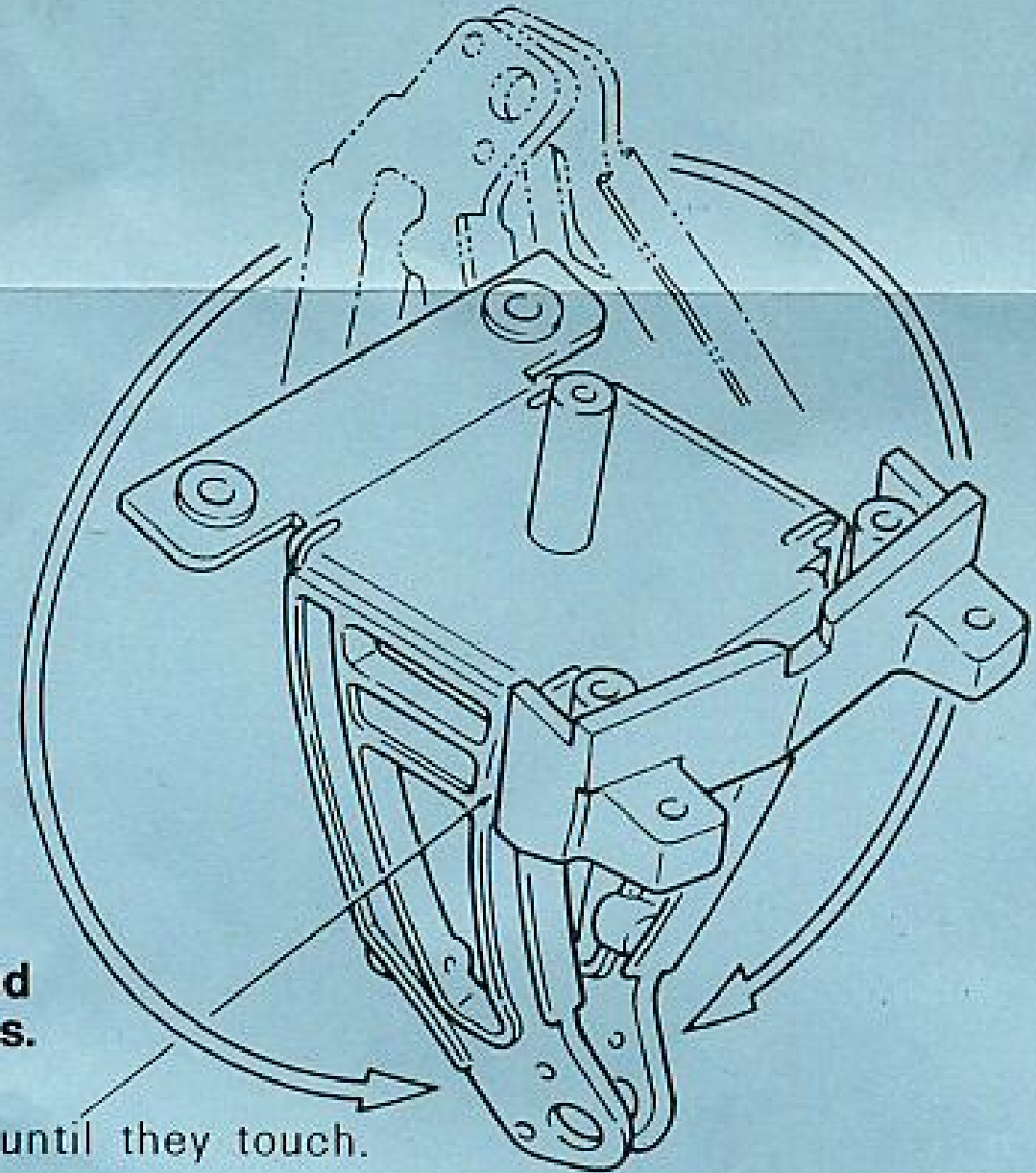
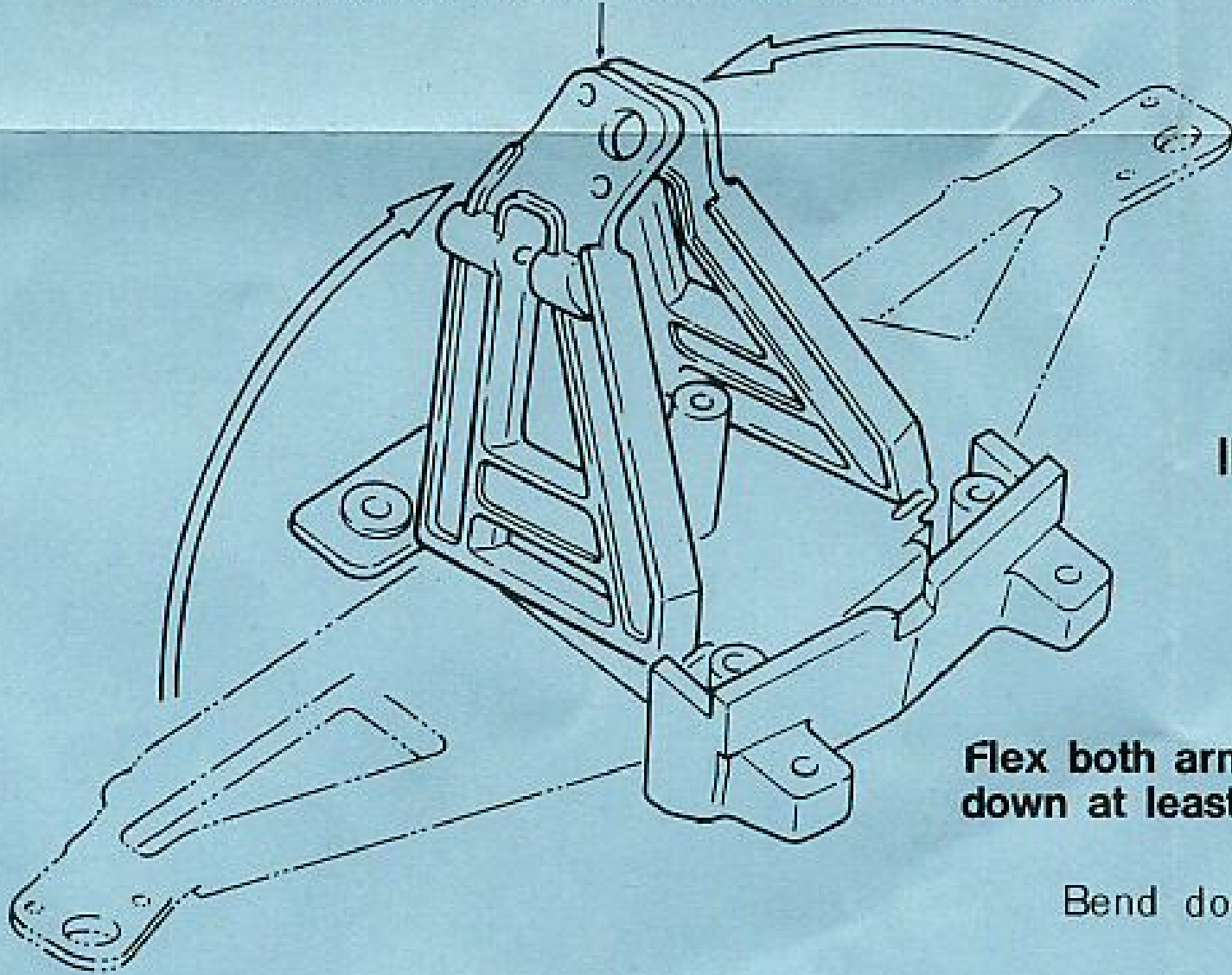


Flex both arms up and down at least 10 times.

Bend downward as shown.

② Front Lower Arm

Flex both arms up and down as described above.

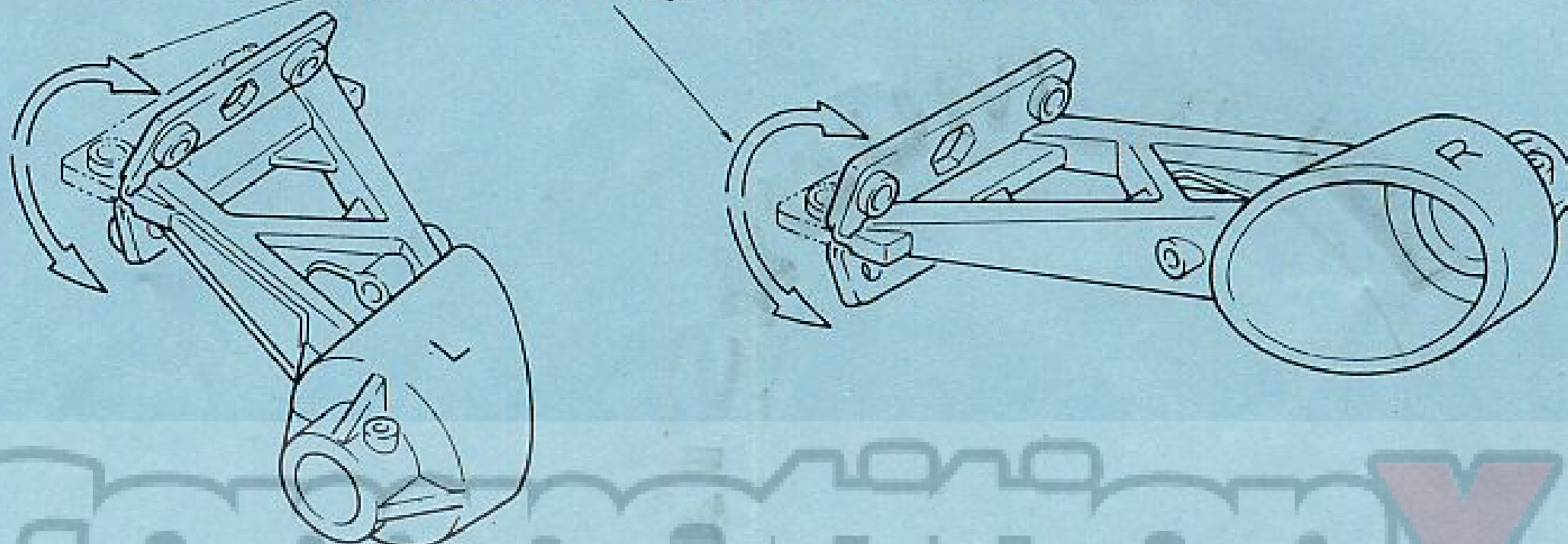


Flex both arms up and down at least 10 times.

Bend downward until they touch.

③ Rear Suspension Arm

Flex both arms up and down at least 10 times.



- The plastic at the hinge joint will become lighter in color as a result of this flexing and the hinge will become more flexible.

Gold Edition X
A WEB SITE FOR THE SERIOUS RACER